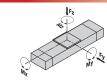
歐標半密式同步帶驅動側軌加强型 HTO 60/80/100







最大動態力和力矩



規格コ	規格 Type		80	80-L	100	100-L
■F(y)	(N)	5300	6980	10470	9702	14554
■F(z)	(N)	5300	6980	10470	9702	14554
■ M(x)	(N·m)	82	118	178	216	374
■ M(y)	(N · m)	118	333	590	765	1080
■M(z)	(N·m)	118	333	590	765	1080

除了滿足最大負載和力矩外,還必須滿足以下公式:

All forces and torques relate to the following: $\frac{Fy}{Fy\ max} + \frac{Fz}{Fz\ max} + \frac{Mx}{Mx\ max} + \frac{My}{My\ max} + \frac{Mz}{Mz\ max} \leq 1$

■ 馬達安裝方向 Motor Mounting Position Version

D01	D02	D03	D04	D05	D06

■ 基本規格 Basic Specification

	НТО		60	80	80-L	100	100-L		
	位置重復精度 Repetitive	Accuracy (mm)		±0.05					
	皮帶輪導程 Pulley Lead	(mm)	130	176	176	224	224		
技術	皮帶型號 Belt Type		5M-25	8M-30	8M-30	8M-50	8M-50		
參數	最高速度 Maximum Spe	ed (mm/s)	5000	5000	5000	5000	5000		
Technical	*注4 *Note4	水平使用Horizontal (kg)	55	100	150	165	247.5		
Parameters	Parameters Maximum Payload	垂直使用Vertical (kg)	25	62	93	105	157.5		
	最大空載扭矩 Max. No-l	oad Driving Torque (N · m)	0.5	0.9	0.9	1.4	1.4		
	最大扭矩 Max. Driving T	orque (N·m)	13.3	49.8	49.8	105.7	105.7		
	標準行程 Stroke (mm)			100	0-4000mm/100 pitc	h			
基本	AC伺服馬達容量 AC Se	rvo Motor Output (W)	200/400	200/400/750	200/400/750	750/1000	750/1000		
規格			15# ×2PCS	20#×1PC + 15# ×1PC	20#×1PC + 15# ×1PC	25#×1PC+ 20#×1PC	25#×1PC+ 20#×1PC		
Basic Specification	主機截面最大外形 Max Outline of Main Eng	ine's Cross Section (mm)	102 .5×79	106 × 122	106 × 122	130 × 151	130 × 151		
	原點感應器 Home Senso	or		E	EE-SX672(NPN)				

注1: 輔助滑塊選項相關參數參見樣本P148.

Note1: Refer to catalogue P148 for relevant parameters of auxiliary carriage option 注2: 馬達座型號相關參數參見樣本P38.

Note2: Refer to catalogue P38 for relevant parameters of motor model 注3: 減速機端聯軸器孔徑尺寸

Note3: Hole dimension of coupling (reducer side) 注4:測定條件爲無力矩的理論數據,根據力矩和加速度數據會相應改變,具體請參考選型軟件。

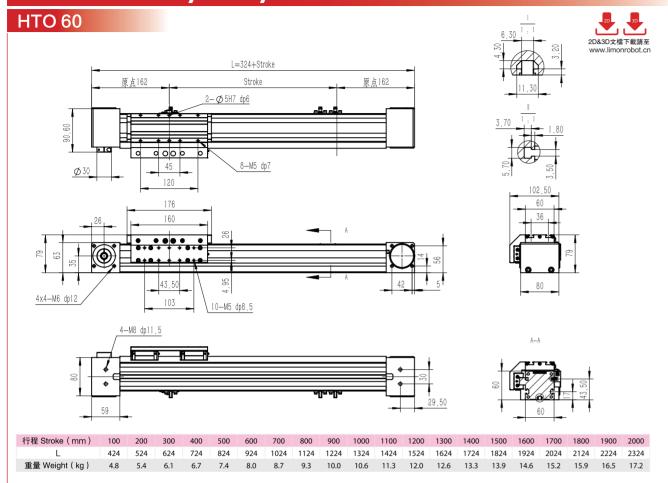
Note4: Date changes relevently according to different torque and acclerated speed. Please refer to the LIMON calculate software.

KS Series

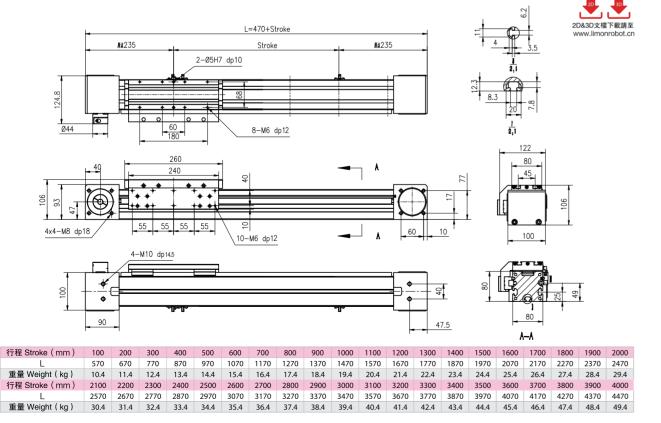
ITO Series

HTO Series

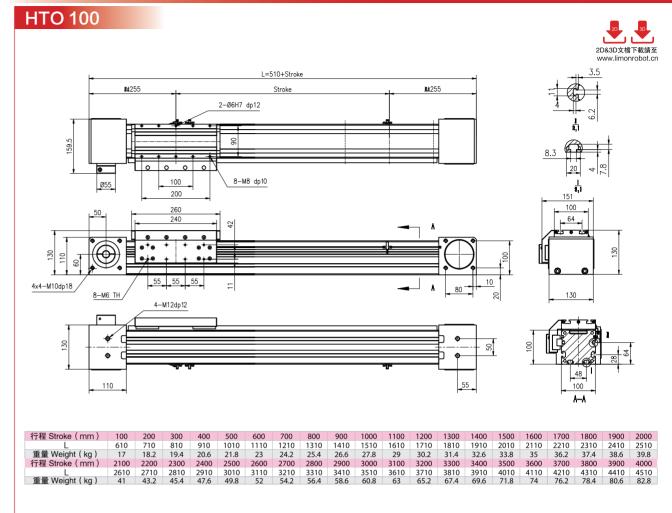
HTO 60/80/100 歐標半密式同步帶驅動側軌加强型 Belt Driven Linear Actuator

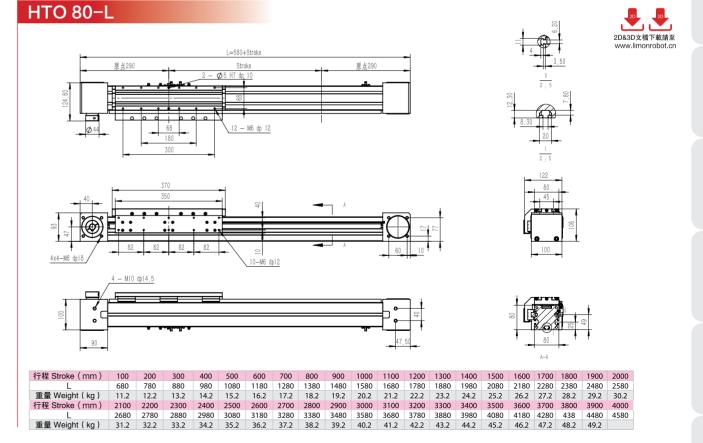


HTO 80



歐標半密式同步帶驅動側軌加强型 HTO 60/80/100





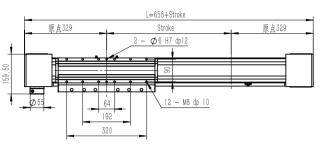
YTO

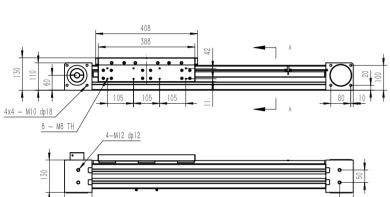
www.limonrobot.cn

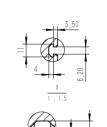
KS Series

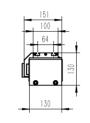
HTO 60/80/100 歐標半密式同步帶驅動側軌加强型 Belt Driven Linear Actuator

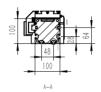
HTO 100-L











行程 Stroke (mm)	100	200	300	400	500	600	700	800	900	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000
L	758	858	958	1058	1158	1258	1358	1458	1558	1658	1758	1858	1958	2058	2158	2258	2358	2458	2558	2658
重量 Weight (kg)	17.6	18.4	19.2	20	20.8	21.6	22.4	23.2	24	24.8	25.6	26.2	27.2	28	28.8	29.6	30.4	31.2	32	32.8
行程 Stroke (mm)	2100	2200	2300	2400	2500	2600	2700	2800	2900	3000	3100	3200	3300	3400	3500	3600	3700	3800	3900	4000
L	2758	2858	2958	3058	3158	3258	3358	3458	3558	3658	3758	3858	3958	4058	4158	4258	4358	4458	4558	4658
重量 Weight (kg)	33.6	34.4	35.2	36	36.8	37.6	38.4	39.2	40	40.8	41.6	42.4	43.2	44	44.8	45.6	46.4	47.2	48	48.8

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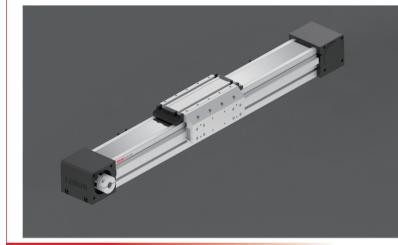
KS Series

ITO Series

HTC 80/100 歐標全密式同步帶驅動側軌加强型 Belt Driven Linear Actuator

□訂購型號代碼 Code





最大動態力和力矩

規格ヿ	уре	80	80-L	100	100-L
■F(y)	(N)	6980	10470	9702	14554
■ F(z)	(N)	6980	10470	9702	14554
■ M(x)	(N·m)	118	178	216	374
■M(y)	(N·m)	333	590	765	1080
■M(z)	(N·m)	333	590	765	1080

·除了滿足最大負載和力矩外,還必須滿足以下公式:

All forces and torques relate to the following:

■ 馬達安裝方向 Motor Mounting Position \

D01	D02	D03	D04	D05	D06

• 基本規格 Basic Specification

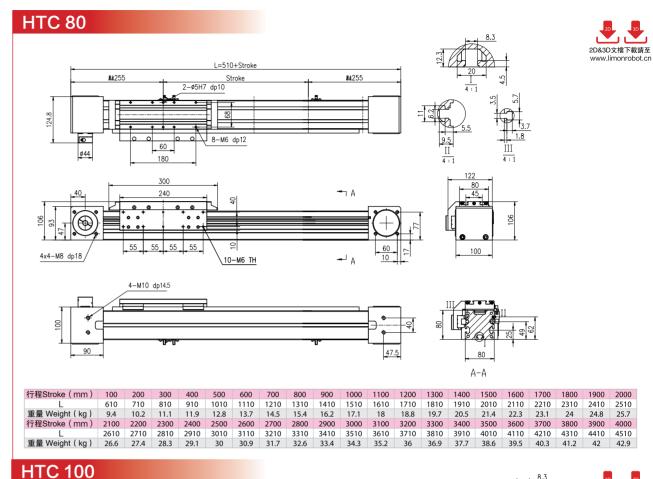
HTC			80	80-L	100 100-L				
	位置重復精度 Repetitive	Accuracy (mm)		±0.05					
	皮帶輪導程 Pulley Lead (mm)	17	'6	224	4			
技術	皮帶型號 Belt Type		8M-	-30	-M8	50			
參數	最高速度 Maximum Spee	ed (mm/s)	500	00	500	0			
Technical	*注4 最大可搬重量 *Note4	水平使用Horizontal (kg)	100	150	165	247.5			
Parameters	Maximum Payload	垂直使用Vertical (kg)	62	93	105	157.5			
	最大空載扭矩 Max. No-lo	oad Driving Torque (N · m)	0.	9	1.4				
	最大扭矩 Max. Driving To	orque (N · m)	49	.8	105.7				
	標準行程 Stroke (mm)			100–4000n	m/100 pitch				
基本	AC伺服馬達容量 AC Set	vo Motor Output (W)	400/	750	750/1000				
規格	高剛性直綫滑軌 Linear Guide		20#×1PC+	15# × 1PC	25# × 1PC+20# × 1PC				
Basic Specification	主機截面最大外形 Max Outline of Main Eng	ine's Cross Section (mm)	106×	: 122	130 × 151				
	原點感應器 Home Senso	r		EE-SX6	672(NPN)				

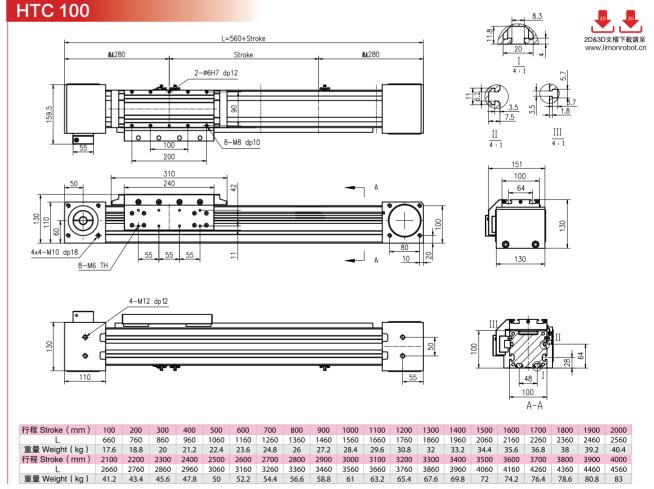
注1: 輔助滑塊選項相關參數參見樣本P148.

Note1: Refer to catalogue P148 for relevant parameters of auxiliary carriage option 注2: 馬達座型號相關參數參見樣本P38.

注4:測定條件爲無力矩的理論數據,根據力矩和加速度數據會相應改變,具體請參考選型軟件。 elevently according to different torque and acclerated speed. Please refer to the LIMON calculate software.

歐標全密式同步帶驅動側軌加强型 HTC 80/100 Belt Driven Linear Actuator

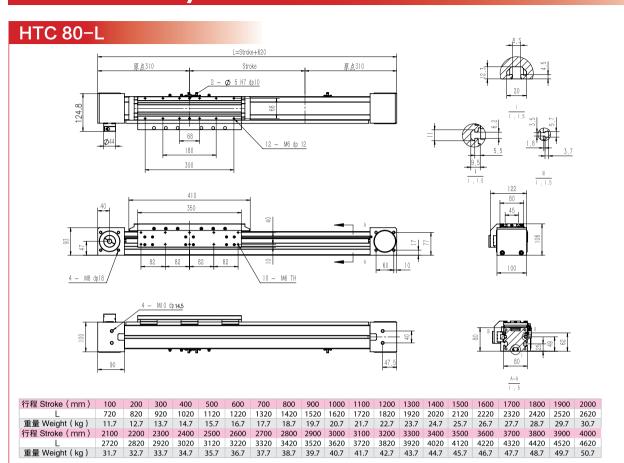


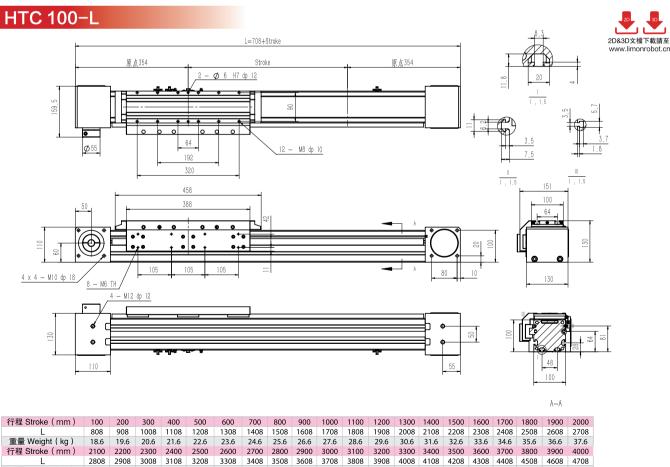


重量 Weight (kg)

HTC 80/100 歐標全密式同步帶驅動側軌加强型 **Belt Driven Linear Actuator**

2D&3D文檔下載請至 www.limonrobot.cr





42.6

43.6

45.6

47.6 48.6 49.6 51.6 52.6 53.6

38.6 39.6

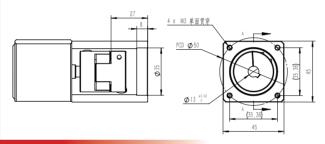
ITO/HTO / ITC / HTC 安裝附件 Accessories

馬達座尺寸圖 Dimentional Drawing of Motor Base

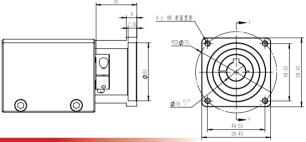


#注1: 此零件爲選購件,如需訂購請在下單時備注。 Note 1: This is optional accessory, please remark if needed.

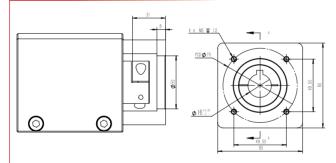
I40-馬達座-GB1



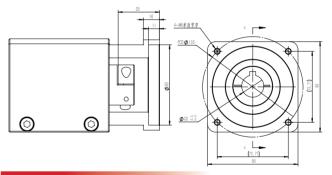
I60-馬達座-GB2



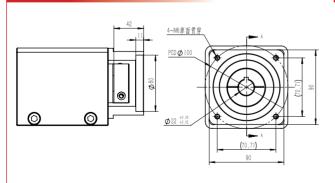
I80-馬達座-GB2



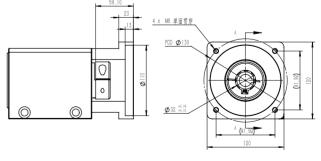
I80-馬達座-GB3



I100-馬達座-GB3



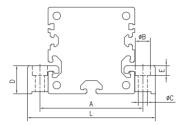
I100-馬達座-GB4

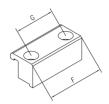


ITO/HTO / ITC / HTC 安裝附件 Accessories

安裝塊尺寸圖 Dimentional Drawing of Jointing Block







#注1: 500mm行程以内建議配4個安裝塊,行程每增加500mm,需多增加2個安裝塊。 Note 1: Suggest to assemble 4 jointing block (stroke ≤ 500mm) , two additional jointing block is required when stroke adds 500mm every time.

#注2:	此零件爲選購件,	如需訂購請在下單時備注。
Note 2	: This is optional	accessory, please remark if needed.

規格Type	Α	В	С	D	Е	F	G	L
ITO40	54	10	5.5	13	5.7	40	26	66
ITO/ITC 60	75	11	6.6	19	6.8	52	36	93
ITO/ITC80	96	14	8.5	26	9	64	45	119
ITO/ITC100	118	14	8.5	29	9	84	64	140
ITO160	75	11	6.6	19	6.8	52	36	93

歐標同步帶模塊聯軸器尺寸表

Coupling dimension table of belt driven linear actuator of Jointing Block

模組型號 Module model	可開孔徑範圍(mm) Hole dimension available range
ITO60/ITO60-L/ITC60/ITC60-L/HTO60/ITZ60	6~16
ITO80/ITO80-L/ITC80/ITC80-L/HTO80/HTO80-L/HTC80/HTC80-L	10 ~ 22
ITO100/ITO100-L/ITC100/ITC100-L/HTO100/HTO100-L/HTC100/HTC100-L	10 ~ 32
ITO160	10 ~ 22