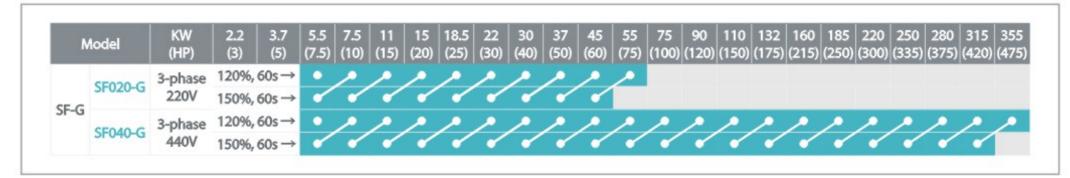
**Dual-load, High Performance Vector Control AC Drive** 



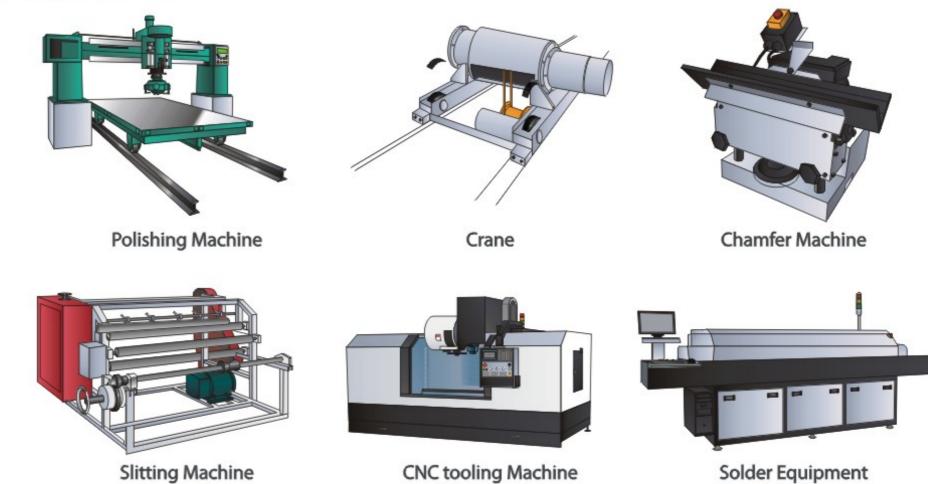
#### Product Range



#### **Main Features**

- \* Dual specifications with HD: 150% 60s / LD: 120% 60s
- \*V/F control, general purpose magnetic flux vector control, SVC sensor-less vector control, FOC+PG closed loop vector control, high torque output at low speed, and the best power saving control mode.
- \* Increased load capacity to 200% / s
- \* Hardware type circuit protection design
- \* Embedded regeneration brake transistor(22kW or below)
- \* Strengthened PID function, Multi-channel control function for fan and pump
- \* RS-485 interface, selection between Shihlin protocol/standard Modbus protocol
- \* Strengthened speed tracking compensation capability
- \* Soft PWM function
- \* Multiple function pulse output
- \* Remote control panel through RJ45
- \* Support various expansion boards: injection molding machine specific expansion boards, Multichannel control function for fan and pump

#### Application





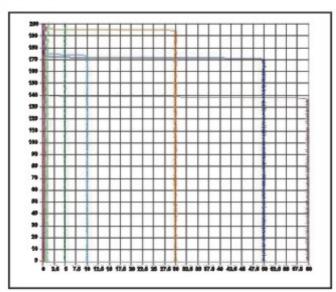
#### **Product Features**

#### **Dual-load specifications**

- Light load 120% 60s / heavy load (-G) 150% 60s.
- The default capacity is light load for air conditioners, pumps, air compressors, conveyors and other machines using light loads.
- The parameters can be adjusted to heavy load by inner parameter setting for punches, cranes, trolleys, screw machinery, machine tools, and injection devices (for PM01 injector expansion card).

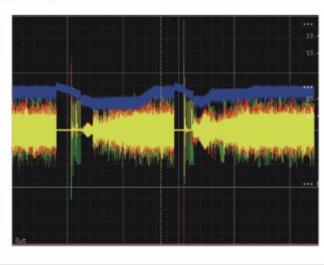
#### **High-performance vector control technology**

- · A 32-bit RISC CPU for high-speed computation.
- SVC sensor1ess vector control with high starting torque of 1Hz150%, and FOC+PG closed loop vector control of OHz 150%.
- Speed accuracy: less than 1% with 0-100% load variation.
- An exclusive pioneer of high-precision motor parameter autotuning function.



#### **Tracking compensation mechanism**

 The enhanced tracking mechanism can detect the rotation speed and direction of motor in idle state, to smooth machine start without jittering.

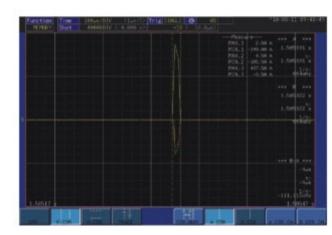


#### Built-in brake transistor (under 22kw)

- Built-in brake transistor (under 22kw).
- Its connection with the brake resistor to improve the braking torque capability.

#### Hardware protection design

- With input power phase failure protection, ground short circuit protection and output short circuit protection
- Hardware design to substantially increase the protection effectiveness.
- Under circumstances of damaged motor insulation or erroneous wiring, to protect the output modules and reduce the failure rate.

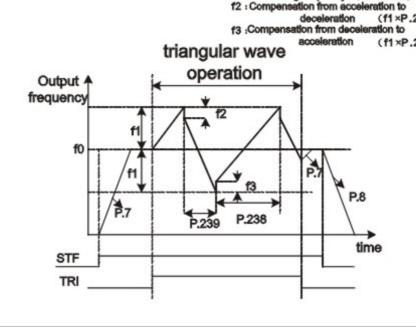


The above picture shows the automatic waveform of SCP abnormality alert from the short circuit of the three-phase output

#### **Equipped with Soft-PWM mechanism**

- Soft-PWM controls the motor noises, transforming the metal sound into a delightful complex tone.
- It provides low noise operation and reduces interference to external RF, ensuring stable operations of nearby PLC and encoder devices.

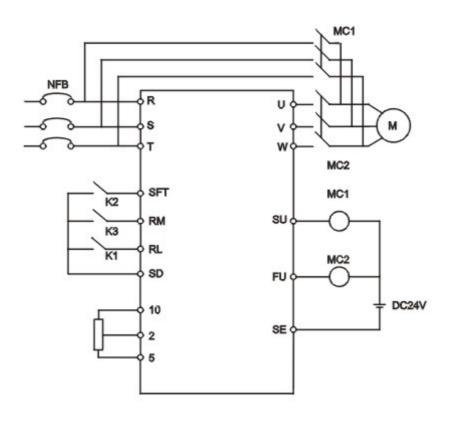
f0: Setting value of frequency



#### **Product Features**

## Equipped with grid power frequency switching mechanism

- It provides automatic switch between the grid power and frequency conversion.
- If the motor is running at rated frequency, using grid power frequency has a much better efficiency.
- In order to prevent the motor from stopping for a long time during the maintenance of AC drive, it is recommended AC drive to have grid power switching function.



## Operating time accumulation and parameters protection

- Time accumulation: the accumulated operating time of the frequency AC drive can be displayed.
- Password protection: It provide 4-digital password to restrict the read and write of parameters, and prevent operative mistakes.

#### **Built-in RS-485 interface**

- Support for MODBUS and Shihlin protocol.
- Capable of simultaneous connections to HMI, PLC and other devices.

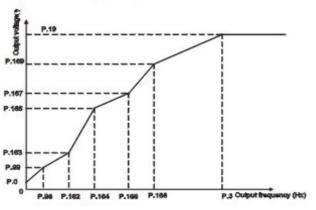
#### PC client communication software

 This provides remote control of multiple frequency AC drive for parameters setup, copy and monitoring.



#### 5-point V/F free setting

 It is more adaptable to various complicated load environment, such as multiple working frequencies.

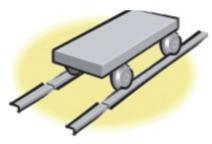


## Containing with 12 sets of abnormality alert records

- The 12 sets of alert records can be easily accessed.
- The system can record abnormal side power input(phase failure), short circuit of side output, over current, over voltage, module overheating, motor overheating, fan abnormalities, communication abnormalities, and so on.

## Excellent performance with load capacity of 200% 1 s (-G)

 For impact load, safe to use (punch/trolley/injector/ screw machinery/machine tool, and so on).



Factory Automation

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# SF-G Series Dual-load, High Performance Vector Control AC Drives

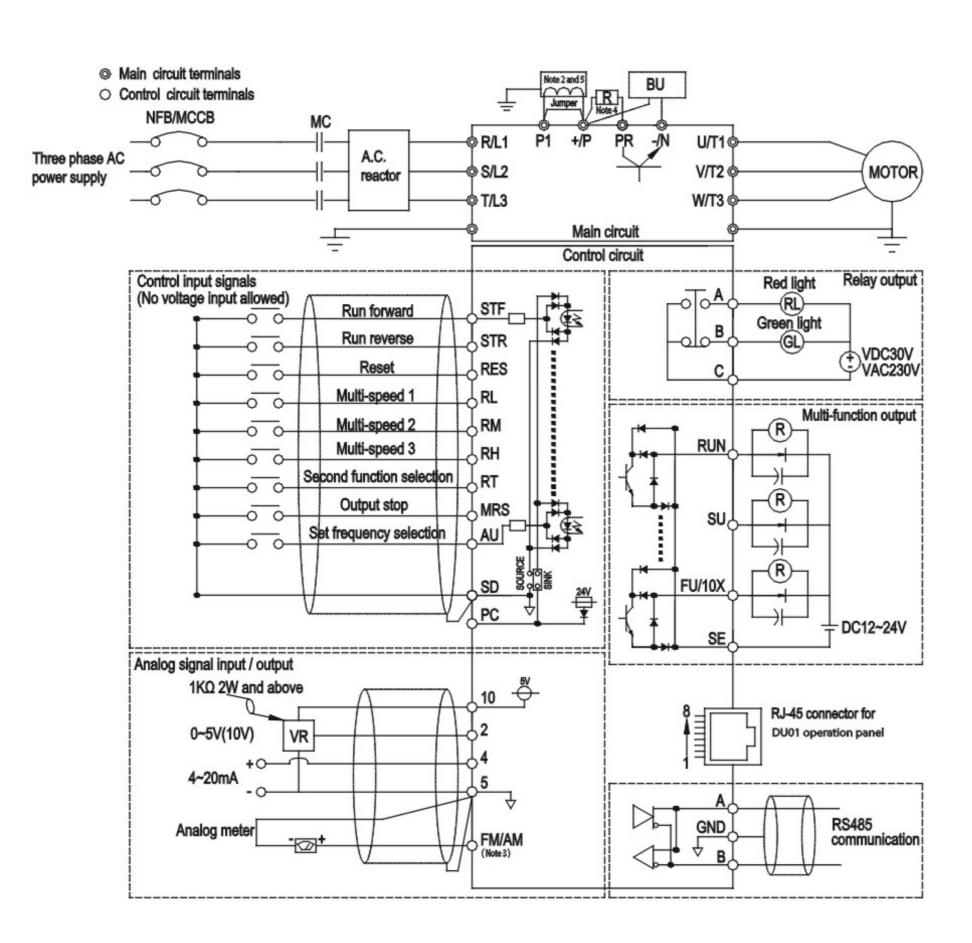
### **Electric Specifications**

	V Series Three				7.0/0.5	W 80		7.5		Elsa		10.5/45		
	Model SF-020- □□□		5.5		7.5/5.5	10	11/		_	5/11		18.5/15		
Appli	cable motor capacity	HP	7.5		10/7.5		15/		_	0/15		25/20		
	Date d autout assault	kw	5.5		7.5/5.5	2 2	11/		_	5/11	_	18.5/15		
0	Rated output capacity kVA		9.5		12.5/9.5		18.3/		+	7/18.3		28.6/24.7		
Output	Rated output current A Overload current rating		25	1200/	33/25 60 second	J- /1500/				5/49	alastian)	75/65		
돆	Maximum output vo		120%	ou second			200 - 24	-	aracte	isucs)				
	Rated power voltage			т		-	240V 50H							
Z 2	Power voltage Power voltage			-				264V 50H			-			
Power	Power frequency per					mee pii	±:		2/00/12					
< ~	Power source capaci		12		17/12				2	8/20		34/28		
Cooli	ing method	y KVA	12 17/12 20/17 28/20 34/20 Forced air cooling									3-1/20		
	ht (kg)											9.0		
		1/DDD K 6			30/22				_			55/45		
	Model SF-020- □□□		22/18.				37/	10000		5/37				
Appli	cable motor capacity	HP kw	30/25 22/18.5		40/30		50/		_	0/50		75/60		
	Pated autnut canadi				30/22		37/		_	5/37		55/45		
0	Rated output capacit		34.3/28	0	45.7/34.3		55/4 145/		_	5/55 0/145	_	81/65		
Output	Rated output current		90/75	1200	120/90	de 1500/					ictics)	212/170		
F	Overload current rati Maximum output vo			1209	6 60 secon			200 - 24	-	aracter	isucs)			
	Rated power voltage	Maria Cara Cara Cara Cara Cara Cara Cara			т.			240V 50H	-		-			
2 2	Power voltage permi							264V 50H						
Power	Power frequency per					mee-bn		264V 50H 5%	2 / OUNZ					
₹ 4	Power source capacit		41/34		52/41		65/		7	9/65	227	99/79		
Cooli	ing method	y KVA	41/34		32/41			r cooling	,	9/03		33//3		
	ht (kg)		20		21		3		1	37	1	67		
			20		- 21			,		3/		0/		
440	V Series Three	-phase												
	Model SF-040- □□□	7 / DDD K-G	5.5	7.5/5.5	11/7.5	1	5/11	18.5/1	5 22/	18.5	30/22	37/30		
		HP	7.5	10/7.5	15/10	2	0/15	25/20	30	/25	40/30	50/40		
Appli	cable motor capacity	kw	5.5	7.5/5.5	11/7.5	1	5/11	18.5/1	5 22/	18.5	30/22	37/30		
	Rated output capacit	y kVA	10	14/10	18/14	2	5/18	29/25	34	/29	46/34	56/46		
Output	Rated output current	A	13	18/13	24/18	3	2/24	38/32	45	/38	60/45	73/60		
Ę.	Overload current rati	ng	•	1209	6 60 second	ds 150%	60 secor	nds (inver	e time cha	aracter	istics)			
-	Maximum output vo	tage	<u> </u>	Three-phase 380 - 480V										
	Rated power voltage		Three-phase380 - 480V 50Hz / 60Hz											
Power	Power voltage permi			Т	hree-ph	ase 342-	528V 50H	z/60Hz						
<u>~</u> €	Power frequency per	missible fluctuation			50	1440	±5	5%						
	Power source capacit	y kVA	11.5 16/11.5 20/16 27/20 32/27					41.	41/32 52/41		65/52			
Cooli	ing method					F	Forced ai	r cooling	- 1					
weig	ht (kg)		5.6	5.6	5.6		5.6	8.3	8	.3	25	25		
	Model SF-040- □□□	/ D D D K-G	45/37	55/45	7.	5/55	90	175	110/90	S .	132/110	160/13		
	Ī	HP	60/50	75/60		00/75	-	/100	150/120	_	175/150	215/17		
Appli	cable motor capacity	kw	45/37	55/45	_	5/55	90/		110/90		132/110	160/13		
7	Rated output capacit		69/56	84/69	_	4/84	_	/114	168/137		198/168	236/19		
Output		Rated output current A		91/73 110/91 150/110 180/150 220/180 260/220 310/2										
ŧ.	Overload current rating		120% 60 seconds 150% 60 seconds (inverse time characteristics)											
4	Maximum output voltage		Three-phase 380 - 480V											
	Rated power voltage	-			Т		_	480V 50H						
Power	Power voltage permi						-	528V 50H						
wei beh	Power frequency per			-		-	-	5%						
	Power source capacit		79/65	100/79	110	0/100	_	/110	165/137		198/165	247/19		
Cooli	ing method	,						r cooling						
	ht (kg)		25	37		37	3		67		67	67		
	Model SF-040- □□□	1/DDDK6	185/160		/185	250/		280/		215	5/280	355/315		
- 2-3	Model 3F-040- HHL	НР	250/215		/250	335/		375/			/375	475/420		
Appli	cable motor capacity	kw	185/160	_	/185	250/		280/	_		/280	355/315		
	Rated output capacit	Control of the Contro	295/236		/185	402/		438/			/438	544/491		
on O	Rated output capacit		340/310	_	/340	480/		530/			/530	683/620		
utput	Overload current rati	1010	340/310		60 second							003/020		
7	Maximum output vo			12070	oo secono		-	380 ~ 48		iui delle	. isucs)			
-	Rated power voltage	-		7	т			480V 50H						
S P	Power voltage permi					-		528V 50H						
					- 11	nee-pna		528V 50F 5%	12 / OUNZ		20			
D X	Power frequency permissible fluctuation											= 1 1 / 1 0 1		
ower		Power source capacity kVA		267	/205	4027	367	420/	402	46.77	/430	EAA (AI)		
Power		y kVA	295/247	367	/295	402/		438/ r cooling	402	491	/438	544/491		

### Common Specifications

Control method				M control, V/F control, close-loop V/F control (VF+PG), general flux vector control, less vector control (SVC), close-loop vector control (FOC+PG)						
Outpo	Output frequency range		0.2-400Hz (The starting frequency setting range is 0-60Hz)							
Volta	Voltage 1 frequency		If the frequency set value is below 100Hz, the resolution will be 0.01 Hz; If the frequency set value is above 100Hz, the resolution will be 0.1 Hz							
outpu	it characteristics	Analog setting	When setting DC 0-5V signals, the resolution will be 1/500; When setting DC 0-10V or 4-20mA signals, the resolution will be 1/1000							
Output frequency Digital setting			Maximum target frequency :±0.01 %							
accuracy Analog setting			Maximum target frequency :±0.5%							
Voltage I frequency output characteristics		Base frequency voltage (P.19), base frequency (P.3) can be arbitrarily set; Constant torque model and applicable load model can be selected (P.14)								
Start 1	torque		150%	1Hz: When the sensorless vector control is started						
Torqu	e boost		The to	rque boost setting range is 0-30% (P.O), auto boost, slip compensation						
Acceleration / deceleration curve characteristics		setting	solution (0.01s/0.1s) of acceleration/deceleration time (P.7, P.8) is switched by P.21. The range has 0~360s or 0~3600s for selection. And different acceleration/deceleration model can be selected by P.29.							
DC br	aking			C braking action frequency is 0-120Hz (P.10); the DC braking time is 0-60s (P.11) The DC g voltage is 0-30% (P.12).Linear braking and idling braking selection (P.71)						
Stallin	ng protection		The sta	alling protection level can be set to 0-400% (P.22)						
Target frequency setting				Operation panel setting; DC 0-5V signal, DC 0-10V signal, DC 4-20 mA signal, multiple speed stage level setting, communication setting						
PID co	PID control		Please refer to manual P.170-P.182 in Chapter 5							
Multi-function control terminals		extern	starting (STF, STR), the second function (RT), 16-speed operation (RH, RM, RL, REX) al thermal relay (OH), reset (RES),etc.(they can be set by the user with HYPERLINK \P.84, P.86 and P.126~P.128).							
	Multi-function output terminals	SU, SE	P.40	AC drive running (RUN), output frequency detection (FU), Up to frequency (SU						
9		RUN, SE	P.129	overload alarm (OL), zero current detection (OMD), alarm (ALARM), section detection						
rtpu		FU/10X,SE	P.130	(P01), periodical detection (P02), and pause detection (P03), AC drive output (BP) work frequency output (GP)						
Output termins	Multi-function output relay	А,В,С	P.85	work frequency output (GP)						
181	Analog output	AM,5	Multi-f	unction DC (0-10V) output: output frequency, current (P.54)						
	Pulse output	FM,SD	Outpu	t the pulse of 0-2300Hz						
op	Operation monitoring		Output frequency monitoring, output current monitoring, and output voltage monitoring abnormality record (Maximum 12 sets)							
Operation Panel	LED indication lamp(8)		Forward rotation indication lamp, reverse rotation indication lamp, frequency monitoring indication lamp, voltage monitoring indication lamp, current monitoring indication lamp, mode switching indication lamp, PU terminals control indication lamp, and external terminals control indication lamp							
Comn	nunication function	1	RS-485 communication, can select Shihlin/Modbus protocol communication protocol							
Protection mechanism / alarm function		Output short circuit protection, Over-current protection, (+/P)-(-/N) over-voltage protection under-voltage protection, motor over-heat protection (P.9), IGBT module over-heat protection communication abnormality protection, etc								
	Ambient temperature		-10~+40°C (non-freezing)							
	Ambient humidity		Below 90%Rh (non-condensing)							
	Storage temperature		-20 ~ +65°C							
O E	Surrounding environmen		Indoor, no corrosive gas, no flammable gas, no flammable powder							
Environmental Condition	Altitude and vibration		Maximum operating altitude is 2000 Meters. If AC drive is installed at altitude 1000~2000m, decrease 2% of rated current for every 100m increase in altitude.							
enta	Grade of protection		IP20							
n tal	The degree of									
ntal n		ollution	2							
ntal n	The degree of environmental po		2 Class I							

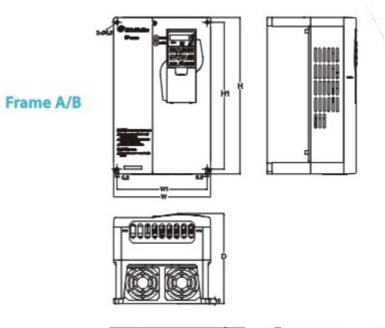
#### **Wiring Diagram**

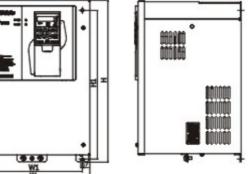


#### NOTE

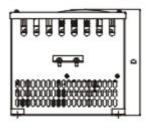
- 1. Please refer to P.80~ P.84, P.86 and P.126~P.128 (OH) of Chapter 5 for the applications of external thermal overload relay.
- Make sure not to short PC and SD.
- 3. The AC resistor between +/P and P1 is optional. Please short +/P and P1 when AC resistor is not used.
- 4. When selecting FM function for the FM/AM output terminal, the reference ground is SD. For more details, please refer to P.64.
- 5. The brake resistor connection approach between +/P and PR is for frames A and B only. For connecting the brake unit of frame C, D, E, F to between +/P and -/N, please refer to terminal arrangement in 3.4.5
- 6. Inverters corresponding to frame C. E. Fhave build-in DC reactors, you can also refer to DC reactor specification on page 34 before adding DC reactors in addition.( When adding DC reactors, please remove the short circuit piece between P1 and +/P.)

#### Dimensions

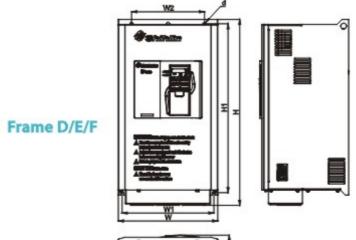


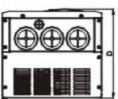






Frame C





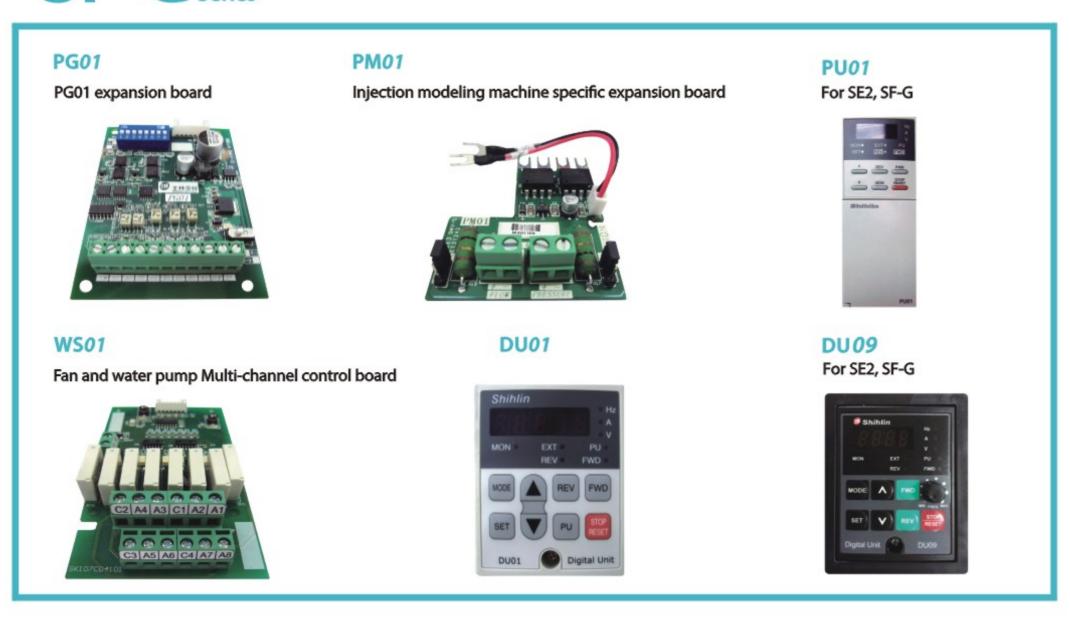


Model	Frame	H (mm)	H1 (mm)	W (mm)	W1 (mm)	D (mm)
SF-020-5.5K	A		303		186	186
SF-020-7.5K/5.5K-G				200		
SF-040-5.5K		222				
SF-040-7.5K/5.5K-G		323				
SF-040-11K/7.5K-G						
SF-040-15K/11K-G						
SF-020-11K/7.5K-G		350	330	230	214	195
SF-020-15K-11K-G	1					
SF-020-18.5K/15K-G	В					
SF-040-18.5K/15K-G	1					
SF-040-22K-18.5K-G	1					

Frame C									
Model	Frame	H (mm)	H1 (mm)	W (mm)	W1 (mm)	D (mm)			
SF-020-22K-18.5K-G	_	379	348	271	236	248			
SF-020-30K/22K-G		3/9		2/1					

Frame D/E/F								
Model	Frame	H (mm)	H1 (mm)	W (mm)	W1 (mm)	W2 (mm)	D (mm)	d (mm)
SF-040-30K/22K-G								
SF-040-37K/30K-G	D	561	510	300	277	220	270	9
SF-040-45K-37K-G								
SF-020-37K/30K-G								
SF-020-45K-37K-G								
SF-040-55K/45K-G	E	595	566	370	336	336	286	13
SF-040-75K/55K-G								
SF-040-90K/75K-G					3			
SF-020-55K/45K-G								
SF-040-110K/90K-G	_	050	024	425	201	201	200	42
SF-040-132K/110K-G	F	850	821	425	381	381	286	13
SF040-160K/132K-G								

Model	Frame	H (mm)	H1 (mm)	W (mm)	W1 (mm)	W2 (mm)	D (mm)	d (mm)
SF-040-185K/160KG								
SF-040-220K/185KG	] _ [	870	850	500	180	180	360	13
SF-040-250K/220KG	G							
SF-040-280K/250KG	1 1							
SF-040-315K/280KG		1000	980	600	230	230	400	13
SF-040-355K/315KG	H							



## Common

