# OPERATION MANUAL OM Series 

Quarter-Turn Electrical Actuator

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## OVERVIEW

Sun Yeh electric quarter-turn actuators offer a range of $35 \mathrm{~N} \cdot \mathrm{~m}$ to $4500 \mathrm{~N} \cdot \mathrm{~m}$ torque. Product design is based on a self-locking worm drive principal, which provides for a smooth running, dependable, robust drive system. All models are ISO 5211 compliant, have a visual position indicator on top of actuator cover and manual override except BM-2 and OMA. The manual operation is non-clutch design that can be operated without any lever, clutch or brake upon power outage. This design has already won the new Patent in Taiwan, U.S.A. and China.

## Features

$\checkmark 30 \%$ duty cycle at rated torque.
$\checkmark$ Self-locking function.
$\checkmark$ Built-in thermal protection prevents motor burning out. AC motor is $125^{\circ} \mathrm{C}\left(257^{\circ} \mathrm{F}\right)$ and $90^{\circ} \mathrm{C}\left(194^{\circ} \mathrm{F}\right)$ for DC motor. (The $75 \%$ duty cycle actuator uses DC motor.)

| Model | Max. Torque |  | Weight |  | Manual Override |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\mathrm{N} \cdot \mathrm{m}$ | $\mathrm{lb} \cdot \mathrm{in}$ | Kg | lb |  |
| OM-A | 50 | 443 | 3 | 6.61 | $\mathrm{~N} / \mathrm{A}$ |
| OM-A-M | 50 | 443 | 3 | 6.61 |  |
| OM-1 | 35 | 310 | 2 | 4.41 |  |
| BM-2 | 120 | 1063 | 5.5 | 12.13 | $\mathrm{~N} / \mathrm{A}$ |
| OM-F | 65 | 576 | 11 | 24.25 |  |
| OM-2 | 90 | 797 | 11 | 24.25 |  |
| OM-G | 90 | 797 | 11 | 24.25 |  |
| OM-3 | 150 | 1328 | 11 | 24.25 |  |
| OM-4 | 400 | 3542 | 20 | 44.09 | Hand-wheel |
| OM-5 | 500 | 4427 | 20 | 44.09 |  |
| OM-6 | 650 | 5756 | 20 | 44.09 |  |
| OM-7 | 1000 | 8855 | 32 | 70.55 |  |
| OM-8 | 1500 | 13282 | 32 | 70.55 |  |
| OM-9 | 2000 | 17709 | 71 | 156.53 |  |
| OM-10 | 2500 | 22137 | 71 | 156.53 |  |
| OM-11 | 3000 | 26564 | 72 | 158.73 |  |
| OM-12 | 3500 | 30991 | 72 | 158.73 |  |
| OM-13 | 4500 | 39846 | 106 | 233.69 |  |

## IMPORTANT NOTICES

## CAUTION !

For the 3-Phase on-off controller actuator, please use the hand-wheel to turn the actuator to 45 degree before test.
** If the direction is opposite after supplying power, please change any two of the $\mathrm{U}, \mathrm{V}, \mathrm{W}$.

1. Check for correct voltage prior to wiring.
2. Turn power off before servicing or for maintenance purpose.
3. Use sealant to seal conduit connections after wiring to prevent dusting or water contamination.
4. The angle of electrical actuator installation must be between $0 \sim 180$ degree. Do not install upside down or below the horizontal. The conduit entries can not face up.
5. When more than one electric actuator needed to operate simultaneously, please connect with the individual cables or install the coupling board.
6. Not intended for vacuum spaces and avoid installing near explosive atmospheres.
7. Actuators should be placed at clean and dry place for storage, and protected with outer carton from being affected by great temperature difference or serious vibration.
8. To avoid functional failure caused by statics, do not touch any components on the PCB with metal tools or bare hands.
9. Please connect the ground wire to PE inside the electric actuator.
10. The warranty period of our products is one year.

## Duty Cycle - compliance to IEC standard

"Duty cycle" means the starting frequency.
The formula: Running Time $\div$ (Running time + Rest Time) $\times 100 \%=$ duty cycle Rest Time $=$ Running Time $\times(1-$ duty cycle $) \div$ duty cycle

For example : $\quad$ The running time for $\mathrm{OM}-2$ is 15 sec .
$30 \%$ duty cycle $15 \times[(1-30 \%) / 30 \%]=35 \rightarrow$ The rest time will be 35 sec .
$75 \%$ duty cycle $15 \times[(1-75 \%) / 75 \%]=5 \rightarrow$ The rest time will be 5 sec .
If the duty cycle is higher, the rest time will be shortened. It means the starting frequency will be higher.

## STANDARD MOUNTING

| Model | MountingFlange(ISO 5211) | Shaft |  | Depth of shaft |  | Key |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | mm | inch | mm | inch | mm | inch |
| BM-2 | F07 | 22 | 0.87 | 30 | 1.18 |  | A |
| OM-A | F05 / F07 | 17 | 0.67 | 20 | 0.78 |  | A |
| OM-A-M | F05 / F07 | 17 | 0.67 | 20 | 0.78 |  | A |
| OM-1 | F03 / F05 | 14 | 0.55 | 17 | 0.67 |  | A |
| OM-F, OM-G | F07 | 22 | 0.87 | 30 | 1.18 |  | A |
| OM-2~OM-3 | F07 | 22 | 0.87 | 30 | 1.18 |  | A |
| OM-4~OM-6 | F10 | 36 | 1.38 | 40 | 1.57 |  | A |
| OM-7~OM-8 | F12 or F14 | 35 | 1.38 | 60 | 2.36 | $10 \times 10$ | $0.39 \times 0.39$ |
| OM-9~OM-12 | F14 or F16 | 75 | 2.95 | 100 | 3.94 | $12 \times 10$ | $0.47 \times 0.39$ |
| $\mathrm{OM}-13$ | F16 / F25 | 72 | 2.83 | 110 | 4.33 | $20 \times 12$ | $0.79 \times 0.47$ |

## SPECIFICATION

$12 \mathrm{~V} / 24 \mathrm{~V}$

| Model No. | Max Torque |  | Speed (90ㅇ) | Motor Power | 12V DC/AC |  |  | 24V DC/AC |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Nm | lb-in |  |  | Run | Start | Lock | Run | Start | Lock |
| BM-2 | - | - | - | - | - | - | - | - | - | - |
| OM-A | 50 | 443 | 20s | 10W | 1.3A | 1.5A | 2.8A | 0.8A | 0.9A | 1.6A |
| OM-A-M | 50 | 443 | 20s | 10W | 1.3A | 1.5A | 2.8A | 0.8A | 0.9A | 1.6A |
| OM-1 | 35 | 310 | 15s | 10W | 1.9A | 2.0 A | 2.8A | 1.1A | 1.1A | 1.6A |
| OM-2 | 90 | 797 | 15 s | 40W | 3.4 A | 5.2A | 16.5A | 2.2 A | 4.5A | 14.5A |
| OM-F | 65 | 576 | 6 s | 60W | - | - | - | 2.6A | 3.8A | 11.0A |
| OM-3 | 150 | 1328 | 22s | 40W | 4.4A | 4.9A | 16.5A | 2.4 A | 5.0A | 14.5A |
| OM-G | 120 | 1063 | 8 s | 60W | - | - | - | 4.4A | 4.8A | 11.0A |
| OM-4 | 400 | 3542 | 16 s | 80W | 16.1A | 16.1A | 33.0 A | 8.5A | 9.2A | 30.0A |
| OM-5 | 500 | 4427 | 22s | 80W | 14.1 A | 13.5A | 33.0 A | 7.5A | 9.0A | 30.0A |
| OM-6 | 650 | 5756 | 28s | 80W | 12.3A | 12.5A | 33.0 A | 7.0A | 8.5A | 30.0A |
| OM-7 | 1000 | 8855 | 46 s | 80W |  |  |  | 6.8A | 7.8A | 30.0 A |
| OM-8 | 1500 | 13282 | 46 s | 80W | 25A | 26A | 59A | 8.1A | 8.0A | 30.0A |
| OM-9 | 2000 | 17709 | 58s | 80W |  |  |  | 8.8A | 11.0A | 26.0A |
| OM-10 | 2500 | 22137 | 58s | 80W | 28A | 60A | 59A | 11.8A | 11.0 A | 26.0A |
| OM-11 | 3000 | 26564 | 58s | 220W |  |  |  | 15.1A | 11.0A | 33.0A |
| OM-12 | 3500 | 30991 | 58s | 220W |  |  |  | 17.8A | 12.0A | 33.0 A |

Single Phase

| Model No. | Max Torque |  | Speed (90 ${ }^{\circ}$ ) |  | Motor Power | 110V Current |  |  | 220V-240V Current |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Nm | lb-in | 60 Hz | 50 Hz |  | Run | Start | Lock | Run | Start | Lock |
| BM-2 | 120 | 1063 | 8s | 10s | 40W | 1.3A | 1.6A | 1.6A | 0.6A | 0.9A | 0.9A |
| OM-A | 50 | 443 | 20s | 24s | 10W | 0.6A | 0.6A | 0.7A | 0.3A | 0.4A | 0.5A |
| OM-A-M | 50 | 443 | 20s | 24s | 10W | 0.6A | 0.6A | 0.7A | 0.3A | 0.4A | 0.5A |
| OM-1 | 35 | 310 | 12s | 13s | 10W | 0.6A | 0.6A | 0.7A | 0.3A | 0.4A | 0.4A |
| OM-2 | 90 | 797 | 15s | 17s | 40W | 1.0A | 1.8A | 1.6A | 0.5A | 0.8A | 0.9A |
| OM-F | 65 | 576 | 6 s | 6s | 60W | 1.4 A | 2.1A | 3.1 A | 0.7A | 1.0A | 1.5A |
| OM-3 | 150 | 1328 | 22s | 26s | 40W | 1.2A | 1.8A | 1.6A | 1.0A | 1.2A | 0.9A |
| OM-G | 120 | 1063 | 8s | 8s | 60W | 1.6A | 3.0A | 3.1 A | 0.8A | 1.2A | 1.5A |
| OM-4 | 400 | 3542 | 16s | 18s | 80W | 1.9A | 3.8A | 3.6A | 1.1A | 2.0A | 2.2A |
| OM-5 | 500 | 4427 | 22s | 25s | 80W | 2.0A | 3.8A | 3.6A | 1.1A | 2.0A | 2.2A |
| OM-6 | 650 | 5756 | 28s | 31s | 80W | 2.1 A | 3.8A | 3.6A | 1.1A | 2.0A | 2.2A |
| OM-7 | 1000 | 8855 | 46s | 55s | 120W | 3.1 A | 8.5A | 9.0A | 1.4 A | 4.1A | 5.0A |
| OM-8 | 1500 | 13282 | 46s | 55s | 120W | 3.3A | 9.0A | 9.0A | 1.6A | 4.4A | 5.0A |
| OM-9 | 2000 | 17709 | 58s | 70s | 180W | 3.3A | 5.8A | 5.9A | 2.1A | 3.8A | 3.6A |
| OM-10 | 2500 | 22137 | 58s | 70s | 180W | 4.0A | 6.5A | 5.9A | 2.3A | 4.0A | 3.6A |
| OM-11 | 3000 | 26564 | 58s | 70s | 180W | 4.5A | 3.5A | 5.9A | 2.5A | 4.2A | 3.6A |
| OM-12 | 3500 | 30991 | 58s | 70s | 220W | 4.0A | 8.0A | 7.5A | 2.4A | 4.4A | 4.8A |
| OM-13 | 4500 | 39846 | 80s | 95s | 220W | 4.2A | 8.0A | 7.5A | 2.4 A | 4.8A | 4.8A |

## SPECIFICATION

## Three Phase

| Model No. | Max Torque |  | Speed (90 ${ }^{\circ}$ ) |  | Motor <br> Power | 220V Current |  |  | 380V Current |  |  | 440V Current |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Nm | lb-in | 60 Hz | 50 Hz |  | Run | Start | Lock | Run | Start | Lock | Run | Start | Lock |
| BM-2 | 120 | 1063 | 8 s | 10 s | 40W | 0.8A | 1.4A | 1.5A | 0.4A | 0.9A | 0.7A | 0.4A | 0.5A | 0.6A |
| OM-1 | - |  |  |  |  |  |  |  |  |  |  |  |  |  |
| OM-A | - |  |  |  |  |  |  |  |  |  |  |  |  |  |
| OM-A-M | - |  | - | - | - | - | - | - | - | - | - |  | - |  |
| OM-2 | 90 | 797 | 15s | 17s | 40W | 0.8A | 1.4A | 1.5A | 0.4A | 0.7A | 0.7A | 0.4A | 0.9A | 0.6A |
| OM-3 | 150 | 1328 | 22s | 26s | 40W | 0.8A | 1.4A | 1.5A | 0.4 A | 0.7 A | 0.7A | 0.4A | 0.9A | 0.6A |
| OM-4 | 400 | 3542 | 16s | 18s | 80W | 1.0A | 1.8A | 2.3A | 0.7A | 1.3A | 1.5A | 0.6A | 1.4A | 1.4A |
| OM-5 | 500 | 4427 | 22s | 25s | 80W | 1.0A | 1.8A | 2.3A | 0.7A | 1.3A | 1.5A | 0.6A | 1.4A | 1.4 A |
| OM-6 | 650 | 5756 | 28s | 31s | 80W | 1.0A | 1.8A | 2.3A | 0.7A | 1.3A | 1.5A | 0.6A | 1.4A | 1.4A |
| OM-7 | 1000 | 8855 | 46 s | 55s | 120W | 0.9A | 2.0A | 2.2A | 0.7A | 1.2 A | 1.4 A | 0.5A | 1.3A | 1.3A |
| OM-8 | 1500 | 13282 | 46s | 55s | 120W | 1.0A | 2.4A | 2.6A | 0.7A | 1.5A | 1.5A | 0.6A | 1.2A | 1.2A |
| OM-9 | 2000 | 17709 | 58s | 70s | 180W | 1.3A | 3.7A | 3.9A | 0.7A | 2.0A | 2.3A | 0.7A | 2.0A | 2.2A |
| OM-10 | 2500 | 22137 | 58s | 70s | 180W | 1.3A | 3.4A | 3.9A | 0.7A | 2.0A | 2.4 A | 0.7A | 2.0A | 2.2A |
| OM-11 | 3000 | 26564 | 58s | 70s | 180W | 1.3A | 3.5A | 3.9A | 0.7A | 2.0A | 2.4 A | 0.7A | 2.0A | 2.2A |
| OM-12 | 3500 | 30991 | 58s | 70s | 220W | 1.5A | 4.8A | 5.4A | 0.9A | 2.5A | 2.5A | 0.8A | 2.6A | 2.4A |
| OM-13 | 4500 | 39846 | 80s | 95s | 220W | 1.5A | 4.9A | 5.4A | 1.0A | 2.5A | 2.5A | 0.8A | 2.6A | 2.4A |

## NOTE :

Run : Full Load Ampere
Lock : Locked Rotor Ampere

## STORAGE INFORMATION

## Receiving/Inspection

Carefully inspect for shipping damage. Damage to the shipping carton is usually a good indication that it has received rough handing. Report all damage immediately to the freight carrier and your seller.

After unpacking the product and information packet, please take care to save the shipping carton and any packing material in case of product return or replacement. Verify that the item on the packing list or bill of lading is the same as your own documentation. If there is any discrepancy, please contact with the seller.

## Storage

If the actuator cannot be installed immediately, store it in a dry place, it must be protected from excess moisture, dust, and weather until you are ready to connect cables.

If the actuator has to be installed but cannot be cabled, please don't remove the plastic transit cable entry plugs. When the actuator has to be cabled, it is recommended to replace to suitable water-proof plugs with IP protection.

## LUBRICATION

The gear train has been permanently lubricated at the factory sufficient.

## INSTALLATION

1. Before mounting actuator, verify that the torque requirement is less than the output torque of the actuator. (The suggested safety factor is $30 \%$ of the max. torque of valve.)

## For example :

If the maximum torque of 5 " valve is $80 \mathrm{~N} \cdot \mathrm{~m} \rightarrow 80 \times 1.3$ (safety factor) $=104 \mathrm{~N} \cdot \mathrm{~m}$

$$
\begin{aligned}
& 104 \mathrm{~N} \cdot \mathrm{~m}<150 \mathrm{~N} \cdot \mathrm{~m}(\mathrm{OM}-3) \rightarrow \mathrm{OK}! \\
& 104 \mathrm{~N} \cdot \mathrm{~m}>90 \mathrm{~N} \cdot \mathrm{~m}(\mathrm{OM}-2) \rightarrow \mathrm{NO}!
\end{aligned}
$$

2. Check if the output shaft fits to the stem of valve before inserting into actuator. Please use mounting plate or adaptor to connect if it does not match.
3. Insert output shaft adaptor into actuator. Make sure it fits satisfactory.
4. Determine that actuator position, open or closed, matches with position of equipment prior to mounting. Use manual override to change position if necessary.
5. Remove valve's manual device and mount on the proper connection.


CAUTION: Don't remove any necessary parts for the proper operation of the valve.
6. Check again that the valve and actuator are in the same position.
7. Install the actuator to valve directly or with mounting kits, then tighten all screws and nuts.
8. Remove actuator cover.

$\triangle$CAUTION: Be sure power is off at the main power box.
9. Wire actuator using the wiring diagram inside cover.

CAUTION: For the 3-Phase on-off controller actuator, please use the

$\triangle$hand-wheel to turn the actuator to 45 degree before test. If the operating direction is opposite after supplying power, please change any two of the $\mathbf{U}$, V, W.
10. Supply power to actuator.


CAUTION: Use remarkable mark warning "there are live circuits that could cause electrical shock or death".
11. Make sure if it is needed to calibrate the fully-open or fully-closed position of the actuator. Refer to the P49~P52 to set the fully -open or fully-closed position and mechanical stops.
12. If the actuator is modulating type, refer to P53~P70 to set the functions.

$\triangle$
13. Replace cover and secure cover screws.

## WIRING DIAGRAM

1. MC1 \& MC2 : Electromagnetic contactor.
2. NFB : No fuse breaker.
3. C.S. : Control switch.
4. C: Capacitor.
5. N : Neutral.
6. L : Live Wire.
7. PE : Protective Earth.
8. O.L. : Over-load relay.
9. H: Heater.
10. LS : Limit switch.
11. TS : Torque switch.
12. Switch(1) : Local/Remote Control.

Switch(2) : Open/Stop/Close select.
13. Duty cycle (Standard Model) :

BM-2, OM-A, OM-A-M, OM-F, OM-G, OM-1~OM-13 : 30\% duty cycle.
Extended duty cycle :
OM-A, OM-A-M, OM-1~OM-8 : 75\% duty cycle.
OM-9~OM-13 : 50\% duty cycle.
14. LS1 : Limit switch for open.

LS2 : Limit switch for close.
15. The usage for 2 additional limit switches :

## OM-1, OM-A, OM-A-M

LS3 Fully-Open : Terminal "A" connects to terminal "B".
LS4 Fully-Closed : Terminal "A" connects to terminal "E".

## OM-1, OM-A, OM-A-M (Option: MODBUS)

LS3 Fully-Open : Terminal "A" connects to terminal " $C$ ".
LS4 Fully-Closed : Terminal "D" connects to terminal "F".

## BM-2, OM-A, OM-AM, OM-F, OM-G, OM-2~OM-13

LS3 Fully-Open : Terminal "A" connects to terminal "C".
LS4 Fully-Closed : Terminal "D" connects to terminal "F".

## NOTE !

When a set of control wire or switch needs to control two or more actuators at the same time, please refer to P48 or install the coupling board.

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-1 , OM-A , OM-A-M 12V , 24V DC

## On-Off Controller



## NOTE:

1. "+" connects to \#1, "-" connects to \#7.
2. "-" connects to \#3 for "OPEN", "-" connects to \#4 for "CLOSE".
3. Using less than 3A current for "A, B, C, E, F".
4. Using battery to supply power for $D C$ units.

## WIRING DIAGRAM - Quarter Turn Actuator

OM-1, OM-A , OM-A-M 12V, 24V AC

## On-Off Controller

Power Supply
12V / 24V AC


## NOTE :

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than 3A current for "A, B, C, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

OM-1, OM-A , OM-A-M 110V , 220V AC 1-Phase

## On-Off Controller



## NOTE :

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than $3 A$ current for "A, B, C, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

OM-1, OM-A , OM-A-M 110V , 220V AC 1-Phase
On-Off Controller , 75\% duty cycle


## NOTE :

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than $3 A$ current for " $A, B, C, E, F$ ".

## WIRING DIAGRAM - Quarter Turn Actuator

OM-1, OM-A , OM-A-M 110V , 220V AC 1-Phase

## On-Off Controller , Coupling Board



## NOTE :

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than 3A current for "A, B, C, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-1, OM-A , OM-A-M 110V , 220V AC 1-Phase

## On-Off Controller , Analog Signal Output

## Power Supply

110V / 220V AC


## NOTE:

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "-" connects to \#4 for "CLOSE".
3. Using less than $3 A$ current for "A, B, C, E, F".
4. JP5 : 2~10V or 1~5V output mode ; J2 : 2~10V or 1~5V output signal

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-1, OM-A , OM-A-M 24V AC/DC

## On-Off Controller , Analog Signal Output

## Power Supply

24V AC/DC


## NOTE:

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "-" connects to \#4 for "CLOSE".
3. Using less than 3 A current for "A, B, C, E, F".
4. JP5 : 2~10V or $1 \sim 5 \mathrm{~V}$ output mode ; J2: 2~10V or $1 \sim 5 \mathrm{~V}$ output signal.

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-1 , OM-A , OM-A-M <br> 24V DC

## Modulating Controller



## NOTE :

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V (It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 3 A current for "A, B, C, E, F".
3. Using battery to supply power for DC units.

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-1, OM-A , OM-A-M 24V AC

## Modulating Controller



## NOTE :

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 3A current for "A, B, C, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

OM-1, OM-A , OM-A-M 110V , 220V AC 1-Phase

## Modulating Controller



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V (It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than $3 A$ current for " $A, B, C, E, F$ ".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-1, OM-A , OM-A-M <br> 24V AC

## Modulating Controller , MODBUS



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 3A current for "A, B, C, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-1 , OM-A , OM-A-M 24V DC

## Modulating Controller , MODBUS



## NOTE :

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30 m .)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 3 A current for "A, B, C, E, F".
3. Using battery to supply power for DC units.

## WIRING DIAGRAM - Quarter Turn Actuator

OM-1, OM-A , OM-A-M 110V , 220V AC 1-Phase

## Modulating Controller , MODBUS



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 3 A current for "A, B, C, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

OM-2 ~ OM-6 12V DC
OM-2 ~ OM-12 , OM-F , OM-G 24V DC
On-Off Controller


## NOTE:

1. "+" connects to \#1, "-" connects to \#7.
2. "-" connects to \#3 for "OPEN", "-" connects to \#4 for "CLOSE".
3. Using less than 5 A current for "A, B, C, D, E, F".
4. Using battery to supply power for DC units.

## WIRING DIAGRAM - Quarter Turn Actuator

OM-2 ~ OM-6 12V AC
OM-2 ~ OM-12 , OM-F , OM-G 24V AC

## On-Off Controller

## Power Supply

12V / 24V AC


## NOTE :

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than 5A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-7 ~ OM-10 12V DC

## On-Off Controller

## Power Supply

12V DC


## NOTE:

1. " + " connects to \#1, "-" connects to \#7.
2. "-" connects to \#3 for "OPEN", "-" connects to \#4 for "CLOSE".
3. Using less than 5 A current for " $A, B, C, D, E, F$ ".
4. Using battery to supply power for DC units.

## WIRING DIAGRAM - Quarter Turn Actuator

BM-2 , OM-2~OM-13 , OM-F , OM-G 110V , 220V AC 1-Phase

## On-Off Controller

Power Supply
110V / 220V AC


## WIRING DIAGRAM - Quarter Turn Actuator

OM-2 ~ OM-13 , OM-F , OM-G 110V , 220V AC 1-Phase

## On-Off Controller , Coupling Board



## NOTE :

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than 5 A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

BM-2 , OM-2 ~ OM-13 220V , 380V , 440V AC 3-Phase

## On-Off Controller

## Power Supply



## NOTE :

1. Using the hand-wheel to turn the actuator to 45 degree before test. If the operating direction is opposite after supplying power, please change any two of the $\mathrm{U}, \mathrm{V}, \mathrm{W}$.
2. Using less than 5 A current for "A, B, C, D, E, F".
3. BM-2 could not install torque switches.

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-8 110V , 220V AC 1-Phase

## On-Off Controller , 75\% duty cycle

## Power Supply

110V / 220V AC


## NOTE :

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than 5A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-9 ~ OM-13 110V AC 1-Phase

## On-Off Controller , 50\% duty cycle

## Power Supply

110V AC


## NOTE :

1. "N" connects to \#1, "L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than 5 A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-9 ~ OM-13 220V AC 1-Phase

## On-Off Controller , 50\% duty cycle



## WIRING DIAGRAM - Quarter Turn Actuator

OM-2 ~ OM-13 110V , 220V AC 1-Phase

## On-Off Controller, Analog Signal Output

## Power Supply

110V / 220V AC


## NOTE:

1. "N" connects to \#1, " L" connects to \#7.
2. "L" connects to \#3 for "OPEN", "L" connects to \#4 for "CLOSE".
3. Using less than 5A current for "A, B, C, D, E, F".
4. If the control power is $220 \mathrm{~V} \mathrm{AC}, \mathrm{N} \& \mathrm{~L}$ connect to \#1 \& \#3.

If the control power is 110 V AC, $\mathrm{N} \& \mathrm{~L}$ connect to \#1 \& \#2 or \#2 \& \#3.

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-13 220V , 380V , 440V AC 3-Phase

## On-Off Controller, Analog Signal Output



## NOTE:

1. If the control power is $220 \mathrm{~V} \mathrm{AC}, \mathrm{N} \& \mathrm{~L}$ connect to \#1 \& \#3.

If the control power is 110 V AC, N \& L connect to \#1 \& \#2 or \#2 \& \#3.
2. Using the hand-wheel to turn the actuator to 45 degree before test. If the operating direction is opposite after supplying power, please change any two of the $\mathrm{U}, \mathrm{V}, \mathrm{W}$.
3. Using less than 5 A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-6 12V DC

## OM-2 ~ OM-12 , OM-F , OM-G 24V DC

## Modulating Controller



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V (It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 5A current for "A, B, C, D, E, F".
3. Using battery to supply power for $D C$ units.

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-12 , OM-F , OM-G 24V AC

## Modulating Controller



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 5 A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-8 , OM-F , OM-G 110V , 220V AC 1-Phase

## Modulating Controller



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 5 A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-13 220V , 380V , 440V AC 3-Phase

## Modulating Controller



## NOTE:

1. Please change any two of the $\mathrm{U}, \mathrm{V}, \mathrm{W}$ when the power lamp is off.
2. Modulating Board
a. Input Signal : 4~20mA, 2~10V, 1~5V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal: 4~20mA, 2~10V
3. Local / Remote Switches
a. Select "Remote" : Controlled by signal.
b. Select "Local" : Controlled by switch (2).
4. Using less than 5A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-8 110V , 220V AC 1-Phase

## Modulating Controller , 75\% duty cycle



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 5 A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-9 ~ OM-13 110V AC 1-Phase

## Modulating Controller , 50\% duty cycle



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 5 A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-9 ~ OM-13 220V AC 1-Phase

## Modulating Controller , 50\% duty cycle



## NOTE:

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Using less than 5 A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

OM-2 ~ OM-13 110V , 220V AC 1-Phase

## On-Off Controller , Local Control Unit



## NOTE:

1. Using less than 5 A current for " $A, B, C, D, E, F$ ".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-13 220V , 380V , 440V AC 3-Phase

## On-off Controller , Local Control Unit



## NOTE :

1. Please change any two of the $\mathrm{U}, \mathrm{V}, \mathrm{W}$ when the power lamp is off.
2. Switch (3) is the switch of remote control (provided by user).
a. Connecting \#1 \& \#3 for OPEN.
b. Connecting \#1 \& \#4 for CLOSE.
c. \#1, \#3, \#4 can not connect together at the same time.
3. Using less than 5 A current for " $A, B, C, D, E, F$ ".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-8 110V , 220V AC 1-Phase

## Modulating Controller , Local Control Unit



## NOTE :

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30 m .)
b. Output Signal : 4~20mA, 2~10V
2. Local / Remote Switches
a. Select "Remote" : Controlled by signal.
b. Select "Local" : Controlled by switch (2).
3. Using less than 5A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

OM-2 ~ OM-8 110V , 220V AC 1-Phase
Modulating Controller, Local Control Unit , 75\% duty cycle


## NOTE :

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V
(It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Local / Remote Switches
a. Select "Remote" : Controlled by signal.
b. Select "Local " : Controlled by switch (2).
3. Using less than 5A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-9 ~ OM-13 110V AC 1-Phase

## Modulating Controller, Local Control Unit , 50\% duty cycle



## NOTE :

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V (It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Local/Remote Switches
a. Select "Remote" : Controlled by signal.
b. Select "Local" : Controlled by switch (2).
3. Using less than 5A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-9 ~ OM-13 220V AC 1-Phase

## Modulating Controller , Local Control Unit , 50\% duty cycle



## NOTE :

1. Modulating Board
a. Input Signal : 4~20mA, 1~5V, 2~10V (It is suggested to use the shielding wire and its length should not exceed 30m.)
b. Output Signal : 4~20mA, 2~10V
2. Local / Remote Switches
a. Select "Remote" : Controlled by signal.
b. Select "Local" : Controlled by switch (2).
3. Using less than 5A current for "A, B, C, D, E, F".

## WIRING DIAGRAM - Quarter Turn Actuator

OM-2 ~ OM-13 110V , 220V AC 1-Phase
On-off Controller, Local Control Unit , Analog Signal Output


## NOTE :

1. Using less than 5 A current for "A, B, C, D, E, F".
2. If the control power is 220 V AC, $\mathrm{N} \& \mathrm{~L}$ connect to \#1 \& \#3.

If the control power is 110 V AC, $\mathrm{N} \& \mathrm{~L}$ connect to \#1 \& \#2 or \#2 \& \#3.

## WIRING DIAGRAM - Quarter Turn Actuator

## OM-2 ~ OM-13 220V , 380V , 440V AC 3-Phase

## On-off Controller , Local Control Unit , Analog Signal Output



## NOTE :

1. Please change any two of the $\mathrm{U}, \mathrm{V}, \mathrm{W}$ when the power lamp is off.
2. Switch (3) is the switch of remote control (provided by user).
a. Connecting \#1 \& \#3 for OPEN.
b. Connecting \#1 \& \#4 for CLOSE.
c. \#1, \#3, \#4 can not connect together at the same time.
3. Using less than 5 A current for " $A, B, C, D, E, F$ ".

## WIRING DIAGRAM - Quarter Turn Actuator

## BM-2, OM-A, OM-A-M, OM-1~OM-13, OM-F, OM-G 110V, 220V AC 1-Phase

## Same Switch Coupling Wiring



## NOTE :

1. The wiring is based on 3 sets of actuators for one switch - 1 set is open and 2 sets are close. (If more sets, the rest can be done by this logic.)
2. When a set of control wire or switch needs to control two or more actuators at the same time, please refer to the wiring diagram.
3. Add one contactor for separation to prevent the interference of compression coupling.
4. $\mathrm{C} 1=3 \mathrm{a} 3 \mathrm{~b}$ contactor

## ADJUSTMENT - Travel Cam \& Limit Switches

## NOTE:

If LS3 \& LS4 are fitted, they should be set to trip prior to LS1 \& LS2 to avoid over-travel.

The travel cams are set to control the open and closed position of the valve. The position is set to stop the travel of the actuator when the travel cams activate the limit switch. Standard is two limit switches (LS1 \& LS2), one for open, one for closed. LS1 \& LS2 limit the maximum range by disabling the electric motor. LS3 \& LS4 are optional. They allow external equipment to confirm that the valve has reached the fully open and fully closed positions.

The travel cams can be adjusted with a 2.5 mm Allen key. The cams are preset at the factory. When additional adjustments are needed, follow steps described below.

## OM-A, OM-A-M

## 1. To set the open position:

a. Turn power off.
b. Use manual override to turn valve to the fully-open position.
c. Remove cover and loosen the M5 set screw on the TC1 with a 2.5 mm Allen Key.
d. Rotate cam(TC1) counterclockwise to contact with switch.
e. Slowly rotate cam(TC1) clockwise until a light click is heard.
f. Securely tighten the M5 set screw and apply power to check the travel position. If the position is not correct, please repeat steps a $\sim \mathrm{f}$.
g. After the adjustment is completed, check again the M5 set screw is securely tightened.
2. To set the close position:
a. Turn power off.
b. Use manual override to turn valve to the fully-closed position.
c. Loosen the M5 set screw on the TC2 with a 2.5 mm Allen key.
d. Rotate cam(TC2) clockwise to contact with switch.
e. Slowly rotate cam(TC2) counterclockwise until a light click is heard.
f. Securely tighten the set screw and apply power to check the traveling position. If the position is not correct, please repeat steps a $\sim \mathrm{f}$.
g. After the adjustment is completed, check again the M5 set screw is securely tightened.

Modulating type: Loosen M5 set screw on round gear before setting, after completing fully-open and fully-closed calibration, run the actuator to fully-closed position, then rotate round gear counterclockwise to the end and tighten M5 set screw.

## ADJUSTMENT－Travel Cam \＆Limit Switches

【OM－A，OM－A－M】


TC 4 Synchronous turn with TC2（optional）．
TC 3 Synchronous turn with TC1（optional）．
TC 2 ＂CLOSE＂
Clockwise：increase closing degree to fully closed．
Counterclockwise：decrease closing degree．
TC 1 ＂OPEN＂Clockwise：decrease opening degree．
5 Counterclockwise：increase opening degree to fully open．

## OM－1，BM－2，OM2～13，OM－F，OM－G

1．To set the open position：
a．Turn power off and loosen both mechanical stops（Please refer to P52 and except OM－A，BM－2，OM－A，OM－A－M）．
b．Use manual override to turn valve to the fully－open position．
c．Remove cover and loosen the M5 set screw on the TC1 with a 2.5 mm Allen key．
d．Rotate cam（TC1）clockwise to contact with switch．
e．Slowly rotate cam（TC1）counterclockwise until a light click is heard．
f．Securely tighten the set screw and apply power to check the travel position．If the position is not correct，please repeat steps a $\sim \mathrm{f}$ ．
g．After the adjustment is completed，check again the M5 set screw is securely tightened．

## ADJUSTMENT－Travel Cam \＆Limit Switches

2．To set the close position：
a．Turn power off．
b．Use manual override to turn valve to the fully closed position．
c．Loosen the M5 set screw on the TC2 with a 2.5 mm Allen key．
d．Rotate cam（TC2）counterclockwise to contact with switch．
e．Slowly rotate cam（TC2）clockwise until a light click is heard．
f．Securely tighten the set screw and apply


Round gear
 power to check the travel position．If the position is not correct，please repeat steps a $\sim \mathrm{f}$ ．
g．After the adjustment is completed，check again the M5 set screw is securely tightened．
h．Tighten both mechanical stops and per P52．
Modulating type：Loosen M5 set screw on sector gear（Round gear）before setting，after completing fully－open and fully－closed calibration，run the actuator to fully－closed position，then rotate sector gear（Round gear）clockwise to the end and tighten M5 set screw．


TC 4 Synchronous turn with TC2（optional）．
TC 3 Synchronous turn with TC1（optional）．
TC 2 ＂CLOSE＂Clockwise：decrease closing degree．
S Counterclockwise：increase closing degree to fully－closed．
TC 1 ＂OPEN＂Clockwise：increase opening degree to fully－open．
Counterclockwise：decrease opening degree．

## ADJUSTMENT－Mechanical Stops

$\triangle$

## CAUTION！

Mechanical stops should only be reached during manual operation．

The Mechanical stops are factory set，though in some cases adjustment may be required once a valve is fitted．

1．For Electric Operation
Please refer to＂Adjustment－Travel Cam \＆Limit Switches＂．

2．For Manual Operation
a．Turn power off．
b．Loosen locknut and unwind it a few turns．
c．For modulating type，loosen the set screw on the sector gear first．
d．Use manual override to turn the actuator to desire limit position．
e．For modulating type，rotate sector gear clockwise to the end．Then tighten set screw．
f．Tighten the mechanical stop screw until it reaches the shaft，then reverse one cycle．
g．Tighten locknut．
h．Check that the electrical limit switches can still be reached．


【OPEN】
【CLOSE】

## ADJUSTMENT - Modulating Control Board

## Part A: Suitable for OM-1~OM-13, OM-A, OM-A-M , OM-F , OM-G

1. Surface The surface is based on the actuator in $110 / 220 \mathrm{~V}$ voltage. OM-1 , OM-A, OM-A-M


OM-2~OM-13, OM-F , OM-G


## ADJUSTMENT - Modulating Control Board

Part A: Suitable for OM-1~OM-13, OM-A, OM-A-M , OM-F , OM-G
2. Procedure


Supplied Voltage : 24V DC / AC, 110V / 220V AC 1- Phase
3. DIP-SWITCH SETTING (SW1)


|  | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Factory setting | ON | OFF | OFF | ON | OFF | OFF | OFF | ON |
| 4~20mA input | ON | OFF |  |  |  |  |  |  |
| 1~5V input | OFF | OFF |  |  |  |  |  |  |
| 2~10V input | OFF | ON |  |  |  |  |  |  |
| 4~20mA output |  |  | OFF | ON | OFF |  |  |  |
| 2~10V output |  |  | ON | OFF | ON |  |  |  |
| $20 \mathrm{~mA} / 5 \mathrm{~V} / 10 \mathrm{~V}$ m | ans va | fully-0 |  |  |  | OFF |  |  |
| $20 \mathrm{~mA} / 5 \mathrm{~V} / 10 \mathrm{~V}$ m | ans va | fully- | sed |  |  | ON |  |  |
| Close valve if input | ignal | conne | d ( wh | S6 s | " OFF |  | OFF | ON |
| Open valve if input | ignal | conne | d ( wh | S6 s | " OFF |  | ON | OFF |
| Actuator will not op (when S6 sets " | rate if ") | ut sig | disco | ected |  |  | $\begin{gathered} \mathrm{ON} \\ \mathrm{OFF} \end{gathered}$ | $\begin{gathered} \mathrm{ON} \\ \mathrm{OFF} \end{gathered}$ |

NOTE:

1. After completing dip-switch setting, restart the actuator.
2. The standard factory presetting is $1,4,8$ for $O N$ and $2,3,5,6,7$ for OFF.

## ADJUSTMENT - Modulating Control Board

Part A: Suitable for OM-1~OM-13, OM-A, OM-A-M, OM-F , OM-G

|  | FUNCTION | SETTING |
| :---: | :---: | :---: |
| S1, 2 | INPUT SIGNAL SELECT. | $\begin{aligned} & " 4 \sim 20 \mathrm{~mA} \text { " set } 1-\mathrm{ON} / 2-O F F \text {. } \\ & " 1 \sim 5 \mathrm{~V} \text { " set } 1-\mathrm{OFF} / 2-O F F \text {. } \\ & " 2 \sim 10 \mathrm{~V} \text { " set } 1-\mathrm{OFF} / 2-O N . \end{aligned}$ |
| S3, 4, 5 | OUTPUT SIGNAL SELECT. | $\begin{aligned} & " 4 \sim 20 \mathrm{~mA} \text { " set 3-OFF / 4-ON / 5-OFF. } \\ & \text { " } 2-10 \mathrm{~V} \text { " set } 3-O N / 4-O F F / 5-O N . \end{aligned}$ |
| When S 6 sets "ON" |  |  |
| S6 | INPUT SIGNAL SELECT : <br> $4 \mathrm{~mA}, 2 \mathrm{~V}, 1 \mathrm{~V} \quad \rightarrow$ valve fully-open. <br> $20 \mathrm{~mA}, 10 \mathrm{~V}, 5 \mathrm{~V} \rightarrow$ valve fully-closed. | Set 6-ON. |
| S7, 8 | POSITION SELECT. <br> (When the input signal fails.) | "valve fully-closed" set 7-ON / 8-OFF. <br> "valve fully-open" set 7-OFF / 8-ON. <br> "valve stops" set 7-ON / 8-ON. <br> or 7-OFF/ 8-OFF. |

When S6 sets "OFF "

| S6 | INPUT SIGNAL SELECT : <br> $4 \mathrm{~mA}, 2 \mathrm{~V}, 1 \mathrm{~V} \rightarrow$ valve fully-closed. <br> $20 \mathrm{~mA}, 10 \mathrm{~V}, 5 \mathrm{~V} \rightarrow$ valve fully-open. | Set 6-OFF. |
| :---: | :---: | :---: |
| S7, 8 | POSITION SELECT. <br> (When the input signal fails.) | "valve fully-closed" set 7-OFF / 8-ON. <br> "valve fully-open" set 7-ON / 8-OFF. <br> "valve stops" set 7-ON / 8-ON. <br> or 7-OFF / 8-OFF. |

## ADJUSTMENT - Modulating Control Board

## Part A: Suitable for OM-1~OM-13, OM-A, OM-A-M , OM-F , OM-G

4. Sensitivity Switch Setting(SW2)

a. When switch to " 1 ": The Highest Sensitive and the $0 \sim 90$ degree can be divided up to around 50 times movement
b. When switch to " 0 ": The Lowest Sensitive and the $0 \sim 90$ degree can be divided up to around 10 times movement.
c. The sensitivity decreases 5 times movement by sectors from SW1 to SW2, SW2 to SW3, SW3 to SW4 and so on.
5. Settings for OPEN and CLOSE (OM-1, OM-A, OM-A-M) The settings are set at factory, though in some cases re-set may be required when a particular rate of signal is requested.

## Adjust output signal/input signal



Note: If it is necessary to adjust VR51 and VR52, VR1 and VR2 also need to be adjusted accordingly.
a. Rotate VR1 counterclockwise until a light click is heard, then supply 10 V (or 20 mA ) to modulating board. Slightly rotate VR1 clockwise until green LED keeps on. Adjust VR51 to complete.
VR51: Clockwise: decreasing signal.
5 Counterclockwise: increasing signal.
b. Rotate VR2 clockwise until a light click is heard, then supply 2V (or 4mA) to modulating board. Slightly rotate VR2 counterclockwise until red LED keeps on.
Adjust VR51 to complete.
VR52 : Clockwise: decreasing signal.
Counterclockwise: increasing signal.

## ADJUSTMENT - Modulating Control Board

Part A: Suitable for OM-1~OM-13, OM-A, OM-A-M , OM-F , OM-G
6. Settings for OPEN and CLOSE (OM-2~OM-13, OM-F , OM-G)

The settings are set at factory, though in some cases re-set may be required when a particular rate of signal is requested.

## OPEN setting

a. Keep pressing "SET" for 2 seconds, then LD 9 comes on, it will enter to the manual mode.
b. Keep pressing "UP" until actuator runs to fully-open position, LD2 comes on, then supplies the input signal ( 5 V or 10 V or 20 mA ).
c. Press "MODE" once. The OPEN setting is completed.

## CLOSE setting

a. Keep pressing "DOWN", until actuator runs to fully-closed position, LD1 comes on , then supplies input signal ( 1 V or 2 V or 4 mA ).
b. Press "MODE" once. The CLOSE setting is completed.

## After completing the above settings, press "SET" once Adjust output signal

VR2 : Clockwise: increasing signal.
Counterclockwise: decreasing signal.

## ADJUSTMENT - Modulating Control Board

Part A: Suitable for OM-1~OM-13, OM-A, OM-A-M, OM-F , OM-G
7. Lamp Signal (OM-2~OM-13, OM-F , OM-G)

| LD1 | Fully-closed | LD6 | Motor thermostat turn off |
| :--- | :--- | :--- | :--- |
| LD2 | Fully-open | LD7 | Output signal short circuit |
| LD3 | Power | LD8 | Motor current is excessive |
| LD4 | Abnormal Voltage | LD9 | Manual Mode |
| LD5 | Wrong input signal |  |  |

If the LED (LD4~LD9) is flashing under modulating control, refer to the following "Modulating Board Troubleshooting".

| Lamp | Possibilities | Solution |
| :---: | :---: | :---: |
| No Lamp (LD3 off) | a. No power supply. <br> b. The voltage is over 260 V to cause the board burn out. <br> c. Wrong connecting for the \#8, \#9 of the VR. <br> d. Faulty Modulating board. | a. Check the power supply and wiring (\#4 \& \#5 of modulating board). <br> b. Check the voltage. <br> c. Check the wiring. <br> d. Send back to factory for inspection. |
| LD5 | a. Setting in 2-10V input signal but supply $4-20 \mathrm{~mA}$. <br> b. Setting in 2-10V input signal, but the input signal is over 13.5 V . <br> **Setting in 4-20mA but supply 2-10V signal. The actuator could still be operated within 2~7V. But if the signal is over 7.2 V the LED5 will come ON. | Confirm if the input signal is the same as dip switch setting ( refer to P54~P55). |
| LD 6 | Motor thermostat turns off. | a. Too high frequency for rated duty cycle(refer to P2). <br> b. Motor thermostat (MOT) is not connected. |
| LD7 | a. Output signal short circuit. <br> b. Wrong connecting of the $2-10 \mathrm{~V}$ input signal. | a. Confirm the wiring of output signal \#11(-), \#12(+). <br> b. Confirm the input signal for \#6(-) , \#7(+). |
| LD8 | Motor current is excessive. | a. Too high frequency for rated duty cycle (refer to P2). <br> b. Check the load (refer to P4~P5). <br> c. Check if the motor rotor is locked (For example: Valve is stuck by foreign objects). |
| LD9 | Manual Mode - Setting position for open \& close. | After completing the settings, press "SET" once. |

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

1. Surface

2. Procedure


## ADJUSTMENT - Modulating Control Board

Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)
3. DIP-SWITCH SETTING (SW)


Analog signal output

| 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ON | OFF | OFF | OFF | ON | OFF | OFF | ON | Factory setting |
|  |  |  |  |  |  | OFF | ON | 4-20mA input |
|  |  |  |  |  |  | OFF | OFF | $1-5 \mathrm{~V}$ input |
|  |  |  |  |  |  | ON | OFF | 2-10V input |
|  |  |  | OFF | ON | OFF | 4-20mA output |  |  |
|  |  |  | ON | OFF | ON | 2-10V output |  |  |
|  |  | OFF | $20 \mathrm{~mA} / 5 \mathrm{~V} / 10 \mathrm{~V}$ means valve fully-open |  |  |  |  |  |
|  |  | ON | $20 \mathrm{~mA} / 5 \mathrm{~V} / 10 \mathrm{~V}$ means valve fully-closed |  |  |  |  |  |
| ON | OFF | Close valve if input signal disconnected ( when S6 sets " OFF") |  |  |  |  |  |  |
| OFF | ON | Open valve if input signal disconnected ( when S6 sets " OFF") |  |  |  |  |  |  |
| $\begin{aligned} & \text { ON } \\ & \text { OFF } \end{aligned}$ | $\begin{aligned} & \text { ON } \\ & \text { OFF } \end{aligned}$ | Actuator will not operate if input signal disconnected (when S6 sets " OFF") |  |  |  |  |  |  |

```
MODBUS
```

| 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | ON | ON | ON | ON | ON | MODBUS |
| OFF | OFF | OFF | Actuator will not operate if input signal disconnected |  |  |  |  |  |

## NOTE:

1. After completing dip-switch setting, restart the actuator or wait for 5 secs.
2. The standard factory presetting is $1,4,8$ for ON and $2,3,5,6,7$ for OFF.

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

Analog signal output

| Dip-switchSetting | FUNCTION | SETTING |
| :---: | :---: | :---: |
| S1, 2 | INPUT SIGNAL SELECT. | $\begin{aligned} & \text { " } 1 \sim 5 \mathrm{~V} \text { " set 1-OFF / 2-OFF. } \\ & \text { " } 2^{\sim} 10 \mathrm{~V} \text { " set 1-OFF / 2-ON. } \\ & \text { " } 4^{\sim} 20 \mathrm{~mA} \text { " set 1-ON / 2-OFF. } \end{aligned}$ |
| S3, 4, 5 | OUTPUT SIGNAL SELECT. | "2-10V" set 3-ON / 4-OFF / 5-ON. <br> "4-20mA" set 3-OFF / 4-ON / 5-OFF. |

When S6 sets " ON "

| S7, 8 POSITION SELECT | "valve fully-closed" set 7-ON / 8-OFF. |  |
| :---: | :---: | :--- |
|  | (When the input signal fails) | "valve fully-open" set 7-OFF 8-ON. |
|  | "valve stops" set 7-ON / 8-ON.Or 7-OFF / 8-OFF. |  |

When S6 sets " OFF "

| S7, 8 POSITION SELECT | "valve fully-closed" set 7-OFF 8-ON. |
| :---: | :---: | :--- |
|  | "valve fully-open" set 7-ON / 8-OFF. |
|  |  |

MODBUS

| Dip-switch Setting | FUNCTION | SETTING |
| :---: | :---: | :--- |
| S1~5 | MODBUS SELECT | MODBUS set 1~5-ON. |
| S6~8 | POSITION SELECT |  |
|  | (When the input signal fails) | "valve stops" set 7-OFF / 8-OFF. |

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

4. Sensitivity Switch Setting (SR1)

5. Factory setting for software edition U 20 is 3 .

Factory setting for software edition U21 is 0

* The software edition will be displayed on LED indication when the actuator powers on.

2. When switching to "1", it will respond at the highest level of sensitivity. When switching to " 0 ", it will respond at the lowest level of sensitivity.
3. The factory setting of the accumulated variation in sensibility for each movement is 0.3 mA and the total variation can be divided into approx. 54 movements.
4. Lamp Indication

| Lamp | Actuator Status |
| :--- | :--- |
| OPD | Fully-open position |
| OP | Opening direction |
| REM | Remote control mode |
| PL | Alerting signal |
| SL | Setting mode |
| LOC | Local control mode |
| CL | Closing direction |
| CLD | Fully-closed position |

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

6. LED Indication
a. Setup flow chart


## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

b. The funtion of LED indication

| LED indication | Function |
| :---: | :---: |
| Hi | Error log |
| $\boldsymbol{P} \boldsymbol{H} \boldsymbol{r}$ | Basic parameter |
| 105 | Local control |
| $1 \square 0$ | Fast setting |
| H 4 | Auto run |
| ¢ $\square \triangle$ | Running time setting |
| $F \boldsymbol{7}$ | Wrong input signal |
| $\boldsymbol{\square} \boldsymbol{\square} \boldsymbol{r}$ | Input signal setting for fully-closed position |
| $F \\|!$ | Input signal setting for fully-open position |
| $5 \pi 5$ | Sensitivity Setting |
| $10 \square$ | Fully-closed position setting |
| Hi | Fully-open position setting |
|  | Output signal setting for fully-closed position |
| $F$  | Output signal setting for fully-open position |
| $b \square$ | Baud rate setting for MODBUS |
| ¢ $\quad$ d | Station setting for MODBUS |
| $\underline{d} \boldsymbol{\square}$ | Display setting |

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

7. Adjustable Speed Setting
a. Press "MODE" several times to get into $\boldsymbol{\square} \boldsymbol{\sim}$, then press "SET" once to enter parameter setting mode.
b. Get into
 and keep pressing "SET" (around 3 sec ) to enter setting mode.
c. Adjust with "UP" and "DOWN" to the required selection.

| Selection | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Running time <br> (Sec.) | Standard | 30 | 60 | 80 | 100 | 120 | 150 | 180 | 200 | 200 |

d. Press "SET" once to complete the adjustable speed setting.
e. Press "MODE" five times to go back to position indicator to complete the setting.

## 8. Travel Setting

a. Press "MODE" five times to get into 180.
b. Keep pressing "SET" (around 5 sec ) until "LOC" comes on, entering the Auto run mode.
c. When the Auto run is completed, "LOC" comes off and the actuator will stop running. The travel setting is completed.

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

9. Signal Setting


## Input signal setting for fully-closed position

a. Press "MODE" several times until get into i a , then press "SET" once to enter signal setting mode.
b. Get into $\square^{\square}$, and keep pressing "SET" (around 3 sec ) until $\square$ glittering.
c. Supply the input signal according to the dip switch setting (1V or 2 V or 4 mA ).
d. Press "SET" once and "MODE" twice to complete the input signal setting for fully-closed position.

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

## Input signal setting for fully-open position

a. Press "MODE" several times until get into 1 , then press "SET" once to enter signal setting mode.
b. Adjust with "UP" and "DOWN" until get $F \begin{array}{ll}F i l \\ L i\end{array}$
c. Keep pressing "SET" (around 3 sec ) until $5 i$
d. Supply the input signal according to the dip switch setting ( 5 V or 10 V or 20 mA ).
e. Press "SET" once and "MODE" twice to complete the input signal setting for fully-open position.

## Output signal setting for fully-closed position

Install the ammeter or monitor to correspond to output signal setting
a. Press "MODE" several times until get into $i \quad \square$, then press "SET" once to enter signal setting mode.
b. Adjust with "UP" and "DOWN" until get into $\Sigma^{7}$.
c. Keep pressing "SET" (around 3 sec ).
d. Adjust the output value with "UP" and "DOWN" until the value can fit with your request.
e. Press "SET" once and "MODE" twice to complete the output signal setting for fully-closed position.

## Output signal setting for fully-open position

! Install the ammeter or monitor to correspond to output signal setting
a. Press "MODE" several times until get into $1 \square$, then press "SET" once to enter signal setting mode.
b. Adjust with "UP" and "DOWN" until get $F / \square$.
c. Keep pressing "SET" (around 3 sec ).
d. Adjust the output value with "UP" and "DOWN" until the value can fit with your request.
e. Press "SET" once and "Mode" twice to complete the output signal setting for fully-open position.

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

## 10.Warning Message

a. Press "MODE" once to get into $\square \square \square$, then press "SET" once to get into warning message.
b. Adjust with "UP" and "DOWN" to review the history log of warning message.


※ The latest data will stay with the item 9 .

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

c. Example

- If you want to check the latest data, press "MODE" several times until get into $\because L \square \rightarrow$ Press "Set" once $\rightarrow$ The LED display will show the latest data 7.
- If you want to check eighth data, press "MODE" several times until get into FL $\square \rightarrow$ Press "SET" once $\rightarrow$ Press "DOWN" seven times and the LED display will show the eighth data.


## 11.MODBUS Setting

0 MODBUS and modulating controller can not be operated at the same
(1) Adjust the dip switch (SW) Pin1~ Pin5 to "ON" position ; Pin6~ Pin8 to "OFF" position.
(2) Baud rate setting
a. Press "MODE" twice until get into $\boldsymbol{\square} \boldsymbol{\square} \boldsymbol{\square}$.
b. Press "SET" once to get into $5 \boldsymbol{P} \boldsymbol{d}$.
c. Press "DOWN" ten times to enter to $\quad 6$.
d. Keep pressing "SET" (around 3 sec ) until the LED indicator is glittering to get into setting mode.
e. Adjust with "UP" and "DOWN" to set baud rate for MODBUS. Adjust to your demand value. (default valve \#4)

| Setting Value | Baud rate |
| :---: | :---: |
| 4 | 9600 |
| 5 | 19200 |

f. Press "SET" once to complete the setting.

## ADJUSTMENT - Modulating Control Board

## Part B: Suitable for OM-1, OM-A, OM-A-M (Option: MODBUS)

(3) Station Setting
a. Press "DOWN" once to get into $i d \square$.
b. Keep pressing "SET" (around 3 sec ) until the LED indicator is glittering to get into setting mode.
c. Adjust with "UP" and "DOWN" to set the station. (Station Range:1~127, default Station: 1)
d. Press "Set" once to complete the setting.
(4) Press "Mode" four times to back to home page.

## TROUBLE SHOOTING

## ON-OFF Controller

1. Motor does not operate and overheats

## Possibilities

a. Supply power to \#3, \#4 simultaneously (Parallel Connection).
b. The capacitor failed (whether the surface of the capacitor deforms).
c. Valve's rubber is getting hardened or the valve's torque is excessive (it takes longer time to reach fully-closed position).
d. Foreign objects in the flow stream.
e. Broken motor stem or bearing.
f. The limit switch for fully-closed does not trip.

Solution
a. Check the wiring (For coupling wiring, refer to P48).
b. Replace to a new part.
c. Use hand-wheel for test or change to a new valve.
d. Check if any obstructions
e. Replace to a new parts
f. Operate the actuator manually to fully-closed position and confirm if the limit switch trips.
2. The actuator is operated very well but the motor is hot.

## Possibilities

a. Actuator operates too frequently (Starting frequency is too high).
b. Overload.
c. Under or over rated voltage.
d. Mechanical stops are reached by the gear train at fully-open or fully-closed position.
e. Wrong power supply.

Solution
a. Change system bandwidth or replace to a higher duty cycle actuator (refer to P2).
b. This situation often happens after operating for a long time. It is suggested to replace to a new valve.
c. Check the supply circuit (refer to P4~P5).
d. Reset the mechanical stops and cam (TC1 \& TC2) (refer to P49~P52).
e. Check the power supply.
3. When operating two or more actuators simultaneously, the actuator works abnormally some times and the motor is getting hot.

Possibilities
Parallel connection.

## Solution

a. Check current values and install a relay respectively.
(refer to wiring diagram P48)

## TROUBLE SHOOTING

4. The valve can not fully-open or fully-closed by either power supply or hand-wheel.

## Possibilities

a. The actuator does not mount with the valve tightly during installation process.
b. The torque of valve is larger than the torque of actuator.
c. The set screw of the cam is loose.
d. The installing angle of actuator and valve is not correct.
5. The capacitor is failed.

## Possibilities

a. Overload (exceed the rated torque of actuator).
b. Starting frequency is too high or ambient temperature is too high.
c. Over service life.
Possibilities
a. Overload (exceed the rated torque of
actuator).
b. Starting frequency is too high or
ambient temperature is too high.
c. Over service life.

Solution
a. Contact technical department to solve the problem.
b. Replace to a new valve or a larger actuator.
c. Readjust the mechanical stops and limit switches (refer to P49~P52).
d. Check the angle of the valve and actuator.

## Solution

a. Replace to a new part. It's suggested to change a new valve or a larger actuator.
b. Replace to a new part and change to $75 \%$ duty cycle actuator (refer to P2).
c. Check the capacitance and surface every year.

## Modulating Controller

1. The LED (LD5~LD9) is flashing after the operating check is completed.

## Solution

Refer to P58.
2. The lamps on the modulating board are normal but the actuator can't work properly during test or it only can turn to fully open/closed position.

| Possibilities |
| :--- |
| The signal is connected oppositely |
| (means to signal failure). |

3. Can not operate by modulating controller.
Possibilities
a. Faulty VR.
b. The sector gear of the VR is loose.
c. Wrong input signal.
d. Faulty modulating board.

## Solution

Confirm if the input signal and the wiring are correct (terminal \#6 connects to
"-" and terminal \#7 connects to "+").
a. Replace to a new VR.
b. Remove the input signal wires. Operate the actuator to fully-closed.
Then readjust the VR (refer to P49~P51).
c. Check if the input signal is correct (refer to P49~P51).
d. Send back to factory for inspection.

## WARRANTY

Sun Yeh Ele. Co. Ltd warrants that for a period of twelve months from the date of manufacture it will either repair or replace, at its option, any of its products which prove to be defective in material or workmanship. This warranty does not cover damage resulting from causes such as abuse, misuse, modification or tampering by users.

This warranty is extended only to the immediate purchaser of Sun Yeh product and is not transferable.

To obtain service under this warranty, the purchaser must first acquire a return authorization from Sun Yeh. Products must be returned to Sun Yeh under freight prepaid.

This warranty is in lieu of all other obligations, liabilities or expressed warranties. Any implied warranties, including any implied warranty of merchantability are hereby expressly excluded. In no event shall Sun Yeh be liable for special, incidental or consequential damages arising in connection with the use of its products, or for any delay in the performance of this warranty due to cause beyond its control.

