Fuji Electric

Innovating Energy Technology

High Performance Multifunctional Inverters

FRENIC-MEGA Series

New Standard

FRENIC-MEGA G2

With the flexibility and functionality to support a wide range of applications on all types of mechanical equipment, the FRENIC-MEGA takes core capability, responsiveness, environmental awareness, and easy maintenance to the next level.

CE c UL us LISTED

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The Industry's Best Just Got Better

Inherits the excellent performance specifications and functionality of the G1 Series while providing a more stylish design.
Unrelenting pursuit of performance and functionality to further enhance adaptability.
It is time to experience the fullness of the MEGA Series world.

High basic performance

Supports vector control, sensorless vector control, dynamic torque vector control, and V/f control.

Various applications

Comes with feature-rich functionality and enhances compatibility with system networks.

FRENIC-MEGA

G2

SERIES

Easy maintenance

Enhances work efficiency through simplified wiring and configuration and ensures safety and security through standard features such as preventive and predictive maintenance functions.

Environmentally resistant

Globally compliant lineup compatible with adverse atmospheres and various safety standards.

CONTENTS

Features

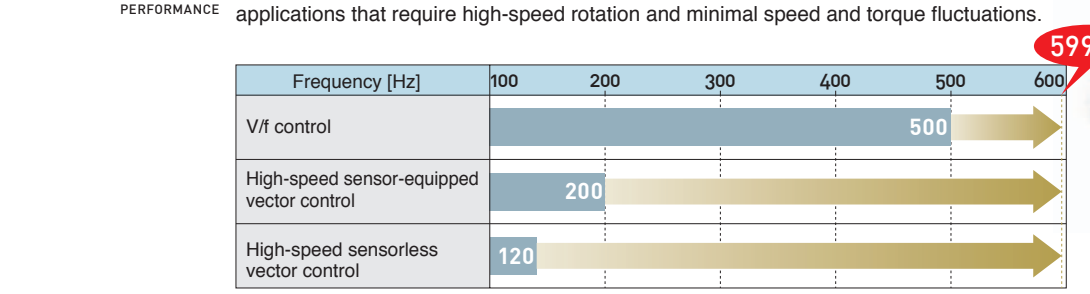
High basic performance

Supports vector control, sensorless vector control, dynamic torque vector control, and V/f control.

01 Faster operating speeds Expanded range

HIGH BASIC PERFORMANCE

Increases the maximum output frequency of all control systems to 599 Hz and supports applications that require high-speed rotation and minimal speed and torque fluctuations.



* Due to revised export control regulations (for frequency converters), the inverter will trip when the output frequency exceeds the upper limit of 599 Hz.

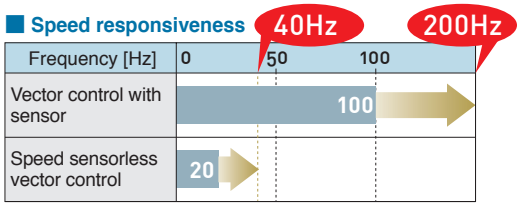
Example	Machine tools, compressors, automotive testing equipment, etc.

02 Enhanced response Improved speed and current

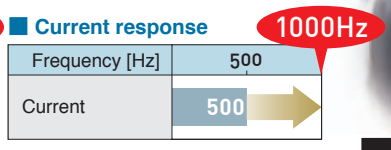
HIGH BASIC PERFORMANCE

Improves speed and current responsiveness and stabilizes product quality by substantially reducing torque ripple and rotation irregularities.

■ Speed responsiveness



■ Current response



Example	Wire drawing machines, metal processing machines, printing machines, etc.

03 Enhanced torque Improves the speed control range

HIGH BASIC PERFORMANCE

Stabilizes torque at low speeds and increases the accuracy of machine operations through its improved speed control range.

■ Speed control range

Induction motor	V/f control	Minimum speed	1:20	Base speed
		Constant torque region	1:2	Constant output region
	Dynamic torque vector control	Minimum speed	1:200	Base speed
		Constant torque region	1:2	Constant output region
	During sensorless vector control	Minimum speed	1:200	Base speed
		Constant torque region	1:2	Constant output region
	During sensor-equipped vector control	Minimum speed	1:1500	Base speed
		Constant torque region	1:16	Constant output region
Synchronous motors	During sensorless vector control	Minimum speed	1:10	Base speed
	During sensor-equipped vector control	Minimum speed	1:1500	Base speed

Example	Conveyance machinery, press machines, etc.

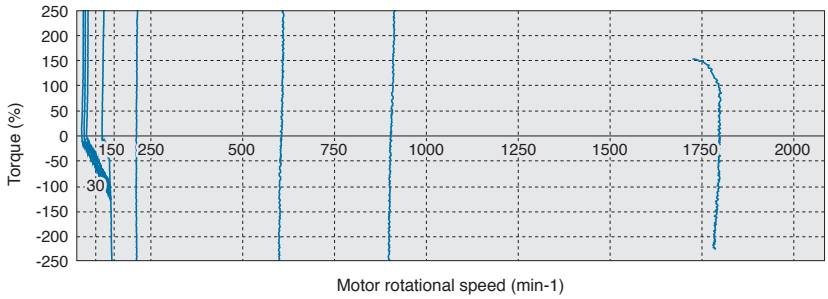
04 Advanced dynamic torque vector control

HIGH BASIC PERFORMANCE

Enhances our proprietary dynamic torque vector control with new motor constant tuning (that takes into account the voltage of the main circuit) and newly designed magnetic flux observer.

Low-speed frequency 0.3 Hz → starting torque 200%

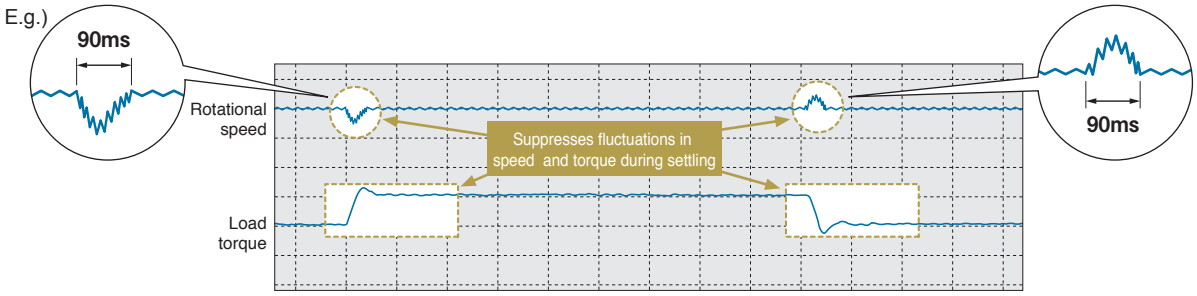
■ Example of torque characteristics (typical unit: 22 kW)



05 Strengthens ability to handle impact loads

HIGH BASIC PERFORMANCE

Achieves its class's highest level of torque responsiveness to sudden load changes.
Minimizes fluctuations in motor rotational speed and suppresses vibration via magnetic flux control.



06 Can be used with any motor NEW

HIGH BASIC PERFORMANCE

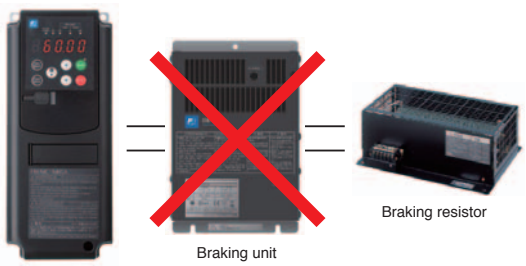
Comes with new auto-tuning features that enable multi-drive operation using our induction and synchronous motors as well as those of other companies.

* The G2 Series can replace conventional FRENIC-MEGA_GX1S Series products (synchronous motor drive types only).

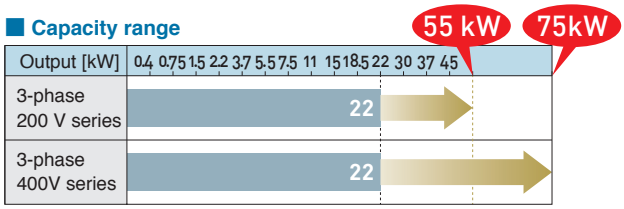
07 Expands the capacity of the built-in braking transistor type Enhancement

HIGH BASIC PERFORMANCE

Comes standard with a larger capacity range and contributes to control panel space and cost savings.



■ Capacity range



Features

Various applications

Comes with feature-rich functionality and enhances compatibility with system networks.

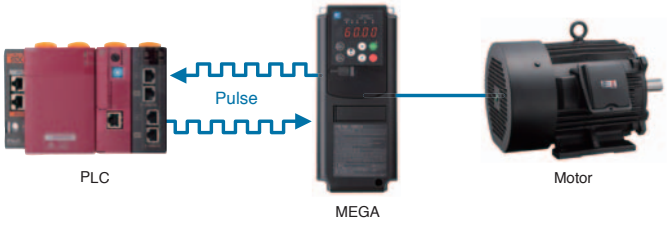
01 Positioning function NEW

VARIOUS APPLICATIONS

Contributes to shortening machine tact time through high-precision positioning control for pulse string input and feedback output instructions.

Main features

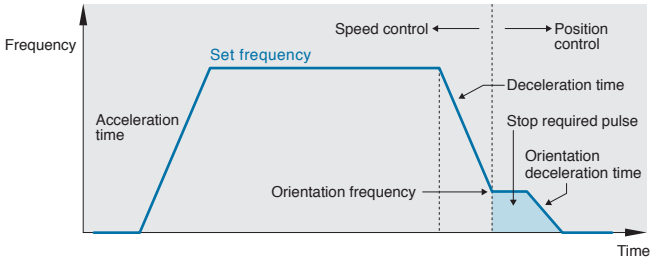
- Eight positioning data points
- Pulse train instruction
- Origin return function
- Overtravel detection function
- Position preset function



02 Orientation function NEW

VARIOUS APPLICATIONS

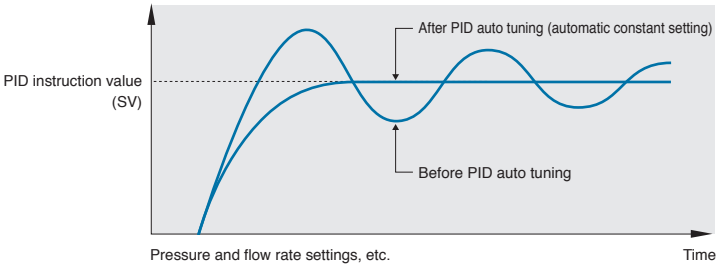
Capable of rotator positioning, enabling machinery to be held in place via servo locking after stoppage.



03 PID auto tuning function NEW

VARIOUS APPLICATIONS

Simplifies optimization via automatic adjustment of proportional and integral gains, resulting in shorter system start-up times, etc.



04 Load limiter NEW

VARIOUS APPLICATIONS

Improves system reliability by stopping when excessive torque is detected and by allowing operation only in the direction opposite to that in which the excessive load was detected.

05 Load adaptive control NEW

VARIOUS APPLICATIONS

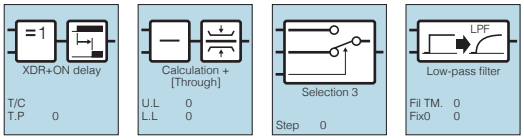
When the actual load level is lower than the configured load level, the system can be operated at a ratio-multiplied frequency, resulting in significantly better efficiency.

06 Customizable logic functions Enhancement

VARIOUS APPLICATIONS

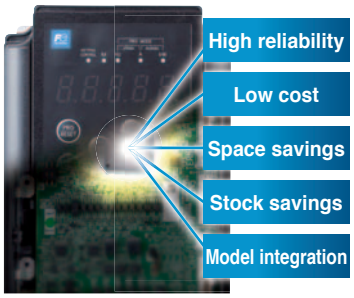
Customizable inverter functions to meet your own specific needs.
Requires no PLC or external control equipment (relays, timers, etc.) circuits, and can be configured simply by setting and combining various parameters inside the inverter.

Comes with a wide variety of logic symbols and programming steps

Item	FRENIC-MEGA
Logic symbol type (Logical operations, counters, timers, arithmetic operations, comparators, limiters, selectors, holders, etc.)	Total of 55 digital & analog types  Digital operations / Analog operations / Selector / Filter
Number of programming steps	260 steps

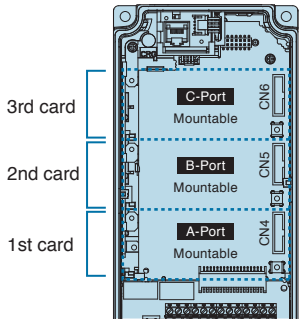
* The programming tool software can be downloaded for free from our website.

Advantages



07 Supports a variety of networks Option cards

VARIOUS APPLICATIONS



Insert the option card into the connector inside the main unit.
Up to three cards can be inserted.

Optional communication card types

1. DeviceNet
2. CC-Link
3. T-Link
4. PROFIBUS-DP
5. CANopen
6. SX bus
7. Ethernet (EtherNet/IP, PROFINET RT)

Coming soon (Modbus-TCP, BACnet/IP, and EtherCAT)

Note) There are some limitations to how option cards can be combined. Please contact us for details.

* For other types of option cards, please refer to page 70.

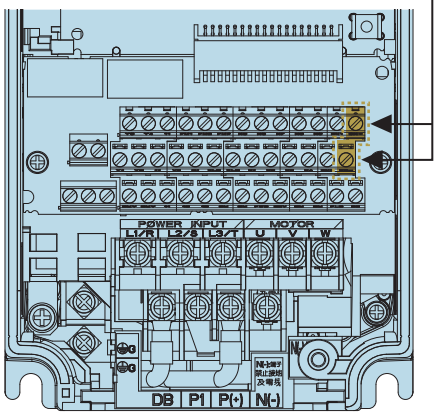
08 Enhanced network functions

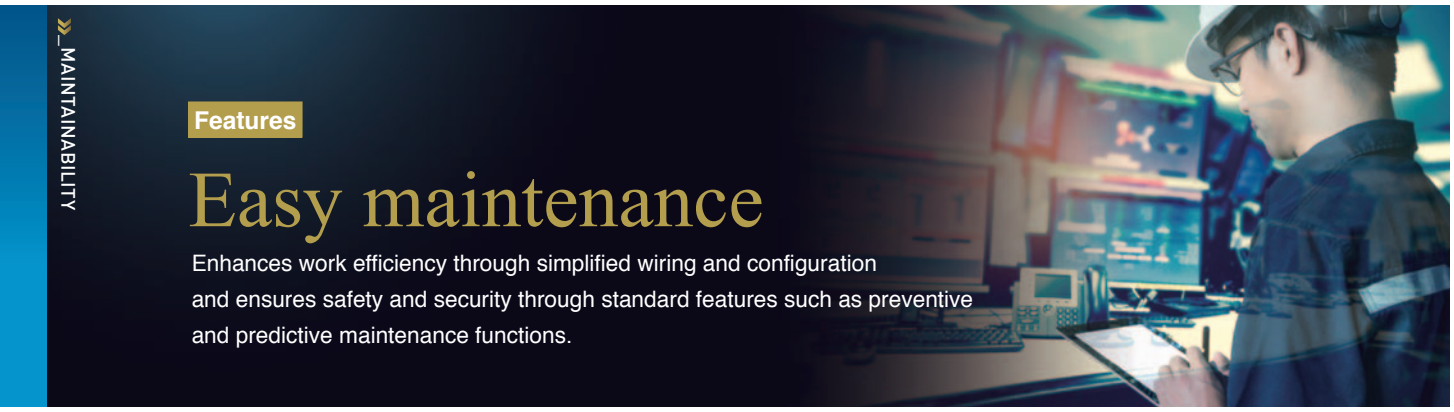
VARIOUS APPLICATIONS

Compatible with RS-485 communication (terminal block)

Comes standard with an RS-485 terminal in addition to a port (RJ-45 connector) that is shared with the keypad.
Simplifies multi-drop connections via terminal connection.

Supports RS-485 terminal multi-drop connection





Features

Easy maintenance

Enhances work efficiency through simplified wiring and configuration and ensures safety and security through standard features such as preventive and predictive maintenance functions.

01 Same mounting dimensions

MAINTAINABILITY

The appearance and mounting dimensions of the inverter are fully compatible.
The 3D position and size of the main circuit screw terminals are also the same.

* Can be installed as a replacement for conventional FRENIC-MEGA_G1 series products.

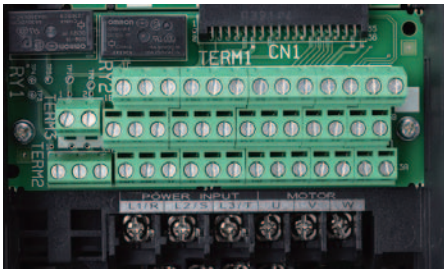
02 Simple wiring NEW

MAINTAINABILITY

The control terminal block uses an industry-standard rod-shaped block (44-pole, ⊖ screw) and improves workability of wiring.

Supports replacement or mounting of conventional FRENIC-MEGA_G1 Series' round terminal blocks (35-pole ⊕ screw).

Rod-shaped terminal block 44 poles



03 Easy parameter migration

MAINTAINABILITY

Compatibility mode allows parameters read from the previous model to be written directly to the G2 Series.

* The previous models include FRENIC-MEGA_G1 and FRENIC-MEGA_GX1 series products.
* The standard conventional touch panel (TP-E1U) is compatible with the PC loader, and the new keypad (TP-E2 and TP-A2SW) can be used to copy data. Please note that the newly added function codes will not be changed.

04 Designed with new operation keypad NEW

MAINTAINABILITY

Comes standard with a 7-segment 5-digit LED display whose large screen is very intuitive and enhances maintainability via improved key button operability and cursor digit control.

Standard Option

Additional features

Character display

·7-segment, 5-digit LED display.

"M/Shift" key

·The cursor can be moved to any position.
·Can assign the same signals as the digital input terminal (X terminal).
·Can fix the assigned signal to ON by pressing and holding the key.

"M" LED display

·Can use LEDs to monitor the digital output signals of inverters.
·Y-terminal signals can be assigned to enable checking without using a conventional loader or keypad.

Multi-function Option

Additional features

Character display

·Equipped with a highly visible LCD.
·Supports a total of 19 languages, including Japanese hiragana, katakana and kanji.

0:Japanese	1:English	2:German	3:French	4:Spanish
5:Italian	6:Chinese	8:Russian	9:Greek	10:Turkish
11:Polish	12:Czech	13:Swedish	14:Portuguese	15:Dutch
16:Malay	17:Vietnamese	18:Thai	19:Indonesian	

USB port

·Mounts to both standard keypad and multifunctional keypad.
·Can be directly connected to a PC with a commercially available USB cable (mini B).

Clock function

·Time data can be added to the alarm history.
* Battery (CR2032 type) not included.

SD card slot

·Can store traceback data on micro SD card.
* SD card not included.

Water resistant

·The front surface and sides are IP55 protected. * The back side is IP20 protected.

Built-in Bluetooth

·Parameter changes and maintenance can be performed remotely using a mobile device.
* Radio law certified countries: Japan, Europe, North America, China, Thailand

05 Enhances alarm history and traceback functions NEW

MAINTAINABILITY

- Capable of displaying and storing data for the past four occurrences, such as data for output voltage and output frequency at the times of alarms.
  * Occurrence time data can also be acquired when using the multi-function keypad. But need a battery.
- Capable of acquiring and saving waveform data immediately before an alarm occurs.

Number of saves

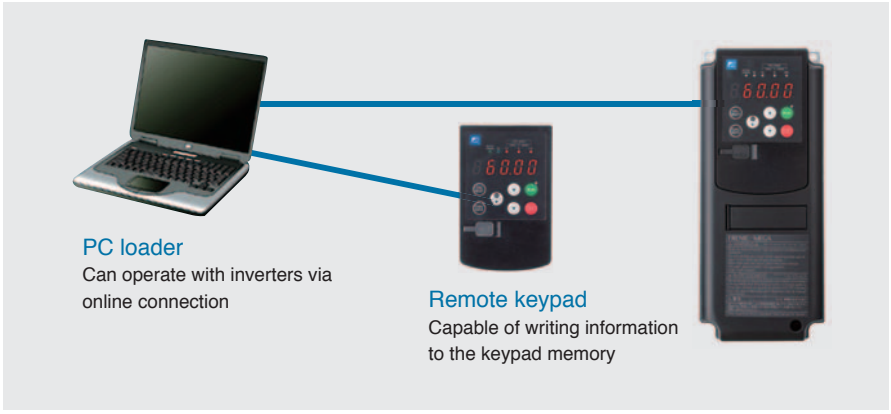
	No.
Standard keypad (TP-E2)	1
Multifunctional keypad (TP-A2SW)	100 * SD card

* The numbers above indicate the number of tracebacks.

06 Enhanced PC loader functions

MAINTAINABILITY

- The PC loader can be used by directly connecting the keypad to a PC using a commercially available USB cable (mini B).
- It makes it easy to store or check various types of information at the office, or send information and check abnormalities at



PC loader
Can operate with inverters via online connection

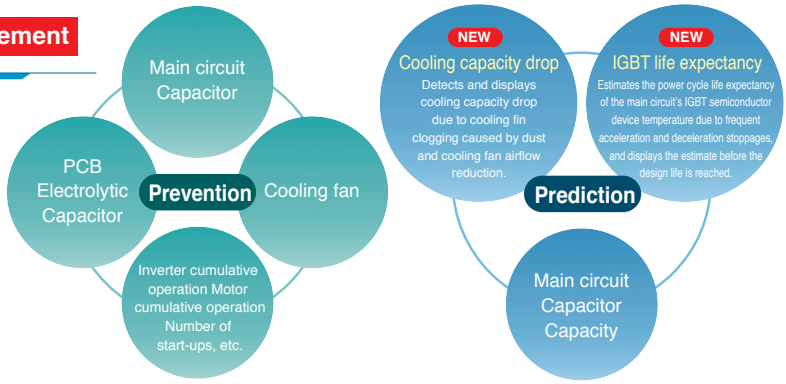
Remote keypad
Capable of writing information to the keypad memory

Usage examples

07 Life expectancy diagnosis and maintenance functions Enhancement

MAINTAINABILITY

The keypad and PC loader make it easy to check the status of equipment and detect problems before they occur, helping to reduce production equipment maintenance time and downtime.



08 Long life expectancy (main components)

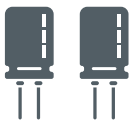
MAINTAINABILITY

Many of the serviceable parts inside the inverter have been designed to meet customer equipment maintenance cycles.

* The above values refer to the design life (calculated values) and are not guaranteed values.

Main circuit capacitor

PCB Electrolytic capacitor



Cooling fan

Life expectancy conditions	Ambient temperature 40°C, load factor 100% (HHD specification), 80% (HND specification)

Features

Environmentally resistant

Globally compliant lineup compatible with adverse atmospheres and various safety standards.

01 Improves environmental resistance Enhancement

ENVIRONMENTAL RESISTANCE

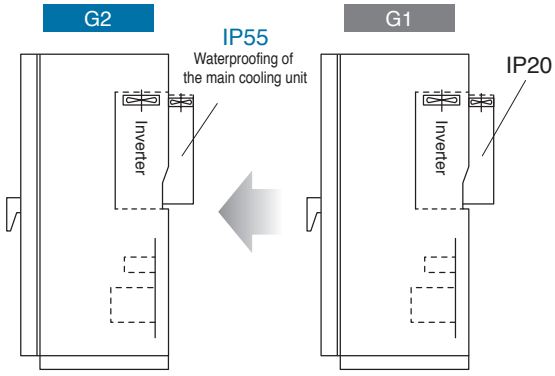
(1) Uses copper bars with Ni and Sn plating

(2) Ambient operating temperature up to +55°C
* Derating is required when used at 50°C or higher.

(3) Further strengthens PCB coating
(JIS C 60721-3-3/IEC 60721-3-3 Class 3C2)
* Products also available with enhanced salt-resistance and made-to-order specifications.

(4) IP55 protection for the inverter's main cooling unit contributes to enhanced cooling outside the panel, lower costs, and downsizing.

Note) If you are using or considering using the product under the following conditions, please contact our sales department.
a. Environments containing sulfurized gas (e.g., some applications in the tire manufacturing, paper manufacturing, sewage treatment, textile industries, etc.)
b. Environments containing conductive dust and foreign objects (e.g., metal processing machines, extruders, printing machines, waste disposal machinery, etc.)
c. When using the product in non-standard environments

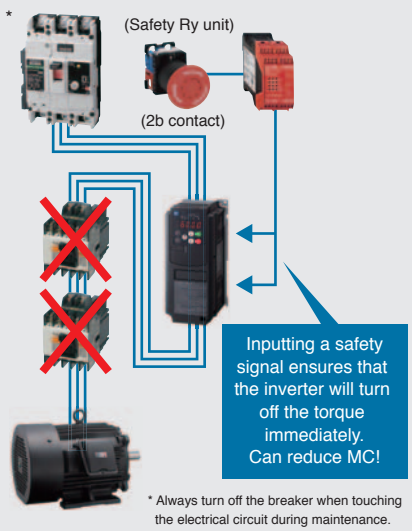


* Supports only 30 kW to 630 kW

02 Includes safety functions NEW

ENVIRONMENTAL RESISTANCE

- Compliant with European safety standards.
  (EN ISO 13849-1:2015, Cat3/PL:e IEC/EN61800-5-2:2016 SIL3 (STO))
- The inverter comes with a function that enables it to adapt to machine safety. This facilitates the design of main circuit switching devices for ensuring safe stoppages.



* Always turn off the breaker when touching the electrical circuit during maintenance.

03 Compliant with the revised European RoHS Directive

ENVIRONMENTAL RESISTANCE

Ten environmental impact substances

RoHS 2019

Lead, mercury, cadmium, and hexavalent chromium
Polybrominated biphenyl (PBB)
Polybrominated diphenyl ether (PBDE)
Di-2-ethylhexyl phthalate (DEHP)
Butyl benzyl phthalate (BBP)
Di-n-butyl phthalate (DBP)
Diisobutyl phthalate (DIBP)

04 Globally compliant

ENVIRONMENTAL RESISTANCE

Compliant with overseas safety standards.

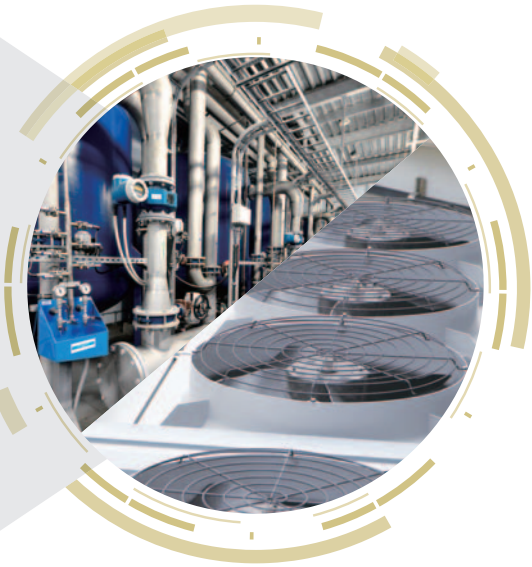
European regions	United States/ Canada
EC directive (CE marking)	UL standard/cUL standard
CE	c UL us LISTED

Main application examples

Expansion of Mega Series app

Fans and pumps

Others Blowers, turbo chillers, etc.



»PID control
Auto tuning function

Ensures smooth equipment startup and optimal operation adjustment through automatic PID parameter adjustment.

»Automatic energy-saving operation mode

Minimizes inverter and motor loss through automatic operation, helping to achieve equipment energy savings.

»Multi drive
New auto tuning function

Enables multi-drive operation with a single inverter through induction and synchronous motor tuning.

Compressors

Others Machine tools, gear pumps, etc.

»Sensorless vector control
Synchronous motors

Capable of driving synchronous motors up to 599 Hz, helping to achieve equipment downsizing and energy savings.

Machine tools

Others Compressors, automobile testing instruments, etc.

»Position control
Orientation functions

Enables operation and rotator stopping angle specification using tool changer positioning, allowing stopped machinery to be held in place via servo locking.

»Speed responsiveness
Vector control

Reduces the effects of rotation irregularities and interference on machines through improved responsiveness (with sensor: 200 Hz; without sensor: 40 Hz).

»High-speed operation

Expands the output frequency range to 599 Hz for all control methods and shortens machining times through high-speed rotation.

lications

Supports a wide variety of applications and is useful in various situations.

Press machines

Others Forging press machines, hoisting and transporting, etc.

»High-speed responsiveness

Speed and current response | Vector control

Stabilizes quality by ensuring a constant rotational speed during load fluctuations through improved speed and current responsiveness.

»Regeneration avoidance function

Stabilizes operations by suppressing load fluctuation overvoltage alarms even in regenerative mode.

»Built-in braking transistor

Saves space and reduces cost of electric panels by expanding the capacity range (200 V series: 0.4 to 55 kW, 400 V series: 0.4 to 75 kW).

Winding machines

Others Printing machines, wrapping machines, etc.

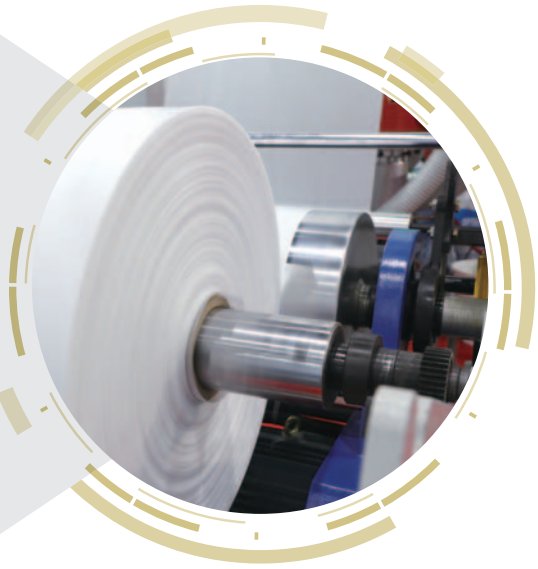
»High-speed responsiveness

Speed and current response | Vector control

Stabilizes quality by ensuring a constant rotational speed during load fluctuations through improved speed and current responsiveness.

»Stability at low speeds

Can control product quality variations even when the motor is running at low speed.



Hoists

Others Cranes and multistory warehouses, etc.

»Load adaptive control

Load adaptive control

When the actual load level is lower than the configured load level, the system can be operated at a ratio-multiplied speed (in terms of the configured frequency), resulting in significantly better efficiency.

»Load limiter

Load limiter

Maintains safety and rescuability of suspended loads by stopping when excessive torque is detected and by allowing operation only in the direction opposite to that in which the excessive load was detected.

»Vector control

Torque biasing function

Automatically incorporates the load portion into torque instructions to enable smooth start-up compensation during lifting and lowering.

Main application examples

Stacker cranes

Others Elevators, escalators, etc.

»Position control function

Enables high-precision positioning control and tact time reduction through use of pulse train instructions and operations, origin return, and position preset overtravel detection.

»Brake release signals

Outputs braking signals based on inverter operating conditions to prevent cargo bed rollback and overrunning.

»Motor constant switching

Enables multi-motor switchover operation for driving, lifting, and forking applications, and reduces costs by decreasing the number of inverters in use.

Multistory parking lots

Others Cranes, hoists, etc.

»Built-in braking transistor

Saves space and reduces cost of electric panels by expanding the capacity range (200 V series: 0.4 to 55 kW, 400 V series: 0.4 to 75 kW).

»Dynamic torque vector control

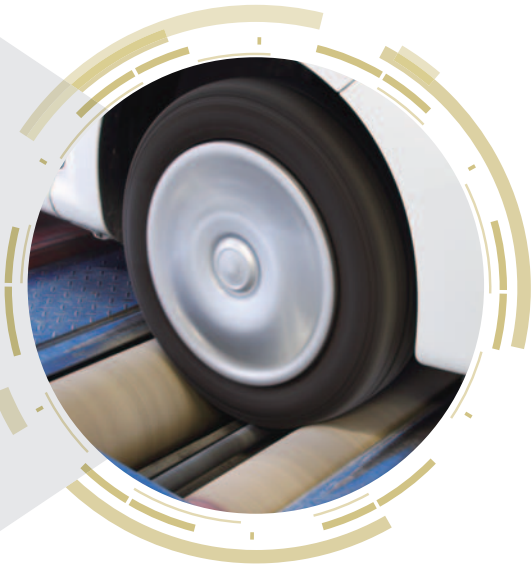
Enables smooth startup by outputting powerful torque even at low speeds.

»Brake release signals

Outputs braking signals based on inverter operating conditions to prevent vehicle rollback and overrunning.

Automotive testing equipment

Others Machine tools, press machines, etc.



»Torque control Sensor-equipped vector control

Supports configuration of test equipment for simulating loads using torque control.

»High-speed responsiveness Speed and current response Vector control

Enables quantification of testing by ensuring a constant rotational speed during load fluctuations through improved speed and current responsiveness.

»Speed control range Sensor-equipped vector control

Enables high-speed motor driving rotation testing through expansion of the constant output range (1:16).

Crushing machines

»Dynamic torque vector control

Enables powerful operation even during sudden load changes and low-speed rotation.

»Life expectancy forecasting

Monitors inverter current and temperature rise to predict and detect inverter tripping and failure. Prevents equipment stoppages and reduces downtime.

»Customizable logic functions

Enables creation of customized programs (such as a program for recovering from stoppages due to jamming) by combining a wide variety of digital and analog operation blocks.

Plant related

1 Rolling mills

»High-speed responsiveness Speed and current response Vector control

Enables high-precision roller operation by ensuring a constant rotational speed during load fluctuations through improved speed and current responsiveness.

»Load inertia estimation

Estimates the theoretical acceleration and deceleration time based on the load inertia, enabling users to make optimal settings.

2 Kilns

»Multi-pole motor operation

Can operate motors with up to 128 poles and supports rated frequencies as low as 5 Hz.

»Life expectancy forecasting

Monitors inverter current and temperature rise to predict and detect inverter tripping and failure. Prevents device and equipment stoppages and reduces downtime.

Model Variations

Model list

HHD spec (High carrier frequency Heavy Duty) : 200%-3s, 150%-1min
HND spec (High carrier frequency Normal Duty) : 120%-1min

Standard applied motor [kW (HP)]	Basic type				EMC filter built-in type	
	3-phase 400 V series		3-phase 200 V series		3-phase 400 V series	
	HHD spec	HND spec	HHD spec	HND spec	HHD spec	HND spec
0.4 (1/2)	FRN0002G2S-4G		FRN0003G2S-2G		FRN0002G2E-4G	
0.75 (1)	FRN0003G2S-4G		FRN0005G2S-2G		FRN0003G2E-4G	
1.5 (2)	FRN0004G2S-4G		FRN0008G2S-2G		FRN0004G2E-4G	
2.2 (3)	FRN0006G2S-4G		FRN0011G2S-2G		FRN0006G2E-4G	
3.7 (5)	FRN0009G2S-4G		FRN0018G2S-2G		FRN0009G2E-4G	
5.5 (7.5)	FRN0018G2S-4G		FRN0032G2S-2G		FRN0018G2E-4G	
7.5 (10)	FRN0023G2S-4G	FRN0018G2S-4G	FRN0046G2S-2G	FRN0032G2S-2G	FRN0023G2E-4G	FRN0018G2E-4G
11 (15)	FRN0031G2S-4G	FRN0023G2S-4G	FRN0059G2S-2G	FRN0046G2S-2G	FRN0031G2E-4G	FRN0023G2E-4G
15 (20)	FRN0038G2S-4G	FRN0031G2S-4G	FRN0075G2S-2G	FRN0059G2S-2G	FRN0038G2E-4G	FRN0031G2E-4G
18.5 (25)	FRN0045G2S-4G	FRN0038G2S-4G	FRN0088G2S-2G	FRN0075G2S-2G	FRN0045G2E-4G	FRN0038G2E-4G
22 (30)	FRN0060G2S-4G	FRN0045G2S-4G	FRN0115G2S-2G	FRN0088G2S-2G	FRN0060G2E-4G	FRN0045G2E-4G
30 (40)	FRN0075G2S-4G	FRN0060G2S-4G	FRN0146G2S-2G	FRN0115G2S-2G	FRN0075G2E-4G	FRN0060G2E-4G
37 (50)	FRN0091G2S-4G	FRN00750G2S-4G	FRN0180G2S-2G	FRN0146G2S-2G	FRN0091G2E-4G	FRN0075G2E-4G
45 (60)	FRN0112G2S-4G	FRN0091G2S-4G	FRN0215G2S-2G	FRN0180G1S-2G	FRN0112G2E-4G	FRN0091G2E-4G
55 (75)	FRN0150G2S-4G	FRN0112G2S-4G	FRN0288G2S-2G	FRN0215G2S-2G	FRN0150G2E-4G	FRN0112G2E-4G
75 (100)	FRN0180G2S-4G	FRN0150G2S-4G	FRN0346G2S-2G	FRN0288G2S-2G	FRN0180G2E-4G	FRN0150G2E-4G
90 (125)	FRN0216G2S-4G	FRN0180G2S-4G	FRN0432G2S-2G	FRN0346G2S-2G	FRN0216G2E-4G	FRN0180G2E-4G
110 (150)	FRN0260G2S-4G	FRN0216G2S-4G		FRN0432G2S-2G	FRN0260G2E-4G	FRN0216G2E-4G
132 (200)	FRN0325G2S-4G	FRN0260G2S-4G			FRN0325G2E-4G	FRN0260G2E-4G
160 (250)	FRN0377G2S-4G	FRN0325G2S-4G			FRN0377G2E-4G	FRN0325G2E-4G
200 (300)	FRN0432G2S-4G	FRN0377G2S-4G			FRN0432G2E-4G	FRN0377G2E-4G
220 (350)	FRN0520G2S-4G	FRN0432G2S-4G			FRN0520G2E-4G	FRN0432G2E-4G
280 (400)	FRN0650G2S-4G	FRN0520G2S-4G			FRN0650G2E-4G	FRN0520G2E-4G
315 (450)	FRN0740G2S-4G				FRN0740G2E-4G	
355 (500)	FRN0960G2S-4G	FRN0650G2S-4G			FRN0960G2E-4G	FRN0650G2E-4G
400 (600)	FRN1040G2S-4G	FRN0740G2S-4G			FRN1040G2E-4G	FRN0740G2E-4G
500 (700)	FRN1170G2S-4G	FRN0960G2S-4G			FRN1170G2E-4G	FRN0960G2E-4G
560 (800)		FRN1040G2S-4G				FRN1040G2E-4G
630 (900)	FRN1386G2S-4G	FRN1170G2S-4G			FRN1386G2E-4G	FRN1170G2E-4G
710 (1000)		FRN1386G2S-4G				FRN1386G2E-4G

How to read the inverter modelerter model

FRN 0003 G 2 S - 4 G

Code	Series name
FRN	FRENIC series

Code	Applicable motor rating
0002	0.4kW (1/2HP)
I	I
1386	630kW (900HP),710kW (1000HP)

Code	Applicable range
G	High performance, multifunctional type

Code	Destination
G	Global

Code	Input power source
4	3-phase 400V
2	3-phase 200V

Code	Enclosure
S	Standard (basic type)
E	EMC filter built-in type

Code	Order of development
2	Series

Standard Specifications

Basic type | **Three-phase** | **400V series**

HHD (High carrier frequency Heavy Duty) spec for heavy load — 0.4 to 45kW

Item			Specifications													
Type (FRN□□□□G2S-4G)			0002	0003	0004	0006	0009	0018	0023	0031	0038	0045	0060	0075	0091	0112
Nominal applied motor [kW (HP)] (*1)			0.4 (1/2)	0.75 (1)	1.5 (2)	2.2 (3)	3.7 (5)	5.5 (7.5)	7.5 (10)	11 (15)	15 (20)	18.5 (25)	22 (30)	30 (40)	37 (50)	45 (60)
Output ratings	Rated capacity [kVA] (*2)		1.1	1.9	3.2	4.5	6.8	10	14	18	24	29	34	45	57	69
	Rated voltage [V] (*3)		Three-phase 380 to 480 (with AVR function)													
	Rated current [A]		1.5	2.5	4.2	6.0	9.0	13.5	18.5	24.5	32	39	45	60	75	91
	Overload capacity		150%-1min, 200%-3.0s													
	Rated frequency [Hz]		50, 60													
Input ratings	Main circuit power: Phases, voltage, frequency		Three-phase 380 to 480V, 50/60Hz													
	Auxiliary control power input: Phases, voltage, frequency		–		Single-phase 380 to 480V, 50/60Hz											
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less (*4)) Frequency:+5 to -5%													
	Rated current [A] (*5)	with DCR	0.85	1.6	3.0	4.5	7.5	10.6	14.4	21.1	28.8	35.5	42.2	57.0	68.5	83.2
		without DCR	1.7	3.1	5.9	8.2	13.0	17.3	23.2	33.0	43.8	52.3	60.6	77.9	94.3	114
	Required power supply capacity [kVA] (*6)	with DCR	0.6	1.2	2.1	3.2	5.2	7.4	10	15	20	25	30	40	48	58
Braking	Torque [%] (*7)		150		100					20				10 to 15		
	Braking transistor		Built-in as standard													
	Min. ohmic value [Ω]		200		160		96	64	48	32	24	16		10	9.0	8.0
	Built-in braking resistance [Ω]		720	470	160			80		Option						
		Braking time[s]	5							–						
		%ED	5	3	5	3	2	3	2	–						
	DC injection braking		Starting frequency:0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level:0 to 100%													
DC reactor (DCR)			Option													
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1													
Enclosure (IEC60529)			IP20 (IEC60529) closed type, UL open type (UL 50)										IP00 open type, UL open type IP55 at external side when external cooling installed			
Cooling method			Natural cooling			Fan cooling										
Weight/Mass [kg (lb)]			1.7 (3.8)	2.0 (4.4)	2.6 (5.7)	2.9 (6.4)	3.0 (6.6)	5.9 (13)	6.0 (13)	5.7 (13)	10 (22)	11 (24)	11 (24)	25 (55)	25 (55)	28 (62)

HHD (High carrier frequency Heavy Duty) spec for heavy load — 55 to 630kW

Item			Specifications												
Type (FRN□□□□G2S-4G)			0150	0180	0216	0260	0325	0377	0432	0520	0650	0740	0960	1040	1170	1386
Nominal applied motor [kW (HP)] (*1)			55 (75)	75 (100)	90 (125)	110 (150)	132 (200)	160 (250)	200 (300)	220 (350)	280 (400)	315 (450)	355 (500)	400 (600)	500 (700)	630 (900)
Output ratings	Rated capacity [kVA] (*2)		85	114	137	164	198	247	287	329	396	445	495	563	731	891
	Rated voltage [V] (*3)		Three-phase 380 to 480 (with AVR function)													
	Rated current [A]		112	150	180	216	260	325	377	432	520	585	650	740	960	1170
	Overload capacity		150%-1min, 200%-3.0s													
	Rated frequency [Hz]		50, 60													
Input ratings	Main circuit power: Phases, voltage, frequency		Three-phase 380 to 480V, 50/60Hz													
	Auxiliary control power input: Phases, voltage, frequency		Single-phase 380 to 480V, 50/60Hz													
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less (*4)) Frequency:+5 to -5%													
	Rated current [A] (*5)	with DCR	102	138	164	201	238	286	357	390	500	559	628	705	881	1115
		without DCR	140	–	–	–	–	–	–	–	–	–	–	–	–	–
	Required power supply capacity [kVA] (*6)	with DCR	71	96	114	140	165	199	248	271	347	388	436	489	611	773
Braking	Torque [%] (*7)		10 to 15													
	Braking transistor		Built-in as standard	Option												
	Min. ohmic value [Ω]		6.5	4.7	–											
	Built-in braking resistance [Ω]		Option													
		Braking time[s]	–													
		%ED	–													
	DC injection braking		Starting frequency:0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level:0 to 100%													
DC reactor (DCR)			Option	Option (*8)												
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1													
Enclosure (IEC60529)			IP00 open type, UL open type IP55 at external side when external cooling installed													
Cooling method			Fan cooling													
Weight/Mass [kg (lb)]			31 (68)	38 (84)	60 (132)	60 (132)	89 (196)	89 (196)	116 (256)	124 (273)	221 (487)	221 (487)	291 (642)	295 (650)	450 (992)	450 (992)

(*1) Fuji's 4-pole standard motor When selecting an inverter, in addition to considering the kWs of the inverter, make sure that the output current rating is larger than the motor current rating.
(*2) Rated capacity is calculated by assuming the rated output voltage as 220 V for 200 V series and 440 V for 400 V series.
(*3) Output voltage cannot exceed the power supply voltage.
(*4) Voltage unbalance(%) =Max. voltage (V) - Min. voltage (V) / Three-phase average voltage (V) ×67 (IEC 61800-3)
If this value is 2 to 3%, use an optional AC reactor (ACR).
(*5) These values are calculated on assumption that the inverter is connected to a power supply with a capacity of 500 kVA (or 10 times the inverter capacity when the inverter capacity exceeds 50 kVA) and %X is 5%.
(*6) Required when a DC reactor (DCR) is used.
(*7) This is the average braking torque when performing individual operation. (This will vary based on the motor efficiency.)
(*8) When using a motor with a rating of 75 kW or more, be sure to use a DC reactor (option).

Standard Specifications

Basic type | **Three-phase** | **400V series**

HND (High carrier frequency Normal Duty)

7.5 to 110kW

Item			Specifications										
Type (FRN□□□□G2S-4G)			0018	0023	0031	0038	0045	0060	0075	0091	0112	0150	0180	0216
Nominal applied motor [kW (HP)] (*1)			7.5 (10)	11 (15)	15 (20)	18.5 (25)	22 (30)	30 (40)	37 (50)	45 (60)	55 (75)	75 (100)	90 (125)	110 (150)
Output ratings	Rated capacity [kVA] (*2)		13	17	23	28	34	45	57	69	85	114	137	164
	Rated voltage [V] (*3)		Three-phase 380 to 480 (with AVR function)											
	Rated current [A]		17.5	23	31	38	45	60	75	91	112	150	180	216
	Overload capacity		120%-1min, 200%-3.0s											
	Rated frequency [Hz]		50, 60											
Input ratings	Main circuit power: Phases, voltage, frequency		Three-phase 380 to 480V, 50/60Hz											
	Auxiliary control power input: Phases, voltage, frequency		Single-phase 380 to 480V, 50/60Hz											
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less (*4)) Frequency:+5 to -5%											
	Rated current [A] (*5)	with DCR	14.4	21.1	28.8	35.5	42.2	57.0	68.5	83.2	102	138	164	201
		without DCR	23.2	33.0	43.8	52.3	60.6	77.9	94.3	114	140	—	—	—
	Required power supply capacity [kVA] (*6)	with DCR	10	15	20	25	30	40	48	58	71	96	114	140
Braking	Torque [%] (*7)		70		15				7 to 12					
	Braking transistor		Built-in as standard											—
	Min. ohmic value [Ω]		64	48	32	24	16		10	9.0	8.0	6.5	4.7	—
	Built-in braking resistance [Ω]		80		Option									
		Braking time[s]	3.7	3.4	—									
		%ED	2.2	1.4	—									
	DC injection braking		Starting frequency:0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level: 0 to 80%											
DC reactor (DCR)			Option									Option (*8)		
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1											
Enclosure (IEC60529)			IP20 (IEC60529) closed type, UL open type (UL 50)						IP00 open type, UL open type IP55 at external side when external cooling installed					
Cooling method			Fan cooling											
Weight/Mass [kg (lb)]			5.9 (13)	6.0 (13)	5.7 (13)	10 (22)	11 (24)	11 (24)	25 (55)	25 (55)	28 (62)	31 (68)	38 (84)	60 (132)

HND (High carrier frequency Normal Duty)

132 to 710kW

Item			Specifications										
Type (FRN□□□□G2S-4G)			0260	0325	0377	0432	0520	0650	0740	0960	1040	1170	1386
Nominal applied motor [kW (HP)] (*1)			132 (200)	160 (250)	200 (300)	220 (350)	280 (400)	355 (450)	400 (500)	500 (700)	560 (800)	630 (900)	710 (1000)
Output ratings	Rated capacity [kVA] (*2)		198	247	287	329	396	495	563	731	792	891	1056
	Rated voltage [V] (*3)		Three-phase 380 to 480 (with AVR function)										
	Rated current [A]		260	325	377	432	520	650	740	960	1040	1170	1386
	Overload capacity		120%-1min										
	Rated frequency [Hz]		50, 60										
Input ratings	Main circuit power: Phases, voltage, frequency		3hree-phase 380 to 480V, 50/60Hz										
	Auxiliary control power input: Phases, voltage, frequency		Single-phase 380 to 480V, 50/60Hz										
	Voltage, frequency variations		Voltage: (10 to -15% (Voltage unbalance: 2% or less (*4)) Frequency: +5 to -5%										
	Rated current [A] (*5)	with DCR	238	286	357	390	500	628	705	881	990	1115	1256
		without DCR	—	—	—	—	—	—	—	—	—	—	—
	Required power supply capacity [kVA] (*6)	with DCR	165	199	248	271	347	436	489	611	686	773	871
Braking	Torque [%] (*7)		7 to 12										
	Braking transistor		Option										
	Min. ohmic value [Ω]		—										
	Built-in braking resistance [Ω]		Option										
		Braking time[s]	—										
		%ED	—										
	DC injection braking		Starting frequency: 0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level: 0 to 80%										
DC reactor (DCR)			Option(*8)										
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1										
Enclosure (IEC60529)			IP00 open type, UL open type IP55 at external side when external cooling installed										
Cooling method			Fan cooling										
Weight/Mass [kg (lb)]			60 (132)	89 (196)	89 (196)	116 (256)	124 (273)	221 (487)	221 (487)	291 (642)	295 (650)	450 (992)	450 (992)

(*1) Fuji's 4-pole standard motor When selecting an inverter, in addition to considering the kWs of the inverter, make sure that the output current rating is larger than the motor current rating.
(*2) Rated capacity is calculated by assuming the rated output voltage as 220 V for 200 V series and 440 V for 400 V series.
(*3) Output voltage cannot exceed the power supply voltage.
(*4) Voltage unbalance(%) =Max. voltage (V) - Min. voltage (V) / Three-phase average voltage (V) ×67 (IEC 61800-3)
If this value is 2 to 3%, use an optional AC reactor (ACR).
(*5) These values are calculated on assumption that the inverter is connected to a power supply with a capacity of 500 kVA (or 10 times the inverter capacity when the inverter capacity exceeds 50 kVA) and %X is 5%.
(*6) Required when a DC reactor (DCR) is used.
(*7) This is the average braking torque when performing individual operation. (This will vary based on the motor efficiency.)
(*8) When using a motor with a rating of 75 kW or more, be sure to use a DC reactor (option).

Basic type | Three-phase | 200V series

HHD (High carrier frequency Heavy Duty) spec for heavy load

Item			Specifications															
Type (FRN□□□□G2S-2G)			0003	0005	0008	0011	0018	0032	0046	0059	0075	0088	0115	0146	0180	0215	0288	0346	0432
Nominal applied motor [kW (HP)] (*1)			0.4 (1/2)	0.75 (1)	1.5 (2)	2.2 (3)	3.7 (5)	5.5 (7.5)	7.5 (10)	11 (15)	15 (20)	18.5 (25)	22 (30)	30 (40)	37 (50)	45 (60)	55 (75)	75 (100)	90 (125)
Output ratings	Rated capacity [kVA] (*2)		1.1	1.9	3.0	4.1	6.8	10	14	18	24	28	34	45	55	68	81	109	131
	Rated voltage [V] (*3)		Three-phase 200 to 240 (with AVR function)											Three-phase 200 to 230 (with AVR function)					
	Rated current [A]		3	5	8	11	18	27	37	49	63	76	90	119	146	180	215	288	346
	Overload capacity		150%-1min, 200%-3.0s																
	Rated frequency [Hz]		50, 60																
Input ratings	Main circuit power: Phases, voltage, frequency		Three-phase 200 to 240V, 50/60Hz											Three-phase 200 to 230V, 50/60Hz					
	Auxiliary control power input: Phases, voltage, frequency		—		Single-phase 200 to 240V, 50/60Hz									Single-phase 200 to 230V, 50/60Hz					
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less (*4)) Frequency:+5 to -5%																
	Rated current [A] (*5)	with DCR	1.6	3.2	6.1	8.9	15	21.1	28.8	42.2	57.6	71.0	84.4	114	138	167	203	282	334
		without DCR	3.1	5.3	9.5	13.2	22.2	31.5	42.7	60.7	80.1	97.0	112	151	185	225	270	—	—
	Required power supply capacity [kVA] (*6)	with DCR	0.6	1.2	2.2	3.1	5.2	7.4	10	15	20	25	30	40	48	58	71	98	116
Braking	Torque [%] (*7)		150			100				20				10 to 15					
	Braking transistor		Built-in as standard															Option	
	Min. ohmic value [Ω]		100		40		24	16	12	8.0	6.0	4.0		2.5	2.25	2.0	1.6	—	
	Built-in braking resistance [Ω]		100		40			20		Option									
		Braking time[s]	5							—									
		%ED	5	3	5	3	2	3	2	—									
	DC injection braking		Starting frequency:0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level:0 to 100%																
EMC filter			Complying EMC standard on emissions and immunity: Category C3 (2nd Env.) (IEC61800-3: 2017)																
DC reactor (DCR)			Option															Option (*8)	
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1																
Enclosure (IEC60529)			IP20 closed type, UL open type											IP00 open type, UL open type IP55 at external side when external cooling installed					
Cooling method			Natural cooling			Fan cooling													
Weight/Mass [kg (lb)]			1.7 (3.7)	1.9 (4.2)	2.6 (5.7)	2.9 (6.4)	2.9 (6.4)	5.8 (13)	6.2 (14)	5.7 (13)	11 (24)	11 (24)	12 (26)	25 (55)	31 (68)	40 (88)	42 (93)	60 (132)	97 (214)

HND (High carrier frequency Normal Duty) spec for light load

Item			Specifications										
Type (FRN□□□□G2S-2G)			0032	0046	0059	0075	0088	0115	0146	0180	0215	0288	0346	0432
Nominal applied motor [kW (HP)] (*1)			7.5 (10)	11 (15)	15 (20)	18.5 (25)	22 (30)	30 (40)	37 (50)	45 (60)	55 (75)	75 (100)	90 (125)	110 (150)
Output ratings	Rated capacity [kVA] (*2)		12	17	22	28	33	43	55	68	81	109	131	164
	Rated voltage [V] (*3)		Three-phase 200 to 240 (with AVR function)						Three-phase 200 to 230 (with AVR function)					
	Rated current [A]		31.8	46.2	59.4	74.8	88	115	146	180	215	288	346	432
	Overload capacity		120%-1min											
	Rated frequency [Hz]		50, 60											
Input ratings	Main circuit power: Phases, voltage, frequency		Three-phase 200 to 240V, 50/60Hz						Three-phase 200 to 230V, 50/60Hz					
	Auxiliary control power input: Phases, voltage, frequency		Single-phase 200 to 240V, 50/60Hz						Single-phase 200 to 230V, 50/60Hz					
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less) Frequency:+5 to -5%											
	Rated current [A] (*5)	with DCR	28.8	42.2	57.6	71.0	84.4	114	138	167	203	282	334	410
		without DCR	42.7	60.7	80.1	97.0	112	151	185	225	270	—	—	—
	Required power supply capacity [kVA] (*6)	with DCR	10	15	20	25	30	40	48	58	71	98	116	143
Braking	Torque [%] (*7)		70		15				7 to 12					
	Braking transistor		Built-in as standard										Option	
	Min. ohmic value [Ω]		16	12	8.0	6.0	4.0		2.5	2.25	2.0	1.6	—	
	Built-in braking resistance [Ω]		20		Option									
		Braking time[s]	3.7	3.4	—									
		%ED	2.2	1.4	—									
	DC injection braking		Starting frequency: 0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level: 0 to 80%											
EMC filter			Complying EMC standard on emissions and immunity: Category C3 (2nd Env.) (IEC61800-3: 2017)											
DC reactor (DCR)			Option									Option (*8)		
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1											
Enclosure (IEC60529)			IP20 closed type, UL open type						IP00 open type, UL open type IP55 at external side when external cooling installed					
Cooling method			Fan cooling											
Weight/Mass [kg (lb)]			5.8 (13)	6.2 (14)	5.7 (13)	11 (24)	11 (24)	12 (26)	25 (55)	31 (68)	40 (88)	42 (93)	60 (132)	97 (214)

(*1) Fuji's 4-pole standard motor When selecting an inverter, in addition to considering the kWs of the inverter, make sure that the output current rating is larger than the motor current rating.
(*2) Rated capacity is calculated by assuming the rated output voltage as 220 V for 200 V series and 440 V for 400 V series.
(*3) Output voltage cannot exceed the power supply voltage.
(*4) Voltage unbalance(%) =Max. voltage (V) - Min. voltage (V) / Three-phase average voltage (V) ×67 (IEC 61800-3)
If this value is 2 to 3%, use an optional AC reactor (ACR).
(*5) These values are calculated on assumption that the inverter is connected to a power supply with a capacity of 500 kVA (or 10 times the inverter capacity when the inverter capacity exceeds 50 kVA) and %X is 5%.
(*6) Required when a DC reactor (DCR) is used.
(*7) This is the average braking torque when performing individual operation. (This will vary based on the motor efficiency.)
(*8) When using a motor with a rating of 75 kW or more, be sure to use a DC reactor (option).

EMC filter built-in type Three-phase 400V series

HHD (High carrier frequency Heavy Duty) spec for heavy load 0.4 to 45kW

Item			Specifications												
Type (FRN□□□□G2E-4G)			0002	0003	0004	0006	0009	0018	0023	0031	0038	0045	0060	0075	0091	0112
Nominal applied motor [kW (HP)] (*1)			0.4 (1/2)	0.75 (1)	1.5 (2)	2.2 (3)	3.7 (5)	5.5 (7.5)	7.5 (10)	11 (15)	15 (20)	18.5 (25)	22 (30)	30 (40)	37 (50)	45 (60)
Output ratings	Rated capacity [kVA] (*2)		1.1	1.9	3.2	4.5	6.8	10	14	18	24	29	34	45	57	69
	Rated voltage [V] (*3)		Three-phase 380 to 480 (with AVR function)													
	Rated current [A]		1.5	2.5	4.2	6.0	9.0	13.5	18.5	24.5	32	39	45	60	75	91
	Overload capacity		150%-1min, 200%-3.0s													
	Rated frequency [Hz]		50, 60													
Input ratings	Main circuit power: Phases, voltage, frequency		Three-phase 380 to 480V, 50/60Hz													
	Auxiliary control power input: Phases, voltage, frequency		—		Single-phase 380 to 480V, 50/60Hz											
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less (*4)) Frequency:+5 to -5%													
	Rated current [A] (*5)	with DCR	0.85	1.6	3.0	4.5	7.5	10.6	14.4	21.1	28.8	35.5	42.2	57.0	68.5	83.2
		without DCR	1.7	3.1	5.9	8.2	13.0	17.3	23.2	33	43.8	52.3	60.6	77.9	94.3	114
	Required power supply capacity [kVA] (*6)	with DCR	0.6	1.2	2.1	3.2	5.2	7.4	10	15	20	25	30	40	48	58
Braking	Torque [%] (*7)		150		100					20				10 to 15		
	Braking transistor		Built-in as standard													
	Min. ohmic value [Ω]		200		160		96	64	48	32	24	16		10	9.0	8.0
	Built-in braking resistance [Ω]		720	470	160			80		Option						
		Braking time[s]	5							—						
		%ED	5	3	5	3	2	3	2	—						
	DC injection braking		Starting frequency:0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level:0 to 100%													
EMC filter			Complying EMC standard on emissions and immunity: Category C3 (2nd Env.) (IEC61800-3: 2017)													
DC reactor (DCR)			Option													
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1													
Enclosure (IEC60529)			IP20 (IEC60529) closed type, UL open type (UL 50)										IP00 open type, UL open type IP55 at external side when external cooling installed			
Cooling method			Natural cooling			Fan cooling										
Weight/Mass [kg (lb)]			1.8 (4.0)	2.1 (4.6)	2.8 (6.2)	3.1 (6.8)	3.2 (7.1)	6.6 (15)	6.6 (15)	6.4 (14)	11 (24)	11 (24)	12 (26)	25 (55)	25 (55)	30 (66)

HHD (High carrier frequency Heavy Duty) spec for heavy load 55 to 630kW

Item			Specifications												
Type (FRN□□□□G2E-4G)			0150	0180	0216	0260	0325	0377	0432	0520	0650	0740	0960	1040	1170	1386
Nominal applied motor [kW (HP)] (*1)			55 (75)	75 (100)	90 (125)	110 (150)	132 (200)	160 (250)	200 (300)	220 (350)	280 (400)	315 (450)	355 (500)	400 (600)	500 (700)	630 (900)
Output ratings	Rated capacity [kVA] (*2)		85	114	137	164	198	247	287	329	396	445	495	563	731	891
	Rated voltage [V] (*3)		Three-phase 380 to 480 (with AVR function)													
	Rated current [A]		112	150	180	216	260	325	377	432	520	585	650	740	960	1170
	Overload capacity		150%-1min, 200%-3.0s													
	Rated frequency [Hz]		50, 60													
Input ratings	Main circuit power: Phases, voltage, frequency		3Three-phase 380 to 480V, 50/60Hz													
	Auxiliary control power input: Phases, voltage, frequency		Single-phase 380 to 480V, 50/60Hz													
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less (*4)) Frequency:+5 to -5%													
	Rated current [A] (*5)	with DCR	102	138	164	201	238	286	357	390	500	559	628	705	881	1115
		without DCR	140	—	—	—	—	—	—	—	—	—	—	—	—	—
	Required power supply capacity [kVA] (*6)	with DCR	71	96	114	140	165	199	248	271	347	388	436	489	611	773
Braking	Torque [%] (*7)		10 to 15													
	Braking transistor		Built-in as standard		Option											
	Min. ohmic value [Ω]		6.5	4.7	—											
	Built-in braking resistance [Ω]		Option													
		Braking time[s]	—													
		%ED	—													
	DC injection braking		Starting frequency:0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level:0 to 100%													
EMC filter			Complying EMC standard on emissions and immunity: Category C3 (2nd Env.) (IEC61800-3: 2017)													
DC reactor (DCR)			Option	Option (*8)												
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1													
Enclosure (IEC60529)			IP00 open type, UL open type IP55 at external side when external cooling installed													
Cooling method			Fan cooling													
Weight/Mass [kg (lb)]			31 (68)	38 (84)	60 (132)	60 (132)	89 (196)	89 (196)	116 (256)	124 (273)	221 (487)	221 (487)	291 (642)	295 (650)	450 (992)	450 (992)

(*1) Fuji's 4-pole standard motor When selecting an inverter, in addition to considering the kWs of the inverter, make sure that the output current rating is larger than the motor current rating.
(*2) Rated capacity is calculated by assuming the rated output voltage as 220 V for 200 V series and 440 V for 400 V series.
(*3) Output voltage cannot exceed the power supply voltage.
(*4) Voltage unbalance(%) =Max. voltage (V) - Min. voltage (V) / Three-phase average voltage (V) ×67 (IEC 61800-3)
If this value is 2 to 3%, use an optional AC reactor (ACR).
(*5) These values are calculated on assumption that the inverter is connected to a power supply with a capacity of 500 kVA (or 10 times the inverter capacity when the inverter capacity exceeds 50 kVA) and %X is 5%.
(*6) Required when a DC reactor (DCR) is used.
(*7) This is the average braking torque when performing individual operation. (This will vary based on the motor efficiency.)
(*8) When using a motor with a rating of 75 kW or more, be sure to use a DC reactor (option).

EMC filter built-in type Three-phase 400V series

HND (High carrier frequency Normal Duty) 7.5 to 110kW

Item			Specifications										
Type (FRN□□□□G2E-4G)			0018	0023	0031	0038	0045	0060	0075	0091	0112	0150	0180	0216
Nominal applied motor [kW (HP)] (*1)			7.5 (10)	11 (15)	15 (20)	18.5 (25)	22 (30)	30 (40)	37 (50)	45 (60)	55 (75)	75 (100)	90 (125)	110 (150)
Output ratings	Rated capacity [kVA] (*2)		13	17	23	28	34	45	57	69	85	114	137	164
	Rated voltage [V] (*3)		Three-phase 380 to 480 (with AVR function)											
	Rated current [A]		17.5	23	31	38	45	60	75	91	112	150	180	216
	Overload capacity		120%-1min											
	Rated frequency [Hz]		50, 60											
Input ratings	Main circuit power: Phases, voltage, frequency		Three-phase 380 to 480V, 50/60Hz											
	Auxiliary control power input: Phases, voltage, frequency		Single-phase 380 to 480V, 50/60Hz											
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less (*4)) Frequency:+5 to -5%											
	Rated current [A] (*5)	with DCR	14.4	21.1	28.8	35.5	42.2	57.0	68.5	83.2	102	138	164	201
		without DCR	23.2	33.0	43.8	52.3	60.6	77.9	94.3	114	140	–	–	–
	Required power supply capacity [kVA] (*6)	with DCR	10	15	20	25	30	40	48	58	71	96	114	140
Braking	Torque [%] (*7)		70		15				7 to 12					
	Braking transistor		Built-in as standard											–
	Min. ohmic value [Ω]		64	48	32	24	16		10	9.0	8.0	6.5	4.7	–
	Built-in braking resistance [Ω]		80		Option									
		Braking time[s]	3.7	3.4	–									
		%ED	2.2	1.4	–									
	DC injection braking		Starting frequency:0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level:0 to 80%											
EMC filter			Complying EMC standard on emissions and immunity: Category C3 (2nd Env.) (IEC61800-3)											
DC reactor (DCR)			Option										Option (*8)	
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1											
Enclosure (IEC60529)			IIP20 (IEC60529) closed type, UL open type (UL 50)						IP00 open type, UL open type IP55 at external side when external cooling installed					
Cooling method			Fan cooling											
Weight/Mass [kg (lb)]			6.6 (15)	6.6 (15)	6.4 (14)	11 (24)	11 (24)	12 (26)	25 (55)	25 (55)	30 (66)	31 (68)	38 (84)	60 (132)

HND (High carrier frequency Normal Duty) 132 to 710kW

Item			Specifications									
Type (FRN□□□□G2E-4G)			0260	0325	0377	0432	0520	0650	0740	0960	1040	1170	1386
Nominal applied motor [kW (HP)] (*1)			132 (200)	160 (250)	200 (300)	220 (350)	280 (400)	355 (500)	400 (600)	500 (700)	560 (800)	630 (900)	710 (1000)
Output ratings	Rated capacity [kVA] (*2)		198	247	287	329	396	495	563	731	792	891	1056
	Rated voltage [V] (*3)		Three-phase 380 to 480 (with AVR function)										
	Rated current [A]		260	325	377	432	520	650	740	960	1040	1170	1386
	Overload capacity		120%-1min										
	Rated frequency [Hz]		50, 60										
Input ratings	Main circuit power: Phases, voltage, frequency		Three-phase 380 to 480V, 50/60Hz										
	Auxiliary control power input: Phases, voltage, frequency		Single-phase 380 to 480V, 50/60Hz										
	Voltage, frequency variations		Voltage:(10 to -15% (Voltage unbalance:2% or less (*4)) Frequency:+5 to -5%										
	Rated current [A] (*5)	with DCR	238	286	357	390	500	628	705	881	990	1115	1256
		without DCR	–	–	–	–	–	–	–	–	–	–	–
	Required power supply capacity [kVA] (*6)	with DCR	165	199	248	271	347	436	489	611	686	773	871
Braking	Torque [%] (*7)		7 to 12										
	Braking transistor		Option										
	Min. ohmic value [Ω]		–										
	Built-in braking resistance [Ω]		Option										
		Braking time[s]	–										
		%ED	–										
	DC injection braking		Starting frequency:0.0 to 60.0Hz, Braking time: 0.0 to 30.0s, Braking level:0 to 80%										
EMC filter			Complying EMC standard on emissions and immunity: Category C3 (2nd Env.) (IEC61800-3)										
DC reactor (DCR)			Option (*8)										
Applicable safety standards (Planned)			UL61800-5-1, C22.2No.274-17, IEC/EN 61800-5-1										
Enclosure (IEC60529)			IP00 open type, UL open type IP55 at external side when external cooling installed										
Cooling method			Fan cooling										
Weight/Mass [kg (lb)]			60 (132)	89 (196)	89 (196)	116 (256)	124 (273)	221 (487)	221 (487)	291 (642)	295 (650)	450 (992)	450 (992)

(*1) Fuji's 4-pole standard motor When selecting an inverter, in addition to considering the kWs of the inverter, make sure that the output current rating is larger than the motor current rating.
(*2) Rated capacity is calculated by assuming the rated output voltage as 220 V for 200 V series and 440 V for 400 V series.
(*3) Output voltage cannot exceed the power supply voltage.
(*4) Voltage unbalance(%) =Max. voltage (V) - Min. voltage (V) / Three-phase average voltage (V) ×67 (IEC 61800-3)
If this value is 2 to 3%, use an optional AC reactor (ACR).
(*5) These values are calculated on assumption that the inverter is connected to a power supply with a capacity of 500 kVA (or 10 times the inverter capacity when the inverter capacity exceeds 50 kVA) and %X is 5%.
(*6) Required when a DC reactor (DCR) is used.
(*7) This is the average braking torque when performing individual operation. (This will vary based on the motor efficiency.)
(*8) When using a motor with a rating of 75 kW or more, be sure to use a DC reactor (option).

Common Specifications

Item				Explanation	Remarks
Output	Adjustment	Maximum output frequency		5 to 599 Hz variable setting	
		Base frequency		5 to 599 Hz variable setting (in conjunction with maximum output frequency)	
		Number of motor poles setting		2 to 128 poles	
		Starting frequency		0.1 to 60.0 Hz variable setting (0.0 Hz when performing speed sensorless vector control/vector control with speed sensor)	
		Carrier frequency		• 0.75 to 16 kHz variable setting (HHD specification : FRN0003G2S-2G to FRN0288G2S-2G/ FRN0002G2■-4G to FRN0150G2■-4G (HND specification : FRN0032G2S-2G to FRN0088G2S-2G/ FRN0018G2■-4G to FRN0045G2■-4G) • 0.75 to 10 kHz variable setting (HHD specification : FRN0346G2S-2G to FRN0432G2S-2G/ FRN0180G2■-4G to FRN1386G2■-4G), (HND specification : FRN0115G2S-2G to FRN0288G2S-2G/ FRN0060G2■-4G to FRN0150G2■-4G) • 0.75 to 6 kHz variable setting (HND specification : FRN0346G2S-2G to FRN0432G2S-2G/ FRN0180G2■-4G to FRN1386G2■-4G) Note: The carrier frequency may automatically lower depending upon the ambient temperature or the output current to protect the inverter. (The automatic lowering function can be disabled.)	
	Output frequency accuracy			• Analog setting : ±0.2% of maximum output frequency (at 25 ±10 °C) (77 ±18 °F) • Keypad setting : ±0.01% of maximum output frequency (at 10 to +50 °C) (14 ±22 °F)	
	Frequency setting resolution			• Analog setting : 1/3000 of maximum output frequency • Keypad setting : 0.01 Hz • Link setting : 1/20000 of maximum output frequency or 0.01 Hz (fixed)	
	Synchronous motors	When performing V/f control with sensor*1 When performing dynamic torque vector control with sensor*2	Speed control Range	• 1:20*1, 1:200*2 (Minimum speed: Nominal speed) • 1:2 (fixed torque area : fixed output area)	
			Speed control accuracy	• Analog setting: ±0.2% of maximum output frequency or below (at 25 ±10 °C) • Digital setting: ±0.01% of maximum output frequency or below (at 10 to +50 °C)	
		When performing sensorless vector control	Speed control Range	• 1:200 (Minimum speed: Nominal speed) • 1:2 (fixed torque area : fixed output area)	
			Speed control accuracy	• Analog setting: ±0.5% of nominal speed or below (at 25 ±10 °C) • Digital setting: ±0.5% of nominal speed or below (at 10 to +50 °C)	
		When performing vector control with sensor	Speed control Range	• 1:1500 (Minimum speed: Nominal speed) • 1:16 (fixed torque area : fixed output area)	
			Speed control accuracy	• Analog setting: ±0.2% of maximum output frequency or below (at 25 ±10 °C) • Digital setting: ±0.01% of maximum output frequency or below (at 10 to +50 °C)	
		When performing sensorless vector control	Speed control Range	• 1:10 (Minimum speed: Nominal speed) • 1:2 (fixed torque area : fixed output area)	
			Speed control accuracy	• Analog setting: ±0.5% of nominal speed or below (at 25 ±10 °C) • Digital setting: ±0.5% of nominal speed or below (at 10 ±+50 °C°C)	
		When performing vector control with sensor	Speed control Range	• 1:1500 (Minimum speed: Nominal speed) • 1:2 (fixed torque area : fixed output area)	
			Speed control accuracy	• Analog setting: ±0.2% of maximum output frequency (at 25 ±10 °C) • Digital setting: ±0.01% of maximum output frequency (at 10 to +50 °C)	
Control	Control method			• V/f control • Dynamic torque vector control • V/f control with sensor, dynamic torque vector control with sensor • Sensorless vector control • Vector control with sensor • Sensorless vector control (synchronous motors) • Vector control with sensor (synchronous motors)	
	Voltage/frequency characteristics		200V series	• The base frequency and maximum output frequency are common, and the voltage can be set between 80 and 240 V. • AVR control can be turned ON or OFF. • Non linear V/f setting (3 points): The desired voltage (0 to 240 V) and frequency (0 to 599 Hz) can be set.	
			400V series	• The base frequency and maximum output frequency are common, and the voltage can be set between 160 and 500 V. • AVR control can be turned ON or OFF. • Non linear V/f setting (3 points): The desired voltage (0 to 500 V) and frequency (0 to 599 Hz) can be set.	
	Torque boost			• Auto torque boost (for constant torque load) • Manual torque boost: The desired torque boost value (0.0 to 20.0%) can be set. • The applicable load can be selected (for constant torque load, quadratic-torque load)	
	Starting torque (HHD specification)			• FRN0115G2S-2G/FRN0060G2■-4G or below 200% or higher, • FRN0145G2S-2G/FRN0075G2■-4G or above 180% or higher set frequency: 0.3 Hz, when performing V/f control (base frequency: 50 Hz, slip compensation/auto torque boost)	
	Running · operation		Key operation:	Start and stop with RUN and STOP keys (standard keypad) Start and stop with FWD, REV, and STOP keys (optional multi-function keypad)	
				External signals: Forward (reverse) rotation, start/stop commands (capable of 3-wire operation), (digital input) coast to stop command, external alarm, alarm reset, etc.	
				Link operation: Operation through RS-485, field bus communication (option)	
				Run command switching : Remote/local switching, link switching	
	Frequency setting			Keypad operation : Using ▲ and ▼ keys	
				External potentiometer: Using external frequency command potentiometer (external resistor of 1 to 5 kΩ, 1/2 W)	
			Analog input :	Voltage input (terminal [12], [V2], [C1] (V3 function)) 0 to ±10 VDC (±5 VDC)/0 to ±100% 0 to +10 VDC (+5 VDC)/0 to +100% (+1 to +5 VDC can also be adjusted with bias, analog input gain) Voltage input (terminal [C1] (C1 function)) 4 to 20 mA DC/0 to 100%, 0 to 20 mA DC/0 to 100% 4 to 20 mA DC/-100 to +100%, 0 to 20 mA DC/-100 to +100%	

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

	Item		Explanation	Remarks
Control	Frequency setting		UP/DOWN operation: Frequency can be increased or decreased while the digital input signal is ON. The frequency recorded with digital input “STZ” can be cleared.	
			Multistep frequency selection: Selectable from 16 different frequencies (step 0 to 15)	
			Pattern operation: The inverter runs automatically according to the previously specified run time, rotation direction, acceleration/deceleration time and reference frequency. Up to 7 stages can be specified.	
			Link operation: Setting through RS-485, field bus communication (option) (built in as standard)	
			Frequency setting switching: Two types of frequency settings can be switched with an external signal (digital input). Remote/local switching, link switching	
			Auxiliary frequency setting: Can be selected by adding and entering the respective terminal [12], [C1], or [V2] inputs.	
			Operation at a specified ratio: The ratio can be set with an analog input signal..	
			Inverse operation: Can be switched from “0 to +10 VDC/0 to 100%” to 10 to 0 VDC/0 to 100%” from an external source. Can be switched from “4 to 20 mA DC/0 to 100%” to “20 to 4 mA DC/0 to 100%” from an external source. Can be switched from “0 to 20 mA DC/0 to 100%” to “20 to 0 mA DC/0 to 100%” from an external source.	
			Pulse train input: (standard) Pulse input = terminal [X6], [X7], forward/reverse pulse, pulse + rotation direction Complementary output: Max. 100 kHz Open collector output: Max. 30 kHz	
			Pulse train input: (option) PG interface option, forward/reverse pulse, pulse + rotation direction Complementary output: Max. 100 kHz Open collector output: Max. 30 kHz	
	Acceleration/ deceleration time		Setting range: Setting range from 0.00 to 6000 s	
			Switching: The four types of acceleration/deceleration time can be set or selected individually (switchable during operation).	
			Acceleration/deceleration pattern: Linear acceleration/Deceleration, S curve acceleration/deceleration (week, random (weak)), curve line acceleration/deceleration (max. acceleration/deceleration at rated output)	
			Deceleration mode (coast to stop): Shutoff of the run command lets the motor coast to a stop.	
			Forcible stop deceleration time: Deceleration stop in exclusive deceleration time by forced stop (STOP). • Dedicated acceleration/deceleration time for jogging: • It is possible to switch between acceleration/deceleration time = 0 with acceleration/deceleration operation cancel “BPS”.	
	Frequency limiter (upper limit and lower limit frequencies)		• Specifies the upper and lower frequencies in Hz. • Processing can be selected when the reference frequency is less than the lower limit (F16). (The output frequency will be maintained at the lower limit/motor decelerates and stops.) • Setting is possible with analog input (terminal [12], [C1], [V2], [V3]).	
	Frequency/PID command bias		Bias of reference frequency and PID command can be independently set (setting range: 0 to ±100%).	
	Analog input		• Gain: Setting range from 0 to 400% • Offset: Setting range from 5.0 to +5.0% • Filter: Setting range from 0.00 to 5.00s	
	Jump frequency		Six operation points and their common jump width (0 to 30.0 Hz) can be set.	
	Ready for jogging		Operation with RUN key (standard keypad), FWD or REV keys (multi function keypad), or digital contact inputs “FWD” or “REV” (Exclusive acceleration/deceleration time setting, exclusive frequency setting)	
	Restart mode after momentary power failure		• Trip immediately: Trip immediately at the time of power failure. • Trip after recovery from power failure: Coast to a stop at the time of power failure and trip when the power is recovered. • Trip after decelerate to stop: Deceleration stop at power failure, and trip after stoppage • Continue to run: Operation is continued using the load inertia energy. • Start at the frequency selected before momentary power failure: Free run at power failure and start after power recovery at the frequency selected before momentary stop. • Start at starting frequency: Free run at power failure and start at the starting frequency after power recovery.	
	Current limiting	Hardware current limiter	Current is limited with hardware to prevent overcurrent trip due to high-speed load fluctuations or momentary power failure which cannot be handled with software current limiting. (This limiter can be canceled.)	
		Software current limiter	Automatically reduces the frequency so that the output current becomes lower than the preset operation level. (This limiter can be canceled.) The operation can be selected (operation at constant speed only, operation when accelerating and at constant speed).	
	Operation by commercial power supply		• With commercial power selection commands (“SW50”, “SW60”), the inverter outputs 50/60 Hz. • Commercial switching sequence built in	
	Slip compensation		Compensates for decrease in speed according to the load.	
	Droop control		Decreases the speed according to the load torque.	
	Torque limit control		• Switchable between 1st and 2nd torque limit values. • Torque limiting/torque current limiting/power limiting for each quadrant • Analog torque limit input	
	PID control		• PID processor for process control/dancer control • Switch normal/inverse operation • Low liquid level stop function (pressurized operation possible before low liquid level stop) • PID command: keypad, analog input (terminals [12], [C1] (C1 function, V3 function), [V2],), RS 485 communication • PID feedback value: analog input (terminals [12], [C1] (C1 function, V3 function), [V2]) • Alarm output (absolute value alarm, deviation alarm) • PID output limiter • Integration reset/hold • Anti reset wind up function • PID constant auto tuning function for process control PID controller	
	Auto search		The motor speed is estimated before startup, and the motor is started without ever stopping the motor while it is idling. (Motor constants must be tuned. Auto tuning (offline))	
	Anti regenerative control (Automatic deceleration)		• If the intermediate DC voltage/torque calculation value reach or exceed the anti regenerative control level when the motor is decelerating, the deceleration time is automatically extended to avoid an overvoltage trip. (Forced deceleration can be set at three or more times the deceleration time.) • If the torque calculation value reaches or exceeds the anti regenerative control level during constant speed operation, overvoltage tripping is avoided by performing control to raise the frequency.	
	Deceleration characteristics (Improvement of braking performance)		The motor loss is increased during deceleration to reduce the regenerative energy in the inverter to avoid overvoltage trip.	
	Auto energy saving operation		Controls the output voltage to minimize the total sum of the motor loss and inverter loss. (Auto energy saving control can be turned ON and OFF from an external source with a digital input signal.)	

* For details, refer to the FRENIC-MEGA (G2) User’s Manual.

Common Specifications

	Item	Explanation	Remarks
Control	Overload prevention control	If the surrounding temperature or IGBT junction temperature increases due to overload, the inverter lowers the output frequency to avoid overload.	
	Offline tuning	Tunes the motor while the motor is stopped or running, for setting up motor parameters.	
	Offline tuning	This corrects changes in motor constants caused by temperature rise.	
	Cooling fan ON OFF control	• Detects inverter internal temperature and stops cooling fan when the temperature is low. • Possible to output a fan control signal to an external device.	
	Motor 1 to 4 settings	• Switching is possible between 4 motors. • It is possible to switch between four types of specific function code data (switching is possible while the motor is running.) The following data can be set for motors 1 to 4: base frequency, rated current, torque boost, electronic thermal slip compensation.	
	Universal DI	Transfers the status of an external digital signal connected with the general purpose digital input terminal to the host controller.	
	Universal DO	Outputs a digital command signal sent from the host controller to the general purpose digital output terminal.	
	Universal AO	Outputs an analog command signal sent from the host controller to the analog output terminal.	
	Speed control	• Selectable among the four set of the auto speed regulator (ASR) parameters. • Notch filter for vibration control	
	Line speed control	Regulates the motor speed to keep the peripheral speed constant even if the roll winding diameter changes on machines such as winders and unwinders. Tension can be controlled when used in combination with PID control. (A PG option card is required.)	
	Master follower operation	Two motors can be run synchronously using a pulse generator (PG). (A PG option card is required.)	
	Pre excitation	Excitation is carried out to create the motor flux before starting the motor.	
	Zero speed control	The motor speed is held to zero by forcibly zeroing the speed command.	
	Servo lock	Stops the motor and holds the motor in the stopped position.	
	DC braking	• Applies DC current to the motor at the operation start time or at the time of inverter stop to generate braking torque.	
	Mechanical brake control	• It is possible to output mechanical brake control signals with the brake ON/OFF timing adjusted by the output current, torque commands, output frequency and timer. • The output timing of control signals can be adjusted individually when performing • Errors can be detected with mechanical brake operation check input signals.	
	Torque control	• Analog torque command input • Speed limit function is provided to prevent the motor from becoming out of control. • Torque bias (with analog setting, digital setting) possible	
	Rotation direction limitation	Select either of reverse or forward rotation prevention.	
	Motor condensation prevention	Current flows automatically when the motor is stopped, and the motor temperature is raised to prevent condensation.	
	Customizable logic	It is possible to select or connect digital logic circuits or analog operation circuits with digital/analog I/O signals, configure a simple relay sequence, and operate it freely. (The maximum number of steps is 260)	
	Battery operation	Inverters at which an undervoltage has occurred are run with the battery power. 200V: 1.5 to 37 kW, 400V: 1.5 to 55 kW	
	Overload stop function	When used for hoisting applications, the motor stops if the inverter detects excessive torque during ascent. After the overload is detected, operation is possible only in the descend direction.	
	Light-load stop function	If the load is lighter than the preset load level, operation can be performed at a frequency that is the set frequency multiplied by a specified ratio / the maximum allowable frequency depending on the load (e.g., vertical transportation machines, conveyors).	
	Position control	•Absolute/relative positioning is possible using a pulse encoder •The stop target position can be set by the user's preferred unit system (using electronic gears) via function code (8 point) communication. •Home return, Preset, Clear function, Teaching function •Position regulator (APR), Position feed forward function •Movable range is settable by overtravel detection and stop function	
	Orientation function	This function makes it possible for rotors such as machine tool spindles and turntables to be positioned. Stop target position can be set by a function code (8 points)	
	Favorites function code	The function code can be registered in "Favorites" and displayed (Applicable to all function codes).	
	Data initialization	All function codes and limited function codes can be initialized.(Per motor, non-communication-related, customized logic only, Favorites only)	
	Simulated operation mode	Sequence check is possible without inverter output.	
	Start check function	To ensure safety, the presence or absence of an operation command is checked at power-on, at alarm reset, and when switching operation command methods. An alarm is displayed if an operation command has been input.	
	Multifunction key	During the operation mode, the multifunction key "M/SHIFT" on standard keypads (TP-E2) can be used as an input method to activate the input terminal function like the X terminal.	
	Traceback	Data (user-selectable) such as frequency, voltage, current, etc., immediately before a trip can be saved and analyzed.	
Display	Running/stopping	Speed monitor (reference frequency, output frequency, motor speed, load shaft speed, line speed, and speed indication percentage), output current [A], output voltage [V], calculated torque [%], power consumption [kW], PID command value, PID feedback value, PID output, load factor [%], motor output [kW], torque current (%), magnetic flux command (%), analog input monitor, input watt hour	
	Inverter lifetime alarm	• It is judged that the life of main circuit capacitors, electrolytic capacitors on PCBs,IGBT or the cooling fan has been reached. • Life alarm information can be output externally. • Ambient temperature: 40 °C Load factor: Inverter rated current of 100% (HHD specification), 80% (HND specification)	
	Cumulative operating status	• The inverter cumulative running time, cumulative input watt hours, and motor cumulative running time/start count (for each motor) is displayed. • A warning is output if the maintenance time or startup count set beforehand is exceeded.	
	Trip	Displays the cause of a trip.	
	Light alarm	The cause of light alarms is displayed.	
	During operation, when trip occurs	• Trip history: The cause (code) of the up to the last four trips is retained and displayed. • All kinds of running status data for up to the past four trips is retained and displayed. •Date and time can be displayed in the history by using the clock function (TP-A2SW)	

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

	Item		Explanation	Remarks
Protective functions	Overcurrent protection		Stops the inverter to protect it from overcurrent caused by an overload.	0C1 0C2 0C3
	Short circuit protection		Stops the inverter to protect it from overcurrent caused by shorting of the output circuit.	
	Ground fault protection		Stops the inverter to protect it from overcurrent caused by an output circuit ground fault. Protection may be disabled if the power is turned ON with the ground fault still occurring.	
			Detects output current zero-phase current, and stops the inverter to protect it from overcurrent caused by an output circuit ground fault. (5.5 kW or higher)	EF
	Overvoltage protection		Stops the inverter if a DC intermediate circuit overvoltage (400V series: 800 VDC, 200V series: 400 VDC) is detected. The inverter cannot be protected if an excessively large voltage is applied by accident.	0U1 0U2 0U3
	Undervoltage protection		Stops the inverter if a drop in DC intermediate circuit voltage (400V series: 400 VDC, 200V series: 200 VDC) is detected. However, this is disabled based on the restart after momentary power failure setting. Furthermore, operation is possible (regenerative operation only) at a voltage level lower than that above when performing battery operation.	LU
	Input phase loss protection		Stops the inverter if input voltage phase loss or interphase unbalance factor is detected. If the load is light, or when a DC reactor is connected, input phase loss may not function.	Lin
	Output phase loss protection		Stops the inverter if inverter output phase loss is detected during operation. This protective function also functions during auto tuning and during magnetic pole position tuning. (Operation selection possible)	OPL
	Overheat protection		Stops the inverter if a cooling fan fault, or cooling fin overheating when an overload occurs is detected.	OH1
			Stops the inverter if inverter unit internal charging resistor overheating is detected.	OH3
			By setting the braking resistor electronic thermal overload relay function, the inverter is stopped to protect the braking resistor from overheating.	dbH
	Inverter overload protection		Stops the inverter if overheating is detected by calculating the IGBT internal temperature from the output current and detected internal temperature.	OLU
	External alarm input		Stops the inverter and displays an error if a digital input signal (THR) is input.	OH2
	Blown fuse		Stops the inverter and displays an error if a main circuit blown fuse is detected inside the inverter. (75 kW or higher (200V class), 90 kW or higher (400V class))	FUS
	Charger circuit error		Stops the inverter and displays an error if an inverter charging circuit error is detected. (37 kW or higher (200V class), 75 kW or higher (400V class))	PbF
	Braking transistor error		Stops the inverter and displays an error if a braking transistor error is detected.	dbA
	Motor protection	Electronic thermal overload relay	Stops the inverter if a motor overload is detected by setting the electronic thermal overload relay. Protects general-purpose motors and inverter motors in the entire frequency range. (The operation level and thermal time constant (0.5 to 75.0 minutes) can be set.)	OL1 to OL4
		PTC/NTC thermistor	The motor temperature is detected by the PTC/NTC thermistor, and the inverter is stopped if overheating is detected. To enable this function, connect the PTC/NTC thermistor between terminals [V2] and [11], and enable the switch on the control board.	OH4
		NTC thermistor wire break	The inverter is stopped and an error is displayed if a wire break is detected at the NTC thermistor connected between terminals [V2] and [11].	nrb
	Memory error		When the power is turned ON, a data check is performed when writing data, and an error is displayed if a memory error is detected.	Er1
	Keypad communication error		Stops the inverter and displays an error if a communication fault is detected at the keypad during operation.	Er2
	CPU error		Stops the inverter and displays an error if a CPU error is detected due to noise, etc.	Er3
	Option communication error		Stops the inverter and displays an error if a communication error with the inverter unit is detected when using an option.	Er4
	Option error		Stops the inverter and displays an error if an error is detected at the option side when using an option.	Er5
	Operation error	STOP key priority	Even when run commands are entered via the terminal block or communication, by pressing the keypad STOP button, the inverter forcibly decelerates and stops the motor, and an error is displayed after the motor has come to a stop.	Er6
		Start check	When the power is turned ON, an alarm is cleared, or when switching the run command method from link operation, the sudden starting of operation is suppressed if a run command has been entered, and an error is displayed to notify the operator.	
		Brake status error	Stops the inverter and displays an error if the brake signal (BRKS) output status and brake ON check signal (BRKE) input status do not match.	
	Tuning error		Stops the inverter and displays an error if tuning failure or interruption is detected during motor constant tuning, or if the tuning result is a defect.	Er7
	RS485 communication error (COM port 1)		Stops the inverter and displays an error if a communication error is detected when communicating via RS-485 COM port 1.	Er8
	RS485 communication error (COM port 2)		Stops the inverter and displays an error if a communication error is detected when communicating via RS-485 COM port 2.	ErP
	Data saving error during undervoltage		Stops the inverter and displays an error if unable to successfully save data when undervoltage protection is triggered.	ErF
	Position control error		Stops the inverter and displays an error if the positioning deviation is excessive when the servo lock is applied, or when performing master-follower operation.	Ero
	Hardware error		Stops the inverter and displays an error if an inverter internal hardware fault is detected.	ErH
	STOP input (EN1, EN2) terminal circuit error		Stops the inverter and displays an error if the inverter detects an EN1 or EN2 terminal circuit mismatch.	ECF
	PG wire break		Stops the inverter and displays an error if a pulse encoder wire break is detected. (This function is valid on some PG interface option cards.)	PG
	Excessive positioning deviation		Stops the inverter and displays an error if the position deviation is found to be excessive while performing position control.	dO
	Overspeed protection		Stops the inverter and displays an error if the following conditions are met. • If d35 = 999, the speed detection value is the maximum output frequency x (d32 or d33) x 120% or higher • If d35 ≠ 999, the speed detection value is the maximum output frequency x (d35) or higher • The detection value exceeds 599 Hz	OS

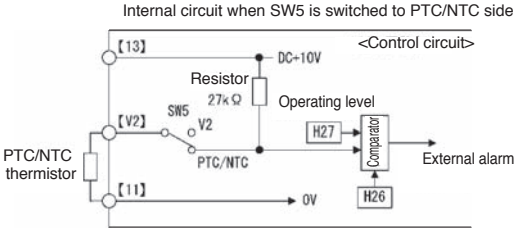
* For details, refer to the FRENIC-MEGA (G2) User's Manual.

Common Specifications

	Item	Explanation	Remarks
Protective functions	Magnetic pole position detection error	Stops the inverter and displays an error if the signal from the magnetic pole position sensor mounted on the PM motor is abnormal.	ErC
	Step-out detection/ detection failure of magnetic pole position at startup	This occurs when a PM motor step-out is detected, or if magnetic pole position detection fails when starting.	Erd
	Speed inconsistency/ excessive speed deviation	Stops the inverter and displays an error if the state in which the speed deviation between the command speed and detected speed (ASR feedback) is too great continues for the specified time or longer.	ErE
	Password protection	Stops the inverter and displays an error if an attempt is made by a malicious third party to disable the password set by the user.	LoP
	Customizable logic error	Stops the inverter and displays an error if an attempt is made to make changes to customizable logic related settings while the inverter is running.	ECL
	Simulation failure	A simulation failure can be produced if the keypad STOP button and FUNC DATA button are held down for 5 seconds or longer. A simulation failure can be produced even if function code H45 is set to "1".	Err
	Current input terminal signal line break detection	Stops the inverter and displays an error if a line break is detected when current is less than 2 mA when using the current input terminal (terminal [C1] or [C2]) as current input 4 to 20 mA.	CoF
	Customizable logic alarm	An error is displayed if the alarm conditions defined by the user with customizable logic are met. (This is not an error at the inverter itself.)	CA1 to CA5
	EN (STO) terminal OFF	This is displayed if the run command turns ON when both terminal [EN1] and [EN2] are OFF, and the inverter is not ready to perform operation (STO status).	En.oFF
	Warning	Motor overload early warning	OL
		Cooling fin overheat early warning	OH
		Lifetime alarm	L iF
		Reference command loss detected	rEF
		PID alarm output	P id
		Low torque detection	uTL
		PTC thermistor activated	PTC
		Machine life (Cumulative motor running hours)	rTE
		Inverter life (Number of startups)	CnT
		Customizable logic alarm	CA1 to CA5
		IGBT lifetime alarm	iGb
		Cooling capability drop warning	rAF
	Retry	The inverter can be automatically reset allowing it to be restarted when it stops due to a trip.(The number of retries and the latency between stop and reset can be specified.)	
	Surge protection	This function protects the inverter from a surge voltage between main circuit power lines and the ground.	
	Main circuit power cutoff detection	• Inverter operation is not possible when the inverter AC input power supply (main power supply) is not ON. • In such cases as when supplying power via a PWM converter or when using a DC bus bar connection, set main circuit power cutoff detection to "None".	
	Forced operation (Fire mode)	Alarms other than critical alarms are ignored, and a retry is performed forcibly.	
Environmental	Usage location	Indoors (environmental standard IEC60721-3-3:3C2); No corrosive gas, flammable gas, dust, oil mist (pollution level 2 (IEC60664-1)); No direct sunlight	
	Ambient temperature	10 to +55°C (derating is required if temperature exceeds 50°C.) *For dense mounting horizontally: -10 to +40°C (22 kW or less)	
	Ambient humidity	5 to 95% RH (avoid condensation)	
	Altitude	1000 m or less	
	Vibration	200 to 400 V Series, 22 kW or less 3 mm: 2 to less than 9 Hz; 9.8 m/s²: 9 to less than 20 Hz 5.9 m/s²: 20 to less than 55 Hz; 1 m/s²: 55 to 200 Hz 200 V Series, 30 kW to 55 kW; 400 V Series, 30 kW to 75 kW 3 mm: 2 to less than 9 Hz; 9.8 m/s²: 9 to less than 20 Hz 2 m/s²: 20 to less than 55 Hz; 1 m/s²: 55 to 200 Hz 200 V Series, 75 kW or more; 400 V Series, 90 kW or more 3 mm: 2 to less than 9 Hz; 2 m/s²: 9 to less than 55 Hz 1 m/s²: 55 to 200 Hz	
	Storage temperature	• -25 to +70°C (during transport) • -25 to +65°C (during temporary storage)	
	Relative humidity	5 to 95% RH (avoid condensation)	

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

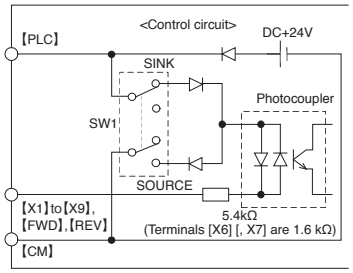
Terminal Specifications

Class	Symbol	Terminal name	Explanation
Main circuit	L1/R,L2/S,L3/T	Main power supply input terminals	Connect a three-phase power supply.
	U,V,W	Inverter output	3-phase motor connection
	P(+),P1	For DC reactor connection	Connect DC reactor (DCR) (optional) HHD specification: Optionally connect for FRN0002 to FRN0150, but always make sure to connect for FRN0180 or more. HND specification: Optionally connect for FRN0018 to FRN0112, but always make sure to connect for FRN0150 or more. * Select a standard motor that is applicable to the HND specifications.
	P(+),N(-)	For DC busbar connection	Use to connect to the DC intermediate circuit of other inverters, PWM converters, etc
	P(+),DB	For braking resistor connection	Connect terminal (+) of the braking resistor (DB) (optional) and the DB (wiring distance: 5 m or less)
	⏚G	For grounding the chassis (case) of the inverter	• This is the earth terminal of the inverter chassis (case) and motor. • Connect one terminal to the ground and the other terminal to the earth terminal of the motor (comes with two terminals).
	R0,T0	Auxiliary control power input	Connect to the power supply when you want to preserve the batch alarm signal during protective function activation (even when the main power of the inverter has been cut off), or when you want to continuously display the keypad (FRN0004 or more).
Analog input	【13】	Power supply for variable resistor	• Use as a power supply (+10 V DC) for an external frequency setter (variable resistor: 1 to 5 kΩ). • Use a variable resistor of 1/2 W or more when connecting.
	【12】	Analog setting voltage input	(1) Set the frequency according to the external analog voltage input instruction value. • 0 to ±10 V DC/0 to ±100 (%) (normal action) • +10 to 0 V DC/0 to 100 (%) (reverse action) (2) It supports using analog inputs to assign frequency settings, PID instructions, PID control feedback signals, auxiliary frequency settings, ratio settings, torque limiting settings, torque instruction values/torque current instruction values, speed limiting values, and analog input monitors. (3) Hardware specification * Input impedance: 22 (kΩ) * Can input up to ±15 V DC. However, it will be deemed to be ±10 V DC for any value that exceeds ±10 V DC. * Set function code C35 to "0" when inputting the analog setting voltage of both poles (0 to ±10 V DC) at terminal [12].
	【C1】	Analog setting current input (C1 function)	(1) Set the frequency according to the external analog current input instruction value. • 4 to 20 mA DC/0 to 100 (%), 0 to 20 mA DC/0 to 100 (%) (normal action) • 20 to 4 mA DC/0 to 100 (%), 20 to 0 mA DC/0 to 100 (%) (reverse action) (2) It supports using analog inputs to assign frequency settings, PID instructions, PID control feedback signals, auxiliary frequency settings, ratio settings, torque limiting settings, torque instruction values/torque current instruction values, speed imiting values, and analog input monitors. (3) Hardware specifications * Input impedance: 250 (Ω) * Can input up to 30 mA DC. However, it will be deemed to be 20 mA DC for any value that exceeds 20 mA DC.
		Analog setting voltage input (V3 function)	(1) Set the frequency according to the external analog voltage input instruction value. • 0 to ±10 V DC/0 to ±100 (%) (normal action) • +10 to 0 V DC/0 to 100 (%) (reverse action) (2) It supports using analog inputs to assign frequency settings, PID instructions, PID control feedback signals, auxiliary frequency settings, ratio settings, torque limiting settings, torque instruction values/torque current instruction values, speed limiting values, and analog input monitors. (3) Hardware specifications * Input impedance: 22 (kΩ) * Can input up to ±15 V DC. However, it will be deemed to be ±10 V DC for any value that exceeds ±10 V DC. * Set function code C78 to "0" when inputting the analog setting voltage of both poles (0 to ±10 V DC) at terminal [V3].
	【V2】	Analog setting voltage input (V2 function)	(1) Set the frequency according to the external analog voltage input instruction value. • 0 to ±10 V DC/0 to ±100 (%) (normal action) • +10 to 0 V DC/0 to 100 (%) (reverse action) (2) It supports using analog inputs to assign frequency settings, PID instructions, PID control feedback signals, auxiliary frequency settings, ratio settings, torque limiting settings, torque instruction values/torque current instruction values, speed limiting values, and analog input monitors. (3) Hardware specifications * Input impedance: 22 (kΩ) * Can input up to ±15 V DC. However, it will be deemed to be ±10 V DC for any value that exceeds ±10 V DC. * Set function code C45 to "0" when inputting the analog setting voltage of both poles (0 to ±10 V DC) at terminal [V2].
		PTC/NTC thermistor input (PTC/NTC function)	(1) A PTC/NTC thermistor can be connected to protect the motor. (2) The PCB's SW5 switch needs to be switched to PTC/NTC side. • The figure below shows the internal circuit when SW5 (the switch for terminal [V2]) is switched to the PTC/NTC side. • When SW5 is switched to PTC/NTC side, function code H26 also needs to be changed. Internal circuit when SW5 is switched to PTC/NTC side 
	【11】	Analog common	• Common terminals for analog I/O signals (terminals [13], [12], [C1], [V2], [FM1], and [FM2]). • Insulated against terminals [CM] and [CMY].

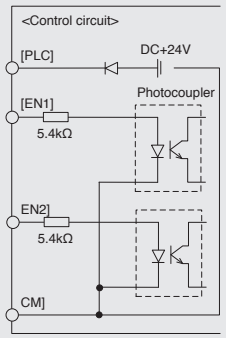
* For details, refer to the FRENIC-MEGA (G2) User's Manual.

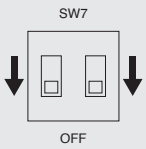
Terminal Specifications

<table>
<tr><th>Class</th><th>Symbol</th><th>Terminal name</th><th>Explanation</th></tr>
<tr><td rowspan="13">Analog input</td><td>【X1】</td><td>Digital input 1</td><td rowspan="10">(1) Various signals (coast to stop command, external alarms, multistep frequency selection, etc.) can be set for terminals [X1] to [X9], [FWD], and [REV].
(2) The input mode and SINK/SOURCE can be switched using SW1.
(3) The operating mode between each digital input terminal and terminal [CM] can be switched to "ON when shorted (active ON)" or "OFF when shorted (active OFF)".
(4) Digital input terminals [X6] and [X7] can be set up as pulse train input terminals by changing the function code.
• When connected to complementary output pulse generator: max. 100 Hz
• When connected to open collector output pulse generator: max. 30 Hz
(A pull-up resistor and pull-down resistor are required.)

<Digital input circuit specifications>
Digital input circuit
 

<table>
<tr><th colspan="2">Item</th><th>Min.</th><th>Max.</th></tr>
<tr><td rowspan="2">Operating voltage (SOURCE)</td><td>ON level</td><td>0V</td><td>2V</td></tr>
<tr><td>OFF level</td><td>20V</td><td>27V</td></tr>
<tr><td rowspan="2">Operating voltage (SINK)</td><td>ON level</td><td>20V</td><td>27V</td></tr>
<tr><td>OFF level</td><td>0V</td><td>2V</td></tr>
<tr><td colspan="2">Operating current when ON (when input voltage 27 V) (X6/X7 input terminals)</td><td>2.5mA (3mA)</td><td>5mA (16mA)</td></tr>
<tr><td colspan="2">Permissible leakage current when OFF</td><td>—</td><td>0.5mA</td></tr>
</table></td></tr>
<tr><td>【X2】</td><td>Digital input 2</td></tr>
<tr><td>【X3】</td><td>Digital input 3</td></tr>
<tr><td>【X4】</td><td>Digital input 4</td></tr>
<tr><td>【X5】</td><td>Digital input 5</td></tr>
<tr><td>【X6】</td><td>Digital input 6</td></tr>
<tr><td>【X7】</td><td>Digital input 7</td></tr>
<tr><td>【X8】</td><td>Digital input 8</td></tr>
<tr><td>【X9】</td><td>Digital input 9</td></tr>
<tr><td>【FWD】</td><td>Forward・rotation/stop command Input</td></tr>
<tr><td>【REV】</td><td>Reverse・rotation/stop command Input</td></tr>
<tr><td>【EN1】
【EN2】</td><td>Enable input</td><td>(1) When the terminal between [EN1] and [-PLC] or between [EN2] and [-PLC] is OFF, the operation of the inverter's output transistor will be stopped (Safe torque off: STO).
Always make sure to operate terminals [EN1] and [EN2] simultaneously.
If the terminals are not operated simultaneously, the eCf alarm will trigger and this will prevent the inverter from operating.
(2) The input mode of terminals [EN1] and [EN2] is fixed to the source and cannot be switched to the sink.
(3) SW7 can be used to enable or disable this function.
To use this function, set each SW7 switch to OFF.

<Enabling input circuit specifications>
 

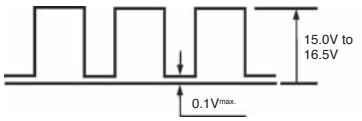
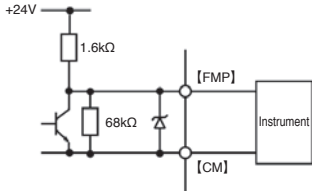
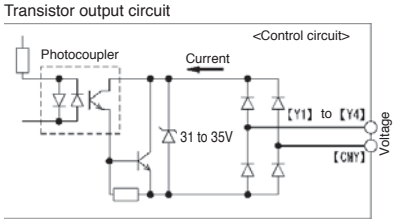
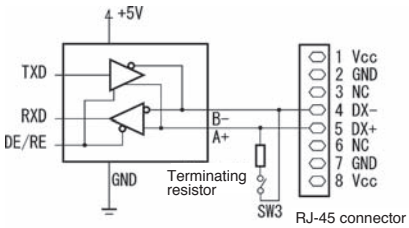
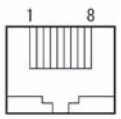


<table>
<tr><th colspan="2">Item</th><th>Min.</th><th>Max.</th></tr>
<tr><td rowspan="2">Operating voltage (SOURCE)</td><td>ON level</td><td>20V</td><td>27V</td></tr>
<tr><td>OFF level</td><td>0V</td><td>2V</td></tr>
<tr><td colspan="2">Operating current when ON (when input voltage 27 V)</td><td>2.5mA</td><td>10mA</td></tr>
<tr><td colspan="2">Permissible leakage current when OFF</td><td>—</td><td>0.5mA</td></tr>
</table></td></tr>
<tr><td>【PLC】</td><td>Programmable controller signal power supply</td><td>(1) Connect the output signal power supply for the programmable controller.
(Rated voltage +24 VDC (power supply voltage fluctuation range: +20 to +27 VDC), maximum 100 mA DC)
(2) The terminal can also be used as the power supply for loads connected to transistor outputs</td></tr>
<tr><td>【CM】</td><td>Digital common</td><td>This is a common terminal for digital input signals.
The terminal is insulated from terminals [11] and [CMY].</td></tr>
<tr><td rowspan="2">Analog output</td><td>【FM1】
【FM2】</td><td>Analog monitor
(FMA function)</td><td>This function outputs a monitor signal of analog DC voltage 0 to ±10 V DC, analog DC current 4 to 20 mA DC, or 0 to 20 mA DC.
The [FM1] output format (VO1/IO1) is switched by the PCB's SW4 switch and function code F29.
The content of the signal is selected from the following items based on the data setting of function code F31.
The [FM2] output format (VO2/IO2) is switched by the PCB's SW6 switch and function code F32.
The content of the signal is selected from the following items based on the data setting of function code F61.

Output frequency / Power consumption / Motor output
Output current / PID feedback amount / Analog output test
Output voltage / Speed detection（PG feedback value） / PID command
Output torque / Intermediate DC voltage / PID output
Load factor / Universal AO / Master-follower angle deviation

* Connectable impedance: Minimum of 5 kΩ (when outputting 0 to ±10 V DC) (up to two analog voltmeters (0 to 10 V DC, input impedance of 10 kΩ) can be connected.)
* Connectable impedance: Maximum of 500 Ω (at 4 m to 20 mA DC output)
* Gain adjustment range: 0 to 300%</td></tr>
<tr><td>【11】</td><td>Analog common</td><td>This is a common terminal for analog input/output signals.
This terminal is isolated from terminals [CM] and [CMY].</td></tr>
</table>

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

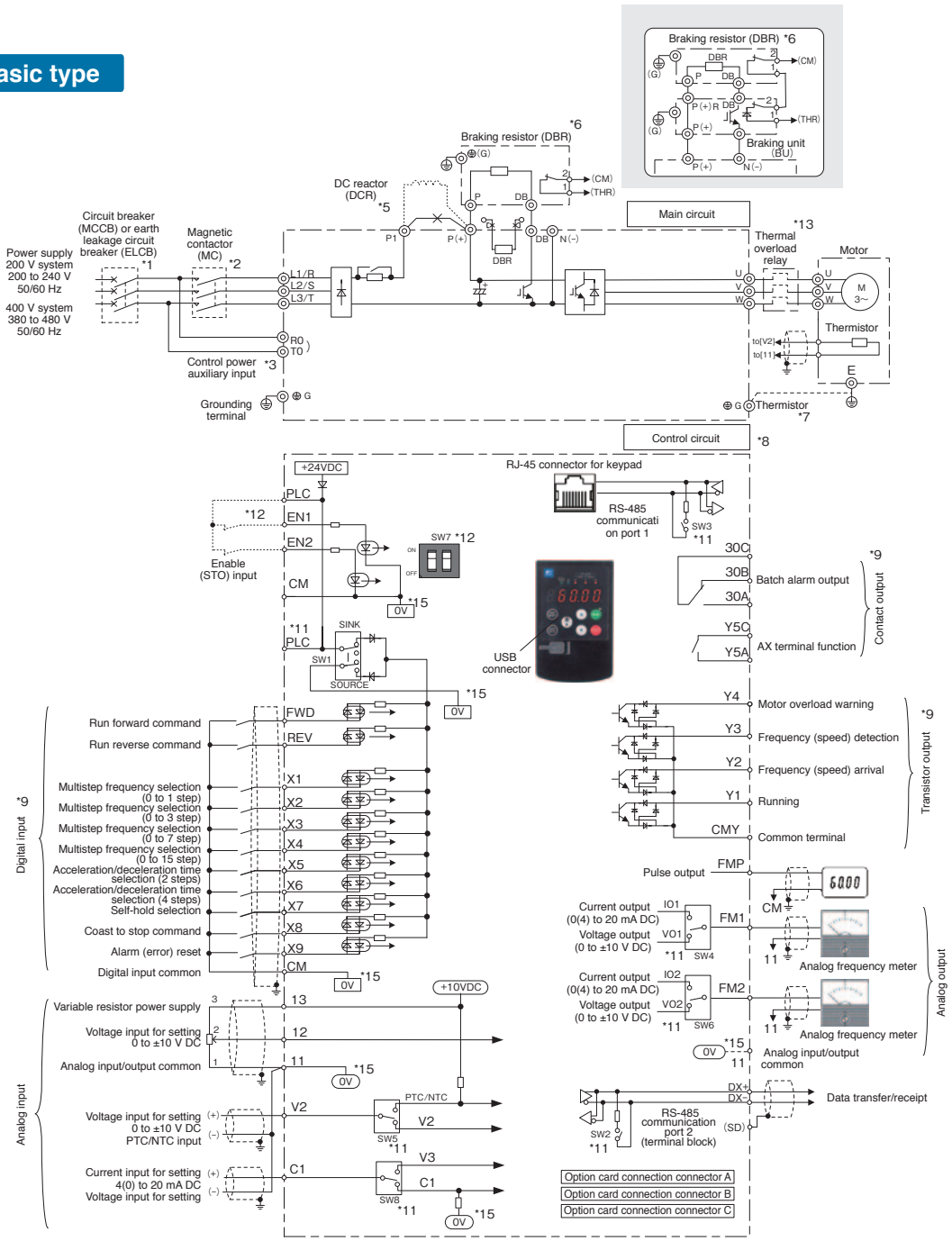
<table>
<tr><th>Class</th><th>Symbol</th><th>Terminal name</th><th>Explanation</th></tr>
<tr><td rowspan="2">Analog output</td><td rowspan="2">【FMP】</td><td>Pulse monitor
(FMP function)</td><td>This function outputs pulse signals. The content of the signal can be selected in the same way as the FM1/2 function by setting the function code F35.
* Connectable impedance: Minimum of 5 kΩ (up to two analog voltmeters (0 to 10 V DC, input impedance of 10 kΩ) can be connected.)
* Pulse duty: About 50%; Pulse rate: 25 to 6000 p/s (at full scale)
Pulse output waveform: 
FMP output circuit:  </td></tr>
<tr><td>Digital common</td><td>This is a common terminal for digital input signals and terminal [FMP] output.
The terminal is insulated from terminals [11] and [CMY]. This is the same terminal as terminal [CM] for digital input.</td></tr>
<tr><td rowspan="5">Transistor output</td><td>【Y1】</td><td>Transistor output 1</td><td rowspan="4">(1) Various signals (running signals, frequency arrival signals, overload early warning signals, etc.) set with function codes E20 to E24 can be output.
(2) The operating mode between transistor output terminals [Y1] and [Y4] and terminal [CMY] can be switched to "ON when signal output (active ON)" or "OFF when signal output (active OFF)".
<Transistor output circuit specifications>
Transistor output circuit
 
<table><tr><th colspan="2">Item</th><th>Max.</th></tr><tr><td rowspan="2">Operating voltage</td><td>ON level</td><td>2V</td></tr><tr><td>OFF level</td><td>48V</td></tr><tr><td colspan="2">Operating current when ON</td><td>50mA</td></tr><tr><td colspan="2">Leakage current when OFF</td><td>0.1mA</td></tr></table></td></tr>
<tr><td>【Y2】</td><td>Transistor output 2</td></tr>
<tr><td>【Y3】</td><td>Transistor output 3</td></tr>
<tr><td>【Y4】</td><td>Transistor output 4</td></tr>
<tr><td>【CMY】</td><td>Transistor output common</td><td>This is a common terminal for transistor output signals.
This terminal is isolated from terminals [CM] and [11].</td></tr>
<tr><td rowspan="2">Analog output</td><td>【Y5A】
【Y5C】</td><td>General-purpose relay output</td><td>(1) The same signals as those of terminals [Y1] to [Y4] can be selected and output as multi-purpose relay outputs.
Contact capacity: 250 VAC 0.3 A cosϕ = 0.3, 48 VDC 0.5 A
(2) It is possible to switch between a "short circuit between terminals [Y5A] and [Y5C] when an ON signal is output (excitation: active ON)" or an "open circuit between terminals [Y5A] and [Y5C] when an ON signal is output (non-excitation: active OFF)".</td></tr>
<tr><td>【30A】
【30B】
【30C】</td><td>Integrated alarm output</td><td>(1) When the inverter stops with an alarm, an integrated alarm is output at the relay contact (1C).
Contact capacity: 250 VAC 0.3 A cosϕ = 0.3, 48 VDC 0.5 A
(2) The same signals as those of terminals [Y1] to [Y4] can be selected and output.
(3) It is possible to switch between a "short circuit between terminals [30A] and [30C] when an ON signal is output (excitation: active ON)" or an "open circuit between terminals [30A] and [30C] when an ON signal is output (non-excitation: active OFF)".</td></tr>
<tr><td rowspan="3">Communication</td><td>【DX+】
【DX-】
【SD】</td><td>RS-485 COM port 2
(terminal block)</td><td>• This is an input/output terminal used to connect a personal computer or programmable controller, etc. by RS-485 communication.
• Use the recommended stick terminal when making a daisy chain connection.</td></tr>
<tr><td>RJ-45 connector
Keypad</td><td>RS-485 COM port 1
(for keypad connection)</td><td>(1) This is used as a connector for connecting the keypad. The keypad power is supplied from the inverter via an extension cable for remote operation.
(2) This is used to connect a personal computer or programmable controller, etc. by RS-485 communication after disconnecting the keypad.
Connector pin assignment
 
RJ-45 connector
 
RJ-45 connector
• Pins 1, 2, 7, and 8 are assigned as the keypad's power source.
• Do not use these pins when connecting the RJ-45 connector to other devices.</td></tr>
<tr><td>USB connector</td><td>USB port (on keypad)</td><td>• This is a USB connector (mini B) for connecting to a personal computer.
• Use the inverter support loader (FRENIC loader) to edit, transfer, and verify function codes, perform test operations for the inverter, and monitor various statuses.</td></tr>
</table>

* For details, refer to the FRENIC-MEGA (G2) User's Manual.

Basic Wiring Diagram

Wiring of main circuit terminal and grounding terminal

Basic type



*1 To protect the wiring, install the recommended molded case circuit breaker (MCCB), or residual-current-operated protective device (RCD)/earth leakage breaker (ELCB) (with overcurrent protection function) in the inverter primary circuit.

*2 If necessary, install a magnetic contactor (MC) in each inverter, and separate the inverter and power supply in addition to the MCCB or RCD/ELCB. If installing a coil such as an MC or solenoid near the inverter, connect a surge absorber in parallel.

*3 Prepare [R0] and [T0] terminals for 0004 type (400V class) and 0008 type (200V class) inverters with capacity of 1.5 kW or higher. Connect the terminals to the power supply line to retain alarm output signal ALM that occurs at the inverter programmable output terminal using a protective function, and to maintain keypad operation even if the main power supply is cut off.

*5 If connecting an optional DC reactor (DCR), remove the jumper bar from between terminals [P0] and [P1]. It is necessary to connect a DCR to LD specification inverters with capacity of 55kW, or 75 kW or higher. Be sure to connect to these inverters.

*6 A built-in braking resistor (DBR) is connected between terminals P(+) and DB on 7.5 kW or lower inverters. If connecting an external braking resistor (DBR), be sure to remove the built-in one.

*7 This terminal is used for grounding the motor. Use this terminal to ensure safety.

*8 Use twisted wire or shielded twisted wire for control signal lines. If using shielded twisted wire, connect the shields to a common terminal on the control circuit. To prevention malfunction due to noise, keep the control circuit wiring as far away from the main circuit wiring as possible (recommended distance: 10 cm or more). Never install the wiring in the same wiring duct. If crossing the control circuit wiring and main circuit wiring, set the angle.

*9 The connection diagram shows the factory default functions assigned to digital input terminals [X1] to [X9], [FWD], and [REV], transistor output terminals [Y1] to [Y4], relay contact output terminals [Y5A/C], and [30A/B/C].

*10 Changes the main circuit connector.

*11 These are control board slide switches. Inverter operation is customized using these switches.

*12 Set SW7 to the "ON" side if using the enable input (EN1, EN2) functions. Use approved, safe relay devices which conform to EN ISO 13849-1 PL-e and IEC/EN 61800-5-2 SIL3 for switching of the hardware circuit between terminals [EN1] and [EN2], and between terminals [EN2] and [PLC].

*13 Make the circuit breakers (MCCB) or the magnetic contactors (MC) trip by the thermal relay auxiliary contacts (manual recovery).

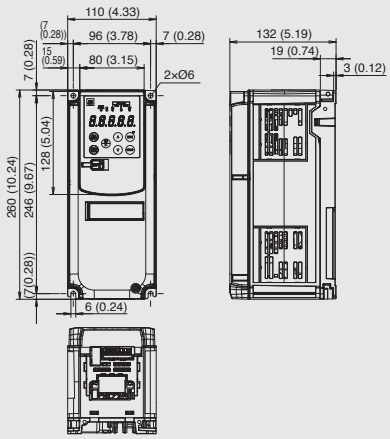
*15 0V and 0V are separated and insulated.

External Dimensions

Basic type | EMC Filter Built-in Type

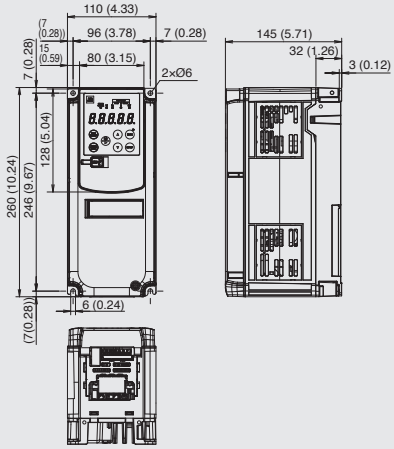
Type FRN0002G2□-2G, FRN0002G2□-4G

[Unit: mm (inch)]



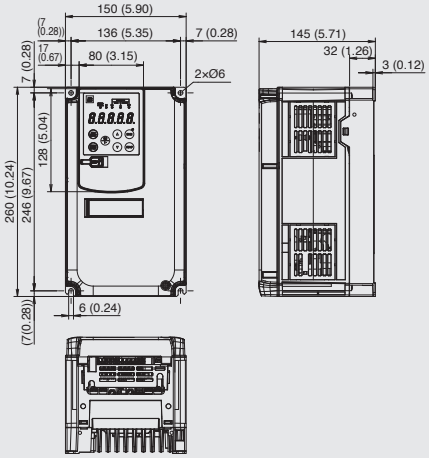
Type FRN0003G2□-2G, FRN0003G2□-4G

[Unit: mm (inch)]



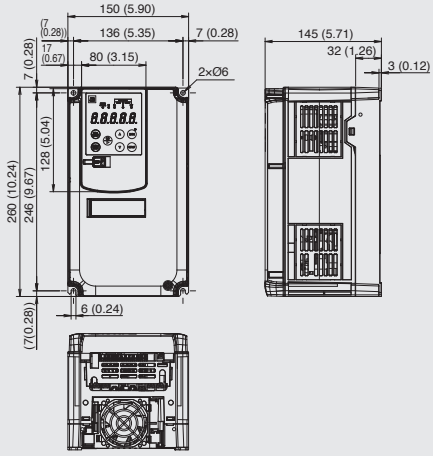
Type FRN0004G2□-2G, FRN0004G2□-4G

[Unit: mm (inch)]



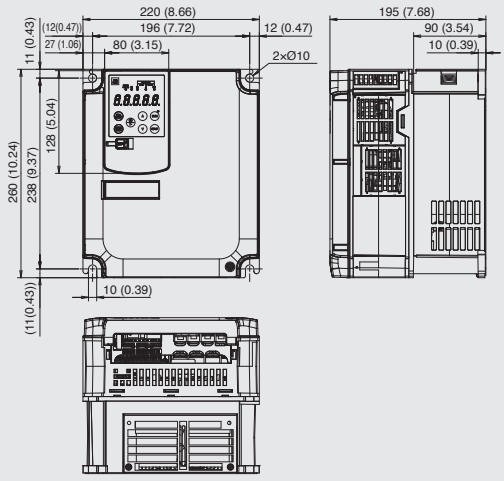
Type FRN0006G2□-2G to 3.7G2□-2G, FRN0006G2□-4G to 0006G2□-4G

[Unit: mm (inch)]



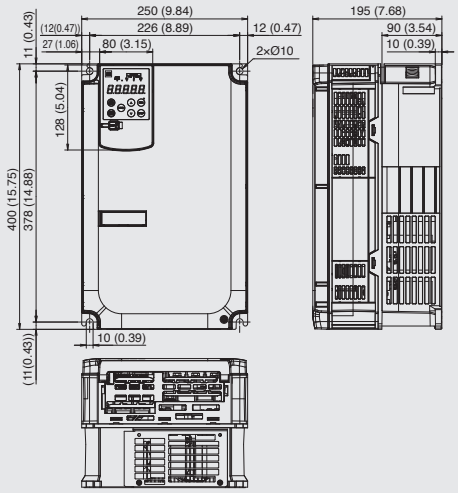
Type FRN0018G2□-2G to 0031G2□-2G, FRN0018G2□-4G to 0031G2□-4G

[Unit: mm (inch)]



Type FRN0038G2□-2G to 0060G2□-2G, FRN0038G2□-4G to 0060G2□-4G

[Unit: mm (inch)]

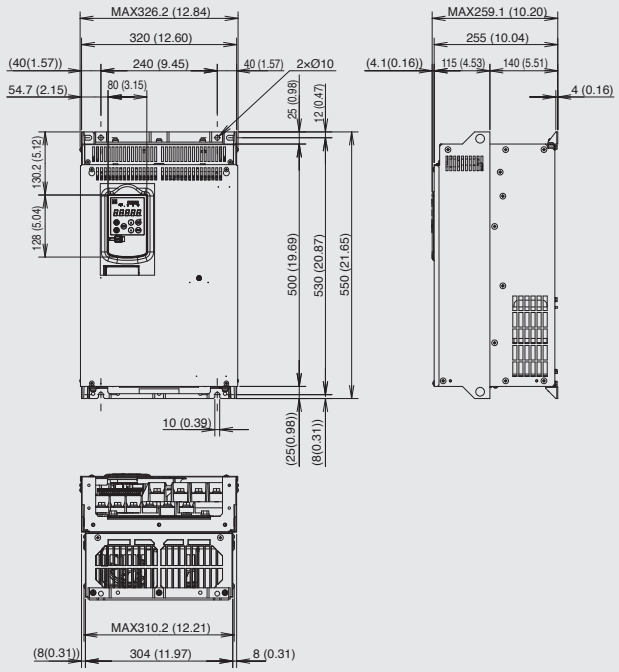


External Dimensions

Basic type **EMC Filter Built-in Type**

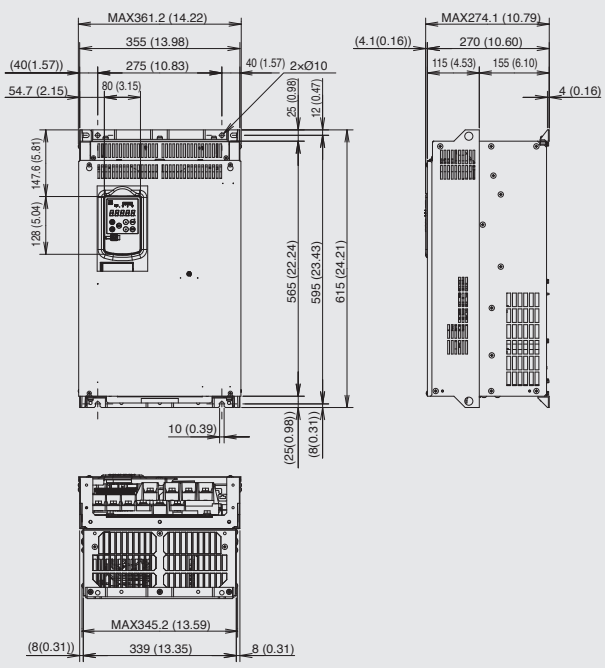
Type FRN0075G2□-2G, FRN0075G2□-4G, FRN0091G2□-4G

[Unit: mm (inch)]



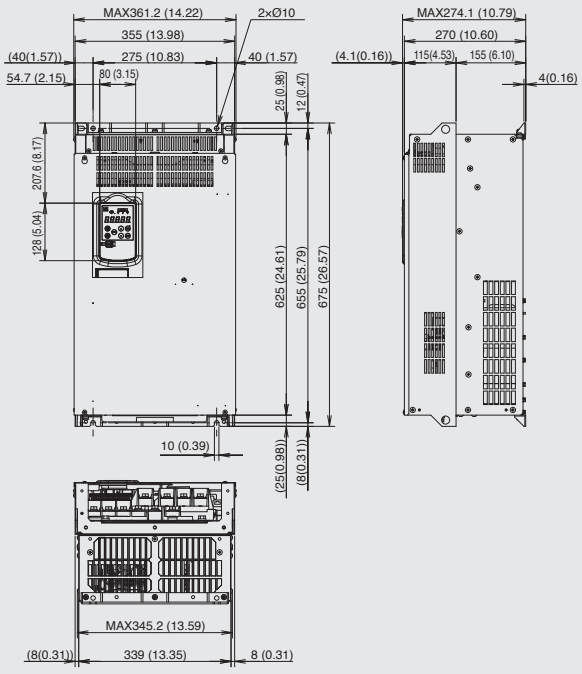
Type FRN0091G2□-2G, FRN0112G2□-4G

[Unit: mm (inch)]



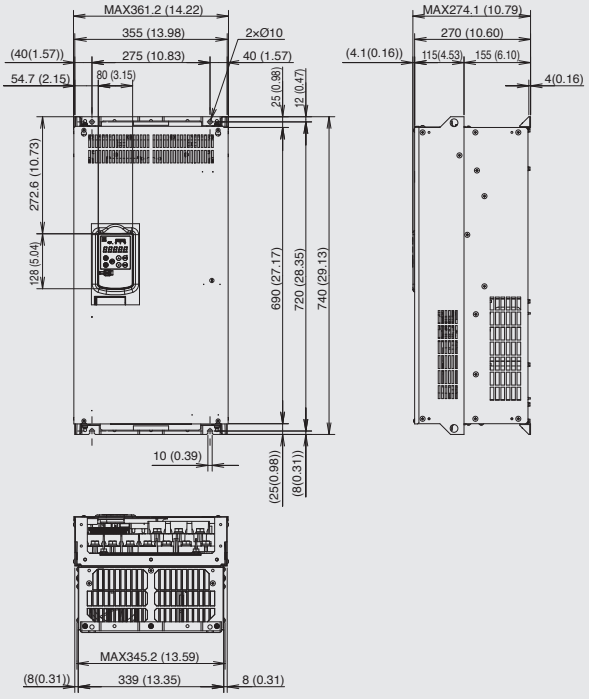
Type FRN0150G2□-4G

[Unit: mm (inch)]



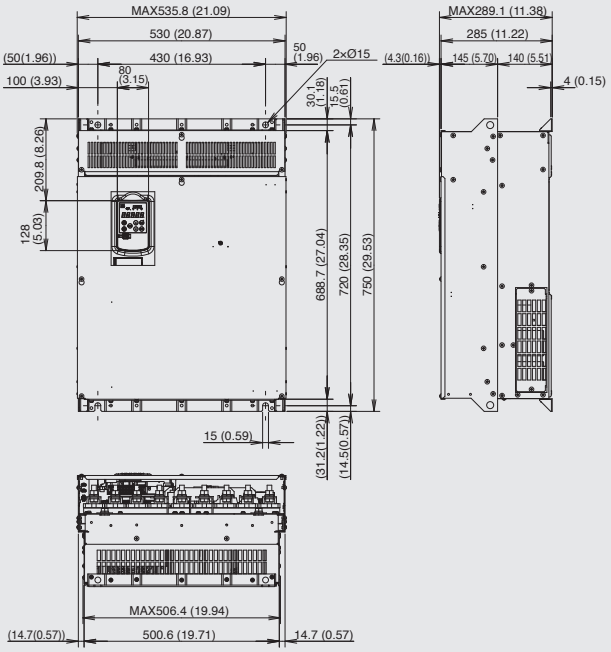
Type FRN0112G2□-2G, FRN0150G2□-2G, FRN0180G2□-4G

[Unit: mm (inch)]



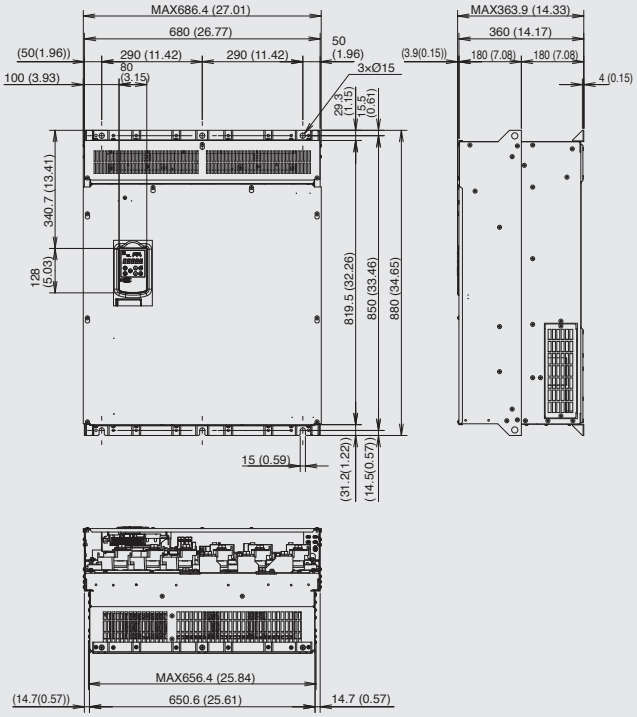
Type FRN0180G2□-2G

[Unit: mm (inch)]



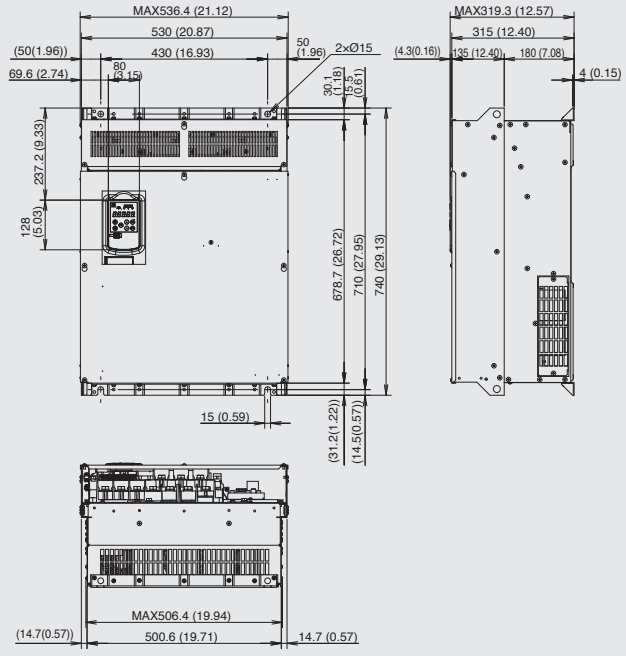
Type FRN0216G2□-2G

[Unit: mm (inch)]



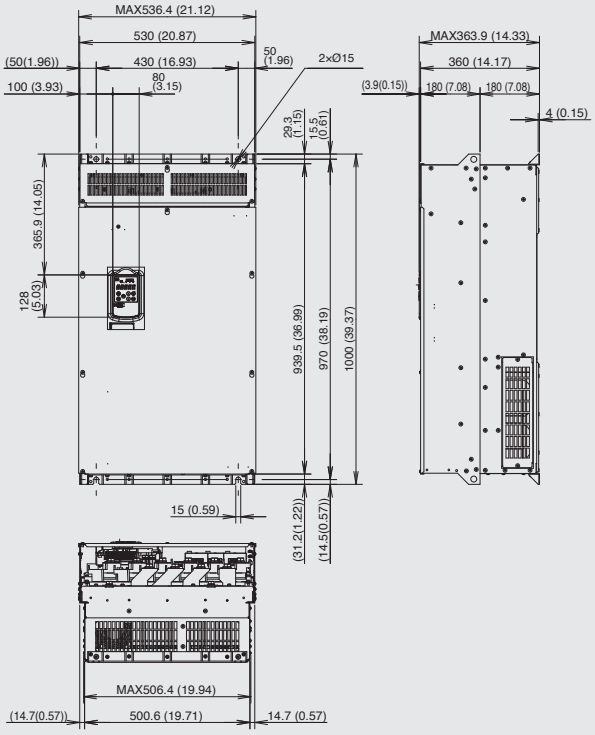
T ype FRN0216G2□-4G, FRN0260G2□-4G

[Unit: mm (inch)]



Type FRN0325G2□-4G, FRN0377G2□-4G

[Unit: mm (inch)]

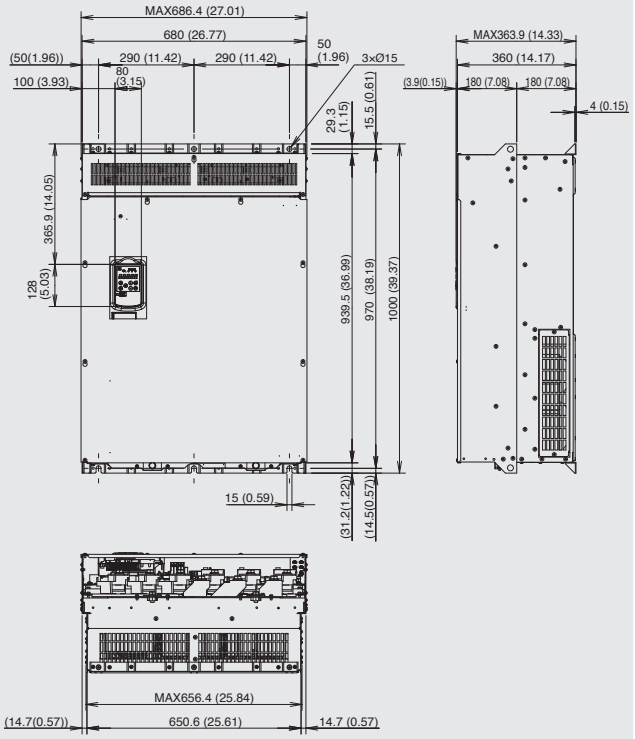


External Dimensions

Basic type **EMC Filter Built-in Type**

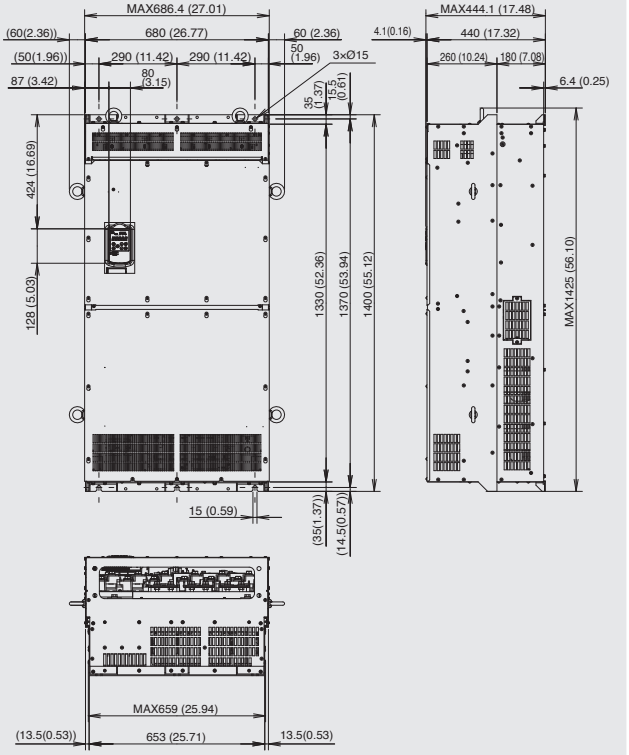
Type FRN0432G2□-4G, FRN0520G2□-4G

[Unit: mm (inch)]



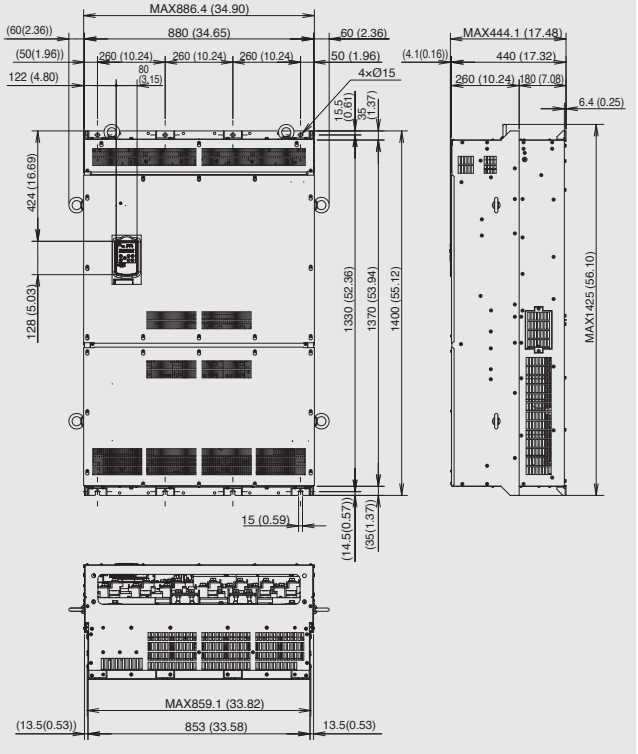
Type FRN0650G2□-4G, FRN0740G2□-4G

[Unit: mm (inch)]



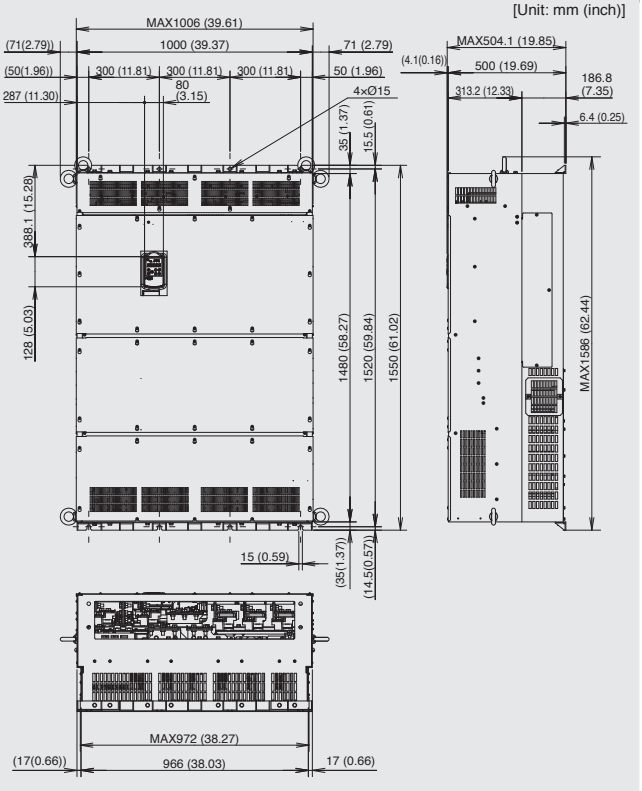
Type FRN0960G2□-4G, FRN1040G2□-4G

[Unit: mm (inch)]



Type FRN1170G2□-4G, FRN1386G2□-4G

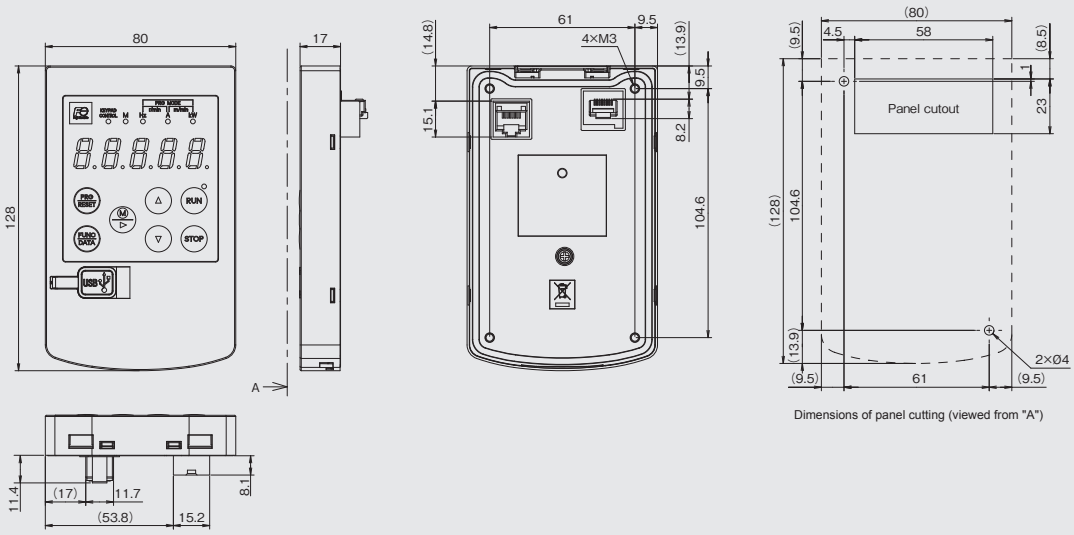
[Unit: mm (inch)]



Keypad

Standard (USB connector model) Type : TP-E2 Option

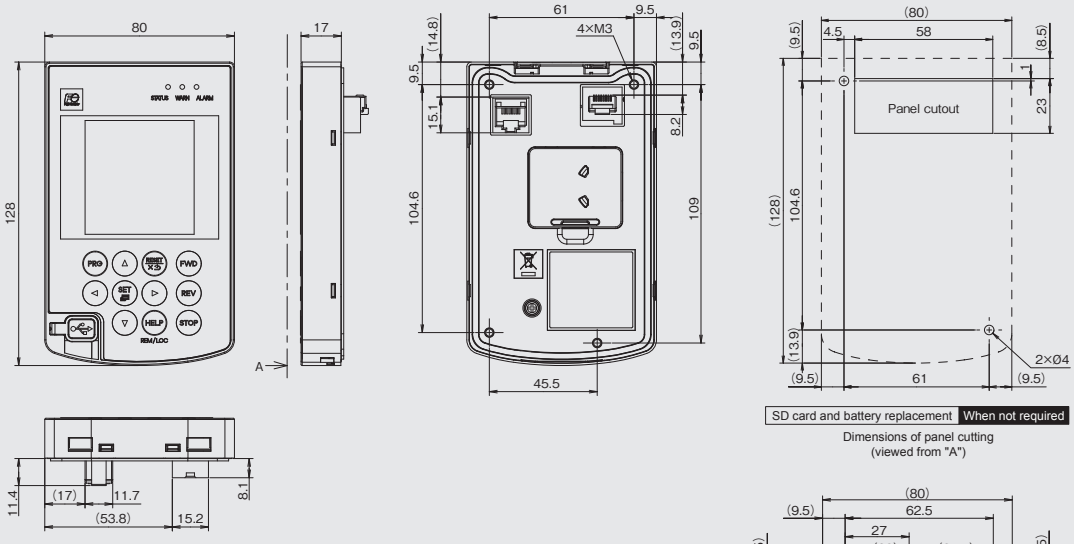
[Unit: mm]



Dimensions of panel cutting (viewed from "A")

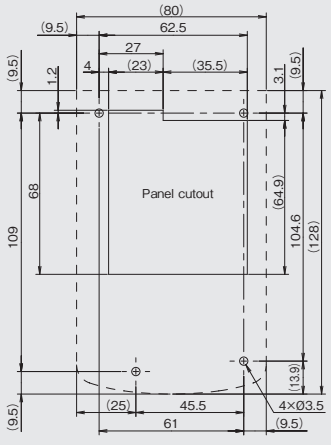
Multi-functional (USB connector model) Type : TP-A2SW Option

[Unit: mm]



SD card and battery replacement | When not required

Dimensions of panel cutting (viewed from "A")



SD card and battery replacement | When required

Dimensions of panel cutting (viewed from "A")

Keypad Functions

Use the keypad to start and stop the inverter, display various data, set function code data, check I/O, and display maintenance and alarm information.

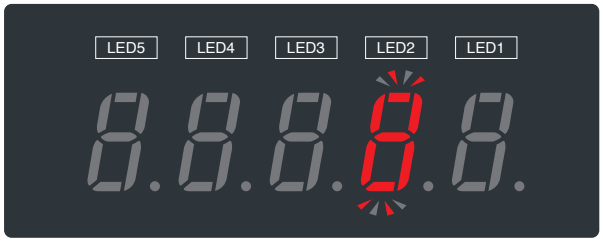
Overview of operation and functionality

Item	Display and keys	Overview of functionality
Data display	8.8.8.8.8.	This is a 5-digit, 7-segment LED monitor. It displays the following information for each operation mode. ■ Operation mode : Operation information (output frequency, output current, output voltage, etc.) Switches to status display when the operating state is other than normal. Switches to minor failure display when a minor failure occurs. ■ Program mode : Menu, function code, function code data, etc. ■ Alarm mode : Alarm code indicating the cause of the protection function's activation.
Key operation	PRG RESET	Switches the operation mode. ■ Operation mode : Pressing this key will switch it to program mode. ■ Program mode : Pressing this key will switch it to operation mode. ■ Alarm mode : After clearing the alarm cause, pressing this key will switch it to the operation mode deactivated by the alarm.
	FUNC DATA	Performs the following operations: ■ Operation mode : Switches the operation state monitoring items (output frequency, output current, output voltage, etc.). ■ Program mode : Displays function code or establishes the data. ■ Alarm mode : Switches the display of the alarm detailed information.
	RUN	Starts the motor operation. (When the keypad is being operated)
	STOP	Stops the motor operation. (When the keypad is being operated)
	▲ / ▼	Used to select the setting items displayed on the LED monitor or change the function code data.
	M	■ Operation mode : The functionality assigned by function code E70 is available. Press and hold for one second to turn the functionality ON or OFF. It is OFF by default when the power is turned on. ■ Program mode During menu display : Proceeds to the next menu number. During function code display : Advances the display number in steps of 10. During numerical setting : Moves the cursor digit to the right. ■ Alarm mode : Advances the alarm detailed information number in steps of 10.
LED display	RUN (Green)	Lights up when the " RUN " key is pressed or when operated by issuing the "FWD" or "REV" signal or communication commands.
	KEYPAD CONTROL (Green)	Lights up when the RUN key on the keypad is enabled as an operation command. However, in program mode or alarm mode, no operation is possible even if this LED is lit. It blinks every second in local mode.
	M (Blue)	Displays the selected signal with function code E71.
	Unit LEDs (three red LEDs)	Hz, A, kW, r/min, m/min: Displays the unit when monitoring the operating status in operation mode via a combination of three LEDs.
		PRG.MODE: Two LEDs on the left and right will light up when you transition to program mode. (●Hz ○A ●kW)
USB port	USB	The inverter can be connected to a computer via a USB cable. The inverter has a mini-B type connector.

Keypad Operation

LED monitor

In Running mode, the LED monitor displays running status information (output frequency, current or voltage); in Programming mode, it displays menus, function codes and their data; and in Alarm mode, it displays an alarm code which identifies the alarm factor that has activated the protective function.
If one of LED5 through LED1 is blinking, it means that the cursor is at this digit, allowing you to change it.



segment LED monitor (LED2 is blinking)

segment LED monitor display

Character	7-segment	Character	7-segment	Character	7-segment	Character	7-segment
0	0	9	9	I*	i or i	R	r
1	1	A	A	J	J	S	5
2	2	b	b	K	P	T*	t or t
3	3	C	C or c	L	L	U*	U or u
4	4	d	d	M	n	V*	U or u
5	5	E	E	N	n	W	W
6	6	F	F	O	0	X	H
7	7	G	G	P	P	Y	y
8	8	H	H	Q	q	Z	Z
Special characters and symbols (numbers with decimal point, minus and underscore)							
0. to 9.	0. to 9.	-	-	_	_	~	~
		[	[	]	]	%	%
		:	:	;	;	^	^

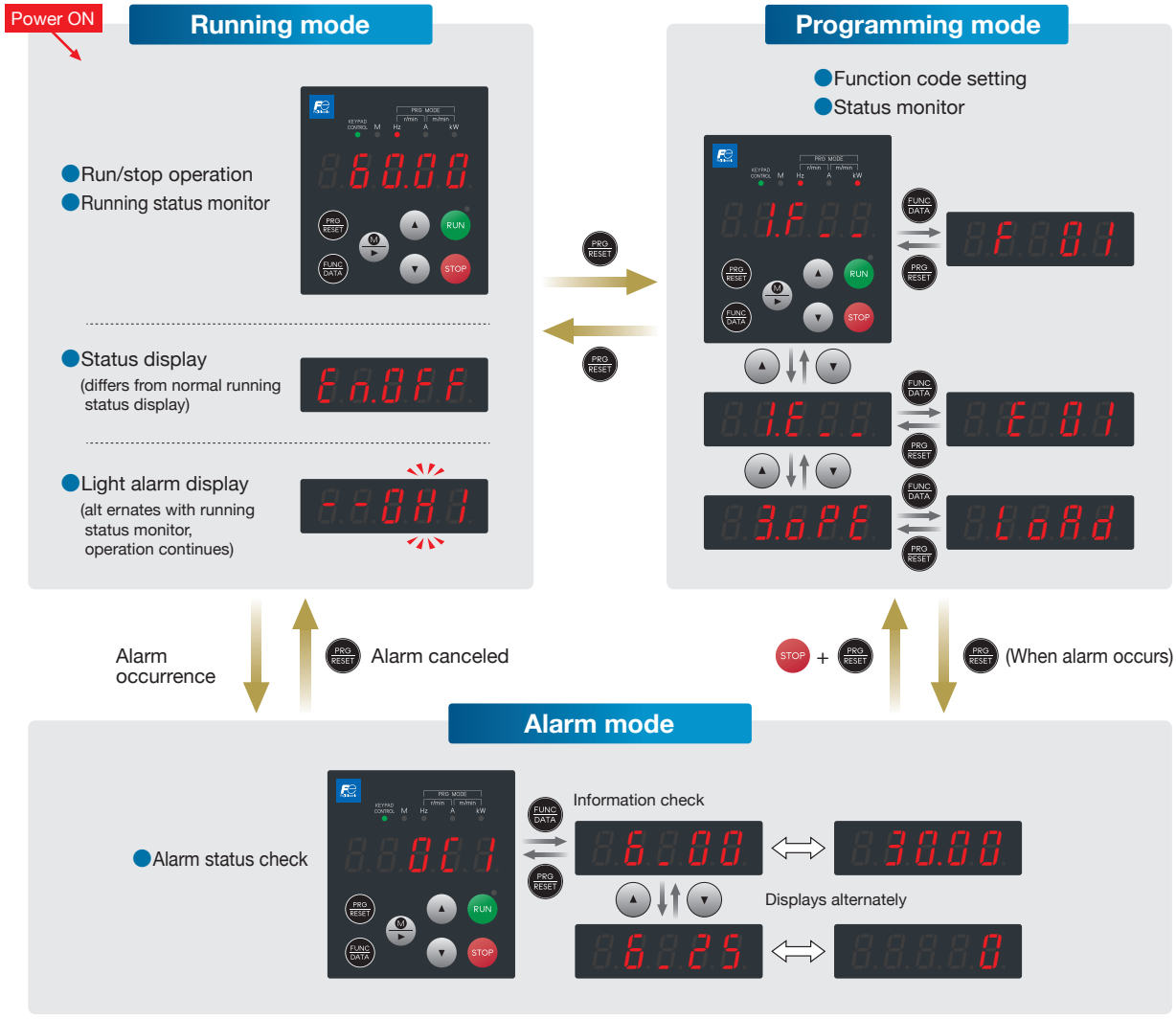
*: Upper case and lower case characters are used based on the displayed content.

Overview of Operation Modes

FRENIC-MEGA is equipped with the following three operation modes.

Operation mode	Description
Running Mode	•When powered ON, the inverter automatically enters this mode. •This mode allows you to specify the reference frequency, PID command value and etc., and run/stop the motor with the RUN / STOP keys. •The running status can also be monitored in real time. •Changes to the status display when not in the normal running status. •Changes to the light alarm display when a light alarm occurs.
Programming Mode	This mode allows you to configure function code data and check a variety of information relating to the inverter status and maintenance.
Alarm Mode	If an alarm condition arises, the inverter automatically enters Alarm mode in which you can view the corresponding alarm code* and its related information on the LED monitor. * Alarm code: Indicates the cause of the alarm condition.

Status transition between operation modes



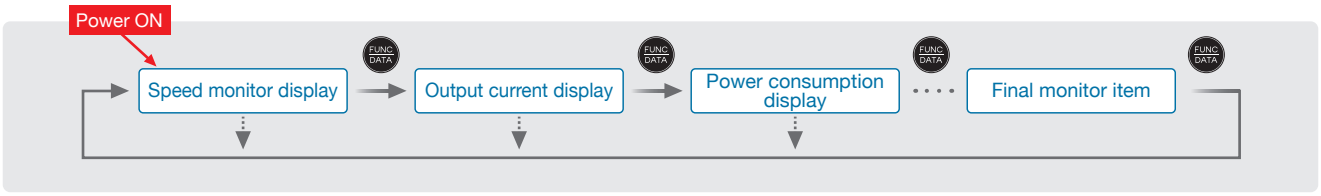
Tip Simultaneous keying

Simultaneous keying means pressing two keys at the same time.
The simultaneous keying operation is expressed by a "+" letter between the keys throughout this manual.
For example, the expression "STOP + PRG RESET keys" stands for pressing the STOP key with the PRG RESET key held down.

Running Mode

Operating State Monitor

In running mode, the items in Table 3.3-1 below can be monitored. The monitor items set with function code E43 are displayed immediately after turning the power on. Press the FUNC DATA key to switch between monitor items.



Tip By holding down the FUNC DATA key, the display returns to the speed monitor display.

Monitor items

●:ON ●:OFF

Monitor item	example	LED indication	Unit	Meaning of displayed value	Data for E43
Speed monitor	Function code E48 specifies what to be displayed on the LED monitor and LED indicators.				0
Output frequency 1 (before slip compensation)	50.00	●Hz ●A ●kW	Hz	Frequency actually being output	(E48=0)
Output frequency 2 (after slip compensation)	50.00	●Hz ●A ●kW	Hz	Frequency actually being output	(E48=1)
Frequency specified by frequency command whenalarm occurred	50.00	●Hz ●A ●kW	Hz	Indicated value = Reference frequency (Hz)	(E48=2)
Motor speed	1500	●Hz ●A ●kW	min^{-1}	Indicated value =Output frequency (Hz) × $\frac{120}{P01}$	(E48=3)
Load shaft speed	300.0	●Hz ●A ●kW	min^{-1}	Indicated value = Output frequency (Hz) × E50	(E48=4)
Line speed	300.0	●Hz ●A ●kW	m/min	Indicated value = Output frequency (Hz) × E50	(E48=5)
Constant feeding rate time	50	●Hz ●A ●kW	min	Indicated value = $\frac{E50}{\text{Output frequency (Hz)} \times E39}$	(E48=6)
Speed (%)	50.0	●Hz ●A ●kW	%	Indicated value = $\frac{\text{Output frequency (Hz)}}{\text{Max. frequency}} \times 100$	(E48=7)
Line speed (after acceleration/deceleration)	1800.	●Hz ●A ●kW	m/min	Line speed setting value after calculating acceleration/deceleration with d166 to d168 for line speed set with E48 = 5	(E48=8)
Line speed (after winding diameter compensation)	1800.	●Hz ●A ●kW	m/min	Roll frequency setting value compensated with winding diameter calculation result for line speed set with E48 = 5	(E48=9)
Output current when alarm occurred.	12.34	●Hz ●A ●kW	A	Current output from the inverter in RMS	3
Power consumption	10.25	●Hz ●A ●kW	kW	Input power to the inverter	9
Calculated torque *1	50	●Hz ●A ●kW	%	Motor output torque in % (Calculated value)	8
Output voltage *2	200U	●Hz ●A ●kW	V	Output voltage (RMS) of the inverter	4
Motor output *3	9.85	●Hz ●A ●kW	kW	Motor output (kW)	16
Load factor *4	50L	●Hz ●A ●kW	%	Load factor of the motor in % as the rated output being at 100%	15
PID output *5, *6	10.00.	●Hz ●A ●kW	-	PID command/feedback amount converted to a physical quantity of the object to be controlled (e.g. temperature) Refer to function codes J106 and J107 for details.	10
PID feedback value*5,*7	9.00.	●Hz ●A ●kW	-		12
PID deviation*5, *7	1.00.	●Hz ●A ●kW	-	PID command value and PID feedback value deviation converted into physical quantities of the object to be controlled	29
PID output *5, *6	100.0.	●Hz ●A ●kW	%	PID output in % as the maximum frequency (F03) being at 100%	14
Timer *10	50	●Hz ●A ●kW	s	Remaining time for timer operation	13
Analog input monitor *8	82.00	●Hz ●A ●kW	-	An analog input to the inverter in a format suitable for a desired scale. Refer to the following function codes. Terminal [12]: C59, C60 Terminal [C1] (C1 function): C65, C66 Terminal [C1] (V2 function): C71, C72	17
Command position*11	765 4321.	●Hz ●A ●kW	-	Alternate display of 4 higher order digits (with sign) and 4 lower order digits	21
Positioning deviation*11	765 4321.	●Hz ●A ●kW	-	Alternate display of 4 higher order digits (with sign) and 4 lower order digits	22

*1 Calculated torque 100% is equal to the motor rated torque. For the calculation formula of the motor rated torque, refer to E.2 "Calculated formula" (1) in Appendix E "Conversion from SI Units."
*2 If displaying the output voltage, is displayed as the last digit on the LED monitor to denote the unit for V (volts). *3 When the LED monitor displays the motor output, the unit LED indicator "kW" blinks.
*4 When the LED monitor displays the load factor, the 7-segment letter in the lowest digit stands for "%". *5 These PID related items appear only under the PID control specified by function code J01 (= 1, 2 or 3).
*6 When the LED monitor displays a PID command or its output amount, the dot (decimal point) attached to the lowest digit of the 7-segment letter blinks.
*7 When the LED monitor displays a PID feedback amount, the dot (decimal point) attached to the lowest digit of the 7-segment letter lights.
*8 The analog input monitor appears only when the analog input monitor function is assigned to one of the analog input terminals by one of function codes E61 to E63 (= 20). Specify the unit with C58, C64 and C70.
*9 Displays 0 (zero) under V/f control. *10 Displays (function code C21 = 3) only if performing timer operation. *11 Displays when the position control function is enabled.

Monitor items

●:ON ●:OFF

Monitor item	example	LED indication	Unit	Meaning of displayed value	Data for E43
Position control start position*11	765 4321.	●Hz ●A ●kW	-	Alternate display of 4 higher order digits (with sign) and 4 lower order digits (with sign) for position when run command ON or when POS-SET enabled with user value	27
Stop target position*11	765 4321.	●Hz ●A ●kW	-	Alternate display of 4 higher order digits (with sign) and 4 lower order digits (with sign) for stop target position with user value	28
Torque current *9	48	●Hz ●A ●kW	%	Torque current command value or calculated torque current	23
Magnetic flux command *9	50	●Hz ●A ●kW	%	Magnetic flux command value	24
Input watt-hour	100.0	●Hz ●A ●kW	kWh	Indicated value = Input watt-hour (kWh) / 100	25
Winding diameter*12	54321	●Hz ●A ●kW	mm	Winding diameter calculation result display for constant surface speed control	26
Torque bias	25	●Hz ●A ●kW	%	Torque bias value display	30
Estimated inertia acceleration/ deceleration time conversion value	1.234	●Hz ●A ●kW	s	Display of estimated inertia result in logic acceleration/deceleration time	31
Customizable logic output*13	82.00	●Hz ●A ●kW	-	Display of output content for specific customizable logic step See function codes U98, U99.	32

*9 Displays 0 (zero) under V/f control.
*11 Displays when the position control function is enabled.
*12 Displays only if constant surface speed control is enabled with d41 = 1.
*13 Displays only if U00 = 1 and U98 0.

Tip The monitoring signals for the monitor items such as keypad output frequency and output current can be filtered with function code E42 (LED display filter). If the display varies unstably so as to be hard to read due to load fluctuation or other causes, increase this filter time constant. (Function code E42)

Programming Mode

The Programming mode provides you with the following functions--setting and checking function code data, monitoring maintenance information and checking input/output (I/O) signal status. The functions can be easily selected with the menu-driven system. Table 3.4-1 below lists menus available in Programming mode. The leftmost digit (numerals) of each letter string on the LED monitor indicates the corresponding menu number and the remaining digits indicate the menu contents.
When the inverter enters Programming mode from the second time on, the menu selected last in Programming mode will be displayed.

Menus available in programming mode

Menu #	Menu	LED monitor indication	Main function	
1	"Data Setting"	1.F_ _	F codes (Basic functions)	Function codes can be displayed and changed.
		1.E_ _	E codes (Extension terminal functions)	
		1.C_ _	C codes (Control functions)	
		~ (Omitted) ~		
		1.o_ _	o codes (optional functions)	
2	"Data Checking"	2.rEP	Displays only function codes that have been changed from their factory defaults. The function code data can be referenced and changed.	
3	Run monitor	3.oPE	Displays the running information required for maintenance or test runs.	
4	I/O check	4.I/O	Displays external interface information.	
5	"Maintenance Information"	5.CHE	Displays maintenance information including cumulative run time.	
6	Alarm Information	6.AL	Alarm codes for the past four alarms can be displayed, and operating information at the time each alarm occurred can be referenced.	
7	Data copy	7.CPY	Function code data can be read, written, and verified.	
8	Destination setting	8.dEST	Sets the region (overseas) in which the product is used. This is not used for machines for use in Japan.	
9	Communication monitor	9.S_ _ 9.Addr 9.dAtA	Codes communicated back and forth between the host device can be monitored, and communication commands can be entered. Refer to the "RS-485 Communication User's Manual" for details.	
0	Favorites	0.FnC	Only function codes selected by users can be referenced or changed.	

Tip Enter Programming mode at the keypad to display the menu. Change the menu with the ▲ and ▼ keys, and select the desired menu item with the FUNC DATA key. Once the entire menu has been cycled through, the display returns to the first menu item. Press the ▶ key to proceed to the next menu number.

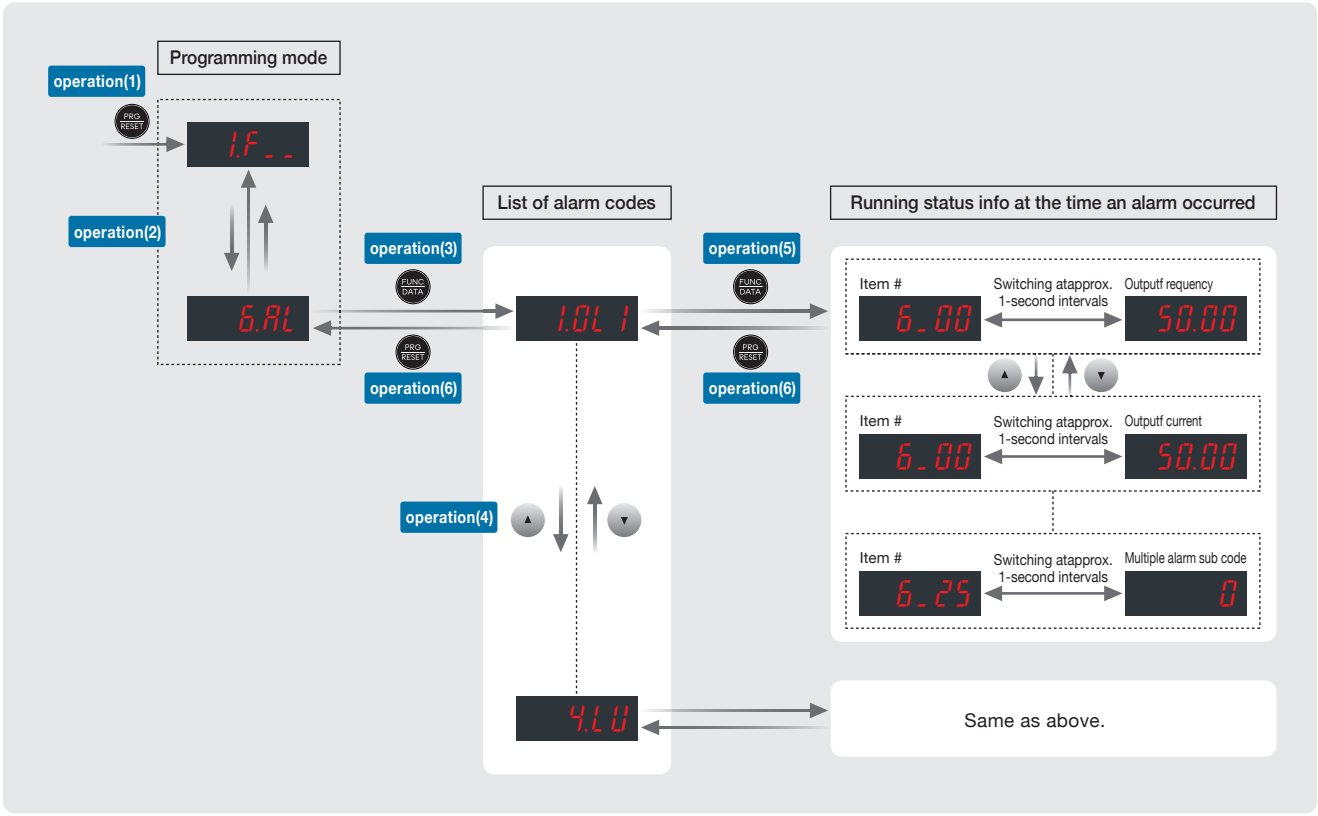
Programming Mode

Reading alarm information

Alarm Information 6.AL

Menu number 6 “Alarm Information: 6.AL ” shows the causes of the past 4 alarms with an alarm code. Further, it is also possible to display alarm information that indicates the status of the inverter when the alarm occurred. “Alarm Information” menu transition”. The menu transition ” is shown in “Alarm Information” display content.

“Alarm Information” menu transition



Basic key operation

operation(1) Turn the inverter ON. It automatically enters Running mode in which you press the PRG RESET key to switch to Programming mode. The function selection menu appears.

operation(2) Use the ▲ or ▼ key to display “Alarm Information” (6.AL).
Press the M key to skip in menu number units.

operation(3) Press the FUNC DATA key to proceed to the list of alarm codes (e.g., 1.0L 1).
In the list of alarm codes, the alarm information for the last 4 alarms is saved as an alarm history.

operation(4) Each time the ▲ or ▼ key is pressed, the last 4 alarms are displayed beginning with the most recent one in the order “ 1. ”, “ 2. ”, “ 3. ”, “ 4. ”.
By pressing the M key, the display returns to the latest alarm history.

operation(5) Press the FUNC DATA key with an alarm code being displayed.
The monitor number (e.g. 6_00) and the inverter status information (e.g. Output frequency) at the time of the alarm occurrence alternately appear at approx. 1-second intervals. Pressing the ▲ / ▼ keys displays other monitor numbers (e.g., 6_01) and the status information (e.g., Output current) for that alarm code.
By pressing the FUNC DATA key at this time, the display can be switched between the monitor number and symbol.

operation(6) Press the PRG RESET key to return to the list of alarm codes. Press the PRG RESET key again to return to the menu.

"Alarm Information" display content

Monitor No.	Symbol	Displayed content	Description
6_00	FoutA	Output frequency	Output frequency before slip compensation when alarm occurred
6_01	IoutA	Output current when alarm occurred.	Output current when alarm occurred. Unit: A (amperes)
6_02	UoutA	Output voltage when alarm occurred	Output voltage when alarm occurred Unit: V (volts)
6_03	trqA	Calculated motor output torque when alarm occurred	Calculated motor output torque when alarm occurred
6_04	FrEF	Frequency specified by frequency command when alarm occurred	Frequency specified by frequency command when alarm occurred
6_05	rotA	Rotation direction	Displays the current rotation direction when alarm occurred. F: forward, :r reverse, _ _ _ _ _: stop
6_06	StAtA	Running status	Running status in 4-digit hexadecimal format Refer to "Displaying running status (3_07 and running status 2 (3_23 " in "3.4.3 Monitoring the running status "Drive Monitoring: 3.oPE " on page 3-23 for details.
6_07	tIME	Cumulative run time	Displays the content of the cumulative power-ON time counter of the inverter when alarm occurred. Counter range: 0 to 65,535 hours Display range: 0 to 65535 When the count exceeds 65,535, the counter will be reset to "0" and start over again.
6_08	no.St	Number of startups	Displays the content of the motor startup counter (i.e., the number of run commands issued) when alarm occurred. Counter range: 0 to 65,535 times Display range: 0 to 65535 When the count exceeds 65,535, the counter will be reset to "0" and start over again.
6_09	Edc	DC link bus voltage	Displays the DC link bus voltage of the inverter main circuit. Unit: V (volts)
6_10	t-inA	Temperature inside the inverter	Displays the temperature of the inverter heat sink when alarm occurred. Unit: °C
6_11	t-finA	Max. temperature of heat sink	Displays the temperature of the inverter heat sink when alarm occurred. Unit: °C
6_12	diA	Terminal I/O signal status (displayed with ON/OFF of LED segments)	Refer to "Table 3.4-9 Display of I/O signal status with ON/OFF of each LED segment" and "Table 3.4-10 Display of I/O signal status in hexadecimal notation (example)" in "3.4.4 Checking I/O signal status "I/O Checking: 4.1_o"
6_13	di-H	Terminal input signal status □ (in hexadecimal)	
6_14	do-H	Terminal output signal status □ (in hexadecimal)	
6_15	no.AL	No. of consecutive occurrences	Shows how many times the same alarm has occurred consecutively.
6_16	o.LAP1	Multiple alarm 1	Simultaneously occurring alarm code (1) ("- - - -" is displayed if no alarm has occurred.)
6_17	o.LAP2	Multiple alarm 2	Simultaneously occurring alarm code (2) ("- - - -" is displayed if no alarm has occurred.)
6_18	diA.L	Terminal I/O signal status under communications control (displayed with the ON/OFF of LED segments)	Displays the ON/OFF state of the digital I/O terminals under RS-485 communications control when alarm occurred. Refer to "Displaying control I/O signal terminals under communications control" in "3.4.4 Checking I/O signal status "I/O Checking: 4.1_o" for the display content.
6_19	di.L-H	Terminal input signal status under communications control (in hexadecimal)	
6_20	do.L-H	Terminal output signal status under communications control (in hexadecimal)	
6_21	Sub	Error sub code	Secondary error code for an alarm.
6_22	StAt2	Running status 2	Displays running status 2 in 5-digit hexadecimal format. Refer to "Table 3.4-4 Running status 2 (3.23) bit assignment" in "3.4.3 Monitoring the running status "Drive Monitoring: 3.oPE" for details.
6_23	SPEEd	Detected value	Displays the detected speed value when alarm occurred.
6_24	StAt3	Running status 3	Displays running status 3 in 5-digit hexadecimal format. Refer to "Table 3.4-15 Running Status 3 (6.24) bit assignment " below for details.
6_25	Sub.o1	Multiple alarm sub code	Secondary error code for a multiple alarm

Alarm Mode

If an abnormal condition arises, the protective function is invoked and issues an alarm, then the inverter automatically enters Alarm mode. At the same time, an alarm code appears on the LED monitor.

Releasing the alarm and switching to Running mode

Remove the cause of the alarm and press the PRG/RESET key to release the alarm and return to Running mode. The alarm can be removed using the PRG/RESET key only when the alarm code is displayed.

Displaying the alarm history

It is possible to display the most recent 3 alarm codes in addition to the one currently displayed. Previous alarm codes can be displayed by pressing the ▲ / ▼ key while the current alarm code is displayed.

Displaying the status of inverter at the time of alarm

When the alarm code is displayed, you may check various running status information when the alarm occurred (output frequency and output current, etc.) by pressing the FUNC/DATA key. The monitor item number and data for each running status information will be displayed alternately.
Further, you can view various information items on the running status of the inverter using the ▲ / ▼ key. The information displayed is the same as for menu number 6 "Alarm Information" in Programming mode. Refer to Table 3.4-14 in "3.4.6 Reading alarm information "Alarm Information: 6.8L"
Pressing the PRG/RESET key while the running status information is displayed returns to the alarm code display.

When the running status information is displayed after removal of the alarm cause, pressing the PRG/RESET key twice returns to the alarm code display and releases the inverter from the alarm state. This means that the motor starts running if a run command has been received by this time.

Switching to Programming mode

You can also switch to Programming mode by pressing "STOP + PRG/RESET keys" simultaneously with the alarm displayed, and modify the function code data.

Function Codes

Drive control

The FRENIC-MEGA runs under any of the following control methods. Some function codes apply exclusively to the specific control method.
The enable or disable status is indicated with an icon for each control method within the permissible setting range field in the function code list table.

Icon example: Under V/f control Enable: V/f Disable: V/f

Function code table permissible setting range field	Control target (H18)	Control method (F42)
V/f	Speed (H18=0)	V/f control Dynamic torque vector control (F42=1) V/f control with slip compensation (F42=2)
PGV/f		V/f control with speed sensor (F42=3) Dynamic torque vector control with speed sensor (F42=4)
SLV		Sensorless vector control (F42=5)
PGV		Vector control with speed sensor (F42=6)
PM SLV		Sensorless vector control (synchronous motors) (F42=15)
PM PGV		Vector control with sensor (synchronous motors) (F42=16)
TRQ	Torque (H18=2, 3)	Vector control (F42=5,6,16)

For details on the control method, refer to "Function code F42".
Note) The FRENIC-MEGA is a general-purpose inverter whose operation is customized by frequency-basis function codes, like conventional inverters. Under the speed-basis drive control, however, the control target is a motor speed, not a frequency, so convert the frequency to the motor speed according to the following expression.

Conversion formula Motor speed (r/min) = 120 x frequency (Hz)/number of poles

F codes :Fundamental functions

Function code	Name	Control method and Data setting range	Change when running	Data copying
F00	Data protection	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: No data protection, no digital setting protection 1: With data protection, no digital setting protection 2: No data protection, with digital setting protection 3: With data protection, with digital setting protection	Y	Y
F01	Frequency setting 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Keypad key operation (▲ / ▼ keys) 1: Analog voltage input (Terminal [12]) (from 0 to ±10 VDC) 2: Analog current input (Terminal [C1] (4 to 20 mA DC) 3: Analog voltage input (Terminal [12]) + analog current input (Terminal [C1]) 5: Analog voltage input (Terminal [V2]) (from 0 to ±10 VDC) 6: Analog voltage input (Terminal [V3]) (from 0 to ±10 VDC) 7: UP/DOWN control 8: Keypad key operation (▲ / ▼ keys) (with balanceless bumpless) 10: Pattern operation 11: Digital input interface card OPC-DI (option) 12: Pulse train input	N	Y
F02	Operation method	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Keypad operation (Rotation direction input: terminal block) 1: External signal (digital input) 2: Keypad operation (forward rotation) 3: Keypad operation (reverse rotation)	N	Y
F03	Maximum output frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5.0 to 599.0 Hz	N	Y
F04	Base frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5.0 to 599.0 Hz	N	Y
F05	Rated voltage at base frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: AVR disable (output voltage proportional to power voltage) 80 to 240 V: AVR operation (200V series) 160 to 500 V: AVR operation (400 V series)	N	Y2
F06	Maximum output voltage 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 80 to 240 V: AVR operation (200V series) 160 to 500 V: AVR operation (400 V series)	N	Y2
F07	Acceleration time 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ	Y	Y
F08	Deceleration time 1	0.00 to 6000s * 0.00 is for acceleration and deceleration time cancel (when performing soft-start and stop externally)	Y	Y
F09	Torque boost 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 20.0% (% value against base frequency voltage 1)	Y	Y
F10	Electronic thermal overload protection for motor 1 (Select motor characteristics)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 1: Enable (for a general-purpose motor with self-cooling fan) 2: Enable (for an inverter-driven motor with separately powered cooling fan)	Y	Y
F11	(Operation level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 A (disable), current value of 1 to 135% of inverter rated current set with A unit (Inverter rated current dependent on F80)	Y	Y1 Y2
F12	(Thermal time constant)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.5 to 75.0min	Y	Y
F14	Restart mode after momentary power failure (operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Trip immediately 1: Trip after a recovery from power failure 2: Trip after momentary deceleration is stopped 3: Continue to run (for heavy inertia load or general load) 4: Restart from frequency at power failure (for general load) 5: Restart from starting frequency	Y	Y
F15	Frequency limiter (upper limit)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
F16	(Lower limit)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
F18	Bias (for frequency setting 1)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -100.00 to 100.00%	Y*	Y
F20	DC braking 1 (starting frequency)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 60.0Hz	Y	Y

*2 A standard value is set for each capacity. *3 The rated current of the motor is set. For details, refer to the FRENIC-MEGA (G2) User's Manual.
*10 6.00 s for 22 kW or less, and 20.00 s for 30 kW or more. *11 5.0 min. for 22 kW or less, and 10.0 min. for 30 kW or more.

Function code	Name	Control method and Data setting range	Change when running	Data copying
F21	DC braking 1 (Operation level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 100% (HHD specification), 0 to 80% (HND specification),	Y	Y
F22	(Braking time)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 (disable): 0.01 to 30.00 s	Y	Y
F23	Starting frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 60.0 Hz If F42 = 5 or 15, 1.0 Hz is automatically set.	Y	Y
F24	(Holding time)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 10.00s	Y	Y
F25	Stop frequency	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 60.0Hz	Y	Y
F26	Motor sound (Carrier frequency)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.75 to 16kHz (HHD specification: 0.4 to 55 kW, HND specification: 5.5 to 18.5 kW) 0.75 to 10kHz (HHD specification: 75 to 630 kW, HND specification: 22 to 55 kW) 0.75 to 6kHz (HND specification: 75 to 630 kW)	Y	Y
F27	(Tone)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Level 0 (disable) 1: Level 1 2: Level 2 3: Level 3	Y	Y
F29	Terminal [FM1] (Operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Voltage output (0 to +10 VDC) 1: Current output (4 to 20 mA DC) 2: Current output (0 to 20 mA DC) 4: Voltage output (0 to +10 VDC)	Y	Y
F30	(Output gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 300%	Y*	Y
F31	(Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Output frequency 1 (before slip compensation) 1: Output frequency 2 (after slip compensation) 2: Output current 3: Output voltage when alarm occurred 4: Output torque 5: Load factor 6: Power consumption 7: PID feedback value 8: Actual speed/estimated speed 9: DC link bus voltage 10: Universal AO 11: Analog output test (-) 13: Motor output 14: Calibration (+) 15: PID command (SV) 16: PID output (MV) 17: Master-follower angle deviation 18: Inverter cooling fin temperature 21: PG feedback value 22: Torque current command 23: PID deviation 24: Line speed command 25: Winding diameter calculation value 26: Setting frequency (before acceleration/deceleration calculation) 111 to 124: Customizable logic output signal 1 to 14	Y	Y
F32	Terminal [FM2] (Operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Voltage output (0 to +10 VDC) 1: Current output (4 to 20 mA DC) 2: Current output (0 to 20 mA DC) 4: Voltage output (0 to +10 VDC)	Y	Y
F33	Terminal [FMP] (Pulse rate)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 25 to 6000 p/s (number of pulse at 100%)	Y*	Y
F34	(Output gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0,1 to 300% 0: Pulse output 1 to 300%	Y*	Y

F codes :Fundamental functions

Function code	Name	Control method and Data setting range	Change when running	Data copying
F35	Terminal [FMP] (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Output frequency 1 (before slip compensation) 1: Output frequency 2 (after slip compensation) 2: Output current 3: Output voltage when alarm occurred 4: Output torque 5: Load factor 6: Power consumption 7: PID feedback value 8: Actual speed/estimated speed 9: DC link bus voltage 10: Universal AO 11: Analog output test (-) 13: Motor output 14: Calibration (+) 15: PID command (SV) 16: PID output (MV) 17: Master-follower angle deviation 18: Inverter cooling fin temperature 21: PG feedback value 22: Torque current command 23: PID deviation 24: Line speed command 25: Winding diameter calculation value 26: Setting frequency (before acceleration/deceleration calculation) 111 to 124 Customizable logic output signal 1 to 14	Y	Y
F37	Load selection/ Auto torque boost/ Auto energy-saving operation 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Quadratic-torque load 1: Constant torque load 2: Auto torque boost 3: Auto energy-saving operation (quadratic-torque load) 4: Auto energy-saving operation (constant torque load) 5: Auto energy-saving operation with auto torque boost	N	Y
F38	Stop frequency(detection mode)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Speed detection value / estimated speed 1: Reference speed	N	Y
F39	(Holding time)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 10.00s	Y	Y
F40	Drive control selection 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 10.00 s	Y	Y
F41	Torque limiter 1-2	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -300 to 0 to 300% ; 999 (Disable)	Y	Y
F42	Drive control selection 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: V/f control without slip compensation 1: Dynamic torque vector control 2: V/f control with slip compensation 3: V/f control with speed sensor 4: Dynamic torque vector control with sensor 5: Sensorless vector control 6: Vector control with speed sensor 15: Sensorless vector control (synchronous motors) 16: Vector control with sensor (synchronous motors)	N	Y
F43	Current limiter (mode selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Disable 1: Enable at constant speed (disable during ACC/DEC) 2: Enable during ACC/constant speed operation (disable during DEC)	Y	Y
F44	(Operation level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 20 to 200% (rated current of the inverter for 100%)	Y	Y
F50	Electronic thermal overload (for braking resistor protection) (discharging capacity)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 (If using built-in breaking resistor) 1 to 9000 kWs OFF (cancel)	Y	Y1 Y2
F51	(Permissible average loss)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.001 to 99.99kW	Y	Y1 Y2
F52	(Braking resistance value)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 999Ω	Y	Y1 Y2

*12 180% for 15 kW or less, and 160% for 22 kW or more. *13 0 for 7.5 kW or less, and OFF for 11 kW or more.

Function code	Name	Control method and Data setting range	Change when running	Data copying
F58	Terminal [FM1] (Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
F59	(Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -100.0 to 100.0%	Y*	Y
F60	Terminal [FM2] (Output gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 300%	Y*	Y
F61	(Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Output frequency 1 (before slip compensation) 1: Output frequency 2 (after slip compensation) 2: Output current 3: Output voltage when alarm occurred 4: Output torque 5: Load factor 6: Power consumption 7: PID feedback value 8: Actual speed/estimated speed 9: DC link bus voltage 10: Universal AO 11: Analog output test (-) 13: Motor output 14: Calibration (+) 15: PID command (SV) 16: PID output (MV) 17: Master-follower angle deviation 18: Inverter heat sink temperature 21: PG feedback value 22: Torque current command 23: PID deviation 24: Line speed command 25: Winding diameter calculation value 26: Setting frequency (before acceleration/deceleration calculation) 111 to 124 Customizable logic output signal 1 to 14	Y	Y
F62	(Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
F63	(Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -100.0 to 100.0%	Y*	Y
F64	Terminal [FMP] (Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
F80	HHD/HND switching	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: HHD specification 1: HND specification	N	Y

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E01	Terminal [X1] (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 (1000): Multistep frequency selection (0 to 1 steps) 『SS1』	N	Y
E02	Terminal [X2]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 1 (1001): Select multistep frequency (0 to 3 steps) 『SS2』	N	Y
E03	Terminal [X3]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 2 (1002): Select multistep frequency (0 to 7 steps) 『SS4』	N	Y
E04	Terminal [X4]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 3 (1003): Select multistep frequency (0 to 15 steps) 『SS8』	N	Y
E05	Terminal [X5]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 4 (1004): Select ACC/DEC time (2 steps) 『RT1』	N	Y
E06	Terminal [X6]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5 (1005): Select ACC/DEC time (4 steps) 『RT2』	N	Y
E07	Terminal [X7]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 6 (1006): Select 3-wire operation 『HLD』	N	Y
E08	Terminal [X8]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 7 (1007): Coast to a stop command 『BX』	N	Y

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E09	Terminal [X9]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 8 (1008): Reset alarm (Abnormal) 『SS1』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 9 (1009): External alarm (9 = Active OFF/1009 = Active ON) 『THR』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 10 (1010): Ready for jogging 『JOG』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 11 (1011): Select frequency setting 2/ frequency setting 1 『Hz2/Hz1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 12 (1012): Select motor 2 『M2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 13: DC braking command 『DCBRK』 PM SLV is valid only when P30 = 0		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 14 (1014): Select torque limit 2/ torque limit 1 『TL2/TL1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 15: Switch to commercial power (50 Hz) 『SW50』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 16: Switch to commercial power (60 Hz) 『SW60』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 17 (1017): UP command 『UP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 18 (1018): DOWN command 『DOWN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 19 (1019): Allow function code editing (data change enabled) 『WE-KP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 20 (1020): Cancel PID control 『Hz/PID』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 21 (1021): Switch normal/ inverse operation 『IVS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 22 (1022): Interlock 『IL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 23 (1023): Cancel torque control 『Hz/TRQ』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 24 (1024): Select link operation (RS-485, BUS option) 『LE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 25 (1025): Universal DI 『U-DI』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 26 (1026): Select auto search for idling motor speed at starting 『STM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 30 (1030): Force to stop (30 = Active OFF/1030 = Active ON) 『STOP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 32 (1032): Pre-excite 『EXITE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 33 (1033): Reset PID integral and differential terms 『PID-RST』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 34 (1034): Hold PID integral term 『PID-HLD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 35 (1035): Local (keypad) command selection 『LOC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 36 (1036): Select motor 3 『M3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 37 (1037): Select motor 4 『M4』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 39: Condensation prevention 『DWP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 40: Switch to commercial power built-in sequence (50 Hz) 『ISW50』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 41: Switch to commercial power built-in sequence (60 Hz) 『ISW60』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 42 (1042): Activate the limit switch at start point 『LS』		

Function code	Name	Control method and Data setting range	Change when running	Data copying
E09	Terminal [X9]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 46 (1046): Overload stop enable command 『OLS』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 47 (1047): Servo lock command 『LOCK』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 48: Pulse train input 『PIN』 * Terminal [X7] only (E06, E07)		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 49 (1049): Pulse train sign terminal 『SIGN』 * Other than terminal [X6] and [X7] (E01 to E05, E08, E09)		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 58(1058) :UP/DOWN frequency clear 『STZ』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 59 (1059): Battery operation selection 『BATRY』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 60 (1060): Select torque bias 1 『TB1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 61 (1061): Select torque bias 2 『TB2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 62 (1062): Hold torque bias 『H-TB』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 65 (1065): Check brake 『BRKE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 70 (1070): Cancel line speed control 『Hz/LSC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 71 (1071): Hold line speed control frequency in the memory 『LSC-HLD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 72 (1072): Count the run time of commercial power-driven motor 1 『CRUN-M1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 73 (1073): Count the run time of commercial power-driven motor 2 『CRUN-M2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 74 (1074): Count the run time of commercial power-driven motor 3 『CRUN-M3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 75 (1075): Count the run time of commercial power-driven motor 4 『CRUN-M4』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 76 (1076): Select droop control 『DROOP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 77 (1077): Speed deviation error cancel 『PG-CCL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 78 (1078): Speed control parameter selection 1 『MPRM1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 79 (1079): Speed control parameter selection 2 『MPRM2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 80 (1080): Cancel customizable logic 『CLC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 81 (1081): Clear all customizable logic timers 『CLTC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 82 (1082): Anti-regenerative control cancel 『AR-CCL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 83 (1083): PG input switching 『PG-SEL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 84 (1084): Acceleration/deceleration cancel (bypass) 『BPS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 94: Forward rotation JOG 『FJOG』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 95: Reverse rotation JOG 『RJOG』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 97 (1097): Direction command 『DIR』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 100: No assignment 『NONE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 105 (1105): Light load automatic double speed judgment permission 『LAC-ENB』		

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E09	Terminal [X9]	V/f PGV/f SLV **PGV** PM SLV **PM PGV** TRQ 110 (1110): Servo lock gain selection 『SLG2』 **V/f PGV/f SLV PGV PM SLV PM PGV TRQ** 111 (1111): Forced stop (terminal block only) 『STOP-T』 (111 = Active OFF/1111 = Active ON) **V/f PGV/f** SLV PGV PM SLV PM PGV TRQ 116 (1116): AVR cancel 『AVR-CCL』 V/f PGV/f **SLV PGV PM SLV PM PGV** TRQ 119 (1119): Speed regulator P selection 『P-SEL』 **V/f PGV/f SLV PGV PM SLV PM PGV TRQ** 121 (1121) to 129(1129): Customizable logic input 1 to 9 “CLI1” to 『CLI1』 to 『CLI9』 **V/f PGV/f SLV PGV PM SLV PM PGV** TRQ 134 (1134): Forced operation command 『FMS』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 135 (1135): Travel/absolute position switching 『INC/ABS』 V/f **PGV/f** SLV **PGV** PM SLV PM PGV TRQ 136 (1136): Orientation command 『ORT』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 137 (1137): Position control/speed control switching 『POS/Hz』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 138 (1138): Homing command 『ORG』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 139 (1139): + direction overtravel 『+OT』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 140 (1140): - direction overtravel 『-OT』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 141 (1141): Position clear command 『P-CLR』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 142 (1142): Position preset command 『P-PRESET』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 143 (1143): Teaching command 『TEACH』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 144 (1144): Positioning data change command 『POS-SET』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 145 (1145): Positioning data selection 『POS-SEL1』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 146 (1146): Positioning data selection 『POS-SEL2』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 147 (1147): Positioning data selection 4 『POS-SEL4』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 169 (1169): Initial diameter set command 『D-SET』 V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 170 (1170): Winding diameter calculation hold command 『D-HLD』 **V/f PGV/f SLV PGV PM SLV PM PGV TRQ** 171 (1171): PID control multistage command 1 『PID-SS1』 **V/f PGV/f SLV PGV PM SLV PM PGV TRQ** 172 (1172): PID control multistage command 2 『PID-SS2』 * Inside the ( ) is the negative logic signal (OFF at short-circuit).	N	Y
E10	Acceleration time 2	**V/f PGV/f SLV PGV PM SLV PM PGV TRQ** 0.00 to 6000 s * 0.00 is for acceleration and deceleration time cancel (when performing soft-start and stop externally)	Y	Y
E11	Deceleration time 2		Y	Y
E12	Acceleration time 3		Y	Y
E13	Deceleration time 3		Y	Y
E14	Acceleration time 4		Y	Y
E15	Deceleration time 4		Y	Y
E16	Torque limiter 2-1	**V/f PGV/f SLV PGV PM SLV PM PGV TRQ** -300 to 0 to 300%; 999 (Disable)	Y	Y
E17	Torque limiter 2-2	**V/f PGV/f SLV PGV PM SLV PM PGV TRQ** -300 to 0 to 300%; 999 (Disable)	Y	Y
E20	Terminal [Y1] (Function selection)	**V/f PGV/f SLV PGV PM SLV PM PGV TRQ** 0 (1000): Inverter running 『RUN』	N	Y
E21	Terminal [Y2]	**V/f PGV/f SLV PGV PM SLV PM PGV** TRQ 1 (1001): Frequency (speed) arrival 『FAR』	N	Y

*1 6.00 s for 22 kW or less, and 20.00 s for 30 kW or more.

Function code	Name	Control method and Data setting range	Change when running	Data copying
E22	Terminal [Y3]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 2 (1002): Frequency (speed) detected 『FDT』	N	Y
E23	Terminal [Y4]	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 3 (1003): Under voltage detected (inverter stopped) 『LU』	N	Y
E24	Terminal [Y5A/C] (Ry output)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 4 (1004): Detected torque polarity 『B/D』	N	Y
E27	Terminal [30A/B/C] (Relay output)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5 (1005): Inverter output limiting 『IOL』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 6 (1006): Auto-restarting after momentary power failure 『IPF』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 7 (1007): Motor overload early warning 『OL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 8 (1008): Keypad operation 『KP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 10 (1010): Inverter ready to run 『RDY』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 11: Commercial/inverter power supply switching 『SW88』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 12: Commercial/inverter power supply switching 『SW52-2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 13: Commercial/inverter power supply switching 『SW52-1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 15 (1015): Switch MC on the input power lines 『AX』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 16 (1016): Pattern operation stage transition 『TU』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 17 (1017): Pattern operation cycle completed 『TO』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 18 (1018): Pattern operation stage 1 『STG1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 19 (1019): Pattern operation stage 2 『STG2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 20 (1020): Pattern operation stage 4 『STG4』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 21 (1021): Frequency (speed) arrival 2 『FAR2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 22 (1022): Inverter output limiting with delay 『IOL2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 25 (1025): Cooling fan in operation 『FAN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 26 (1026): Auto-resetting 『TRY』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 27 (1027): Universal DO 『U-DO』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 28 (1028): Heat sink overheat early warning 『OH』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 29 (1029): Master-follower operation complete 『SY』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 30 (1030): Lifetime alarm 『LIFE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 31 (1031): Frequency (speed) detected 2 『FDT2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 33 (1033): Reference loss detected 『REF OFF』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 35 (1035): Inverter outputting 『RUN2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 36 (1036): Overload prevention controlling 『OLP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 37 (1037): Current detected 『ID』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 38 (1038): Current detected 2 『ID2』		

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E27	Terminal [30A/B/C] (Relay output)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 39 (1039): Current detected 3 『ID3』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 41 (1041): Low current detected 『IDL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 42 (1042): PID alarm 『PID-ALM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 43 (1043): Under PID control 『PID-CTL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 44 (1044): Under sleep mode of PID control 『PID-STP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 45 (1045): Low torque detected 『U-TL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 46 (1046): Torque detected 1 『TD1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 47 (1047): Torque detected 2 『TD2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 48 (1048): Motor 1 selected 『SWM1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 49 (1049): Motor 2 selected 『SWM2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 50 (1050): Motor 3 selected 『SWM3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 51 (1051): Motor 4 selected 『SWM4』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 52 (1052): Forward rotation 『FRUN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 53 (1053): Reverse rotation 『RRUN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 54 (1054): Under remote mode 『RMT』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 56 (1056): Motor overheat detected by thermistor 『THM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 57 (1057): Mechanical brake control 『BRKS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 58 (1058): Frequency (speed) detected 3 『FDT3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 59 (1059): Current input wire break detection (terminal [C1] and [C2]) 『C1OFF』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 70 (1070): Speed valid 『DNZS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 71 (1071): Speed agreement 『DSAG』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 72 (1072): Frequency (speed) arrival 3 『FAR3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 76 (1076): Speed mismatch 『PG-ERR』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 77 (1077): Low DC link bus voltage detection 『U-EDC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 79 (1079): During decelerating at momentary power failure 『IPF2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 82 (1082): Positioning complete 『PSET』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 84 (1084): Maintenance timer counted up 『MNT』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 87 (1087): Frequency arrival and detected 『FARFDT』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 89 (1089): Magnetic pole position detection complete signal 『PTD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 90 (1090): Alarm content 1 『AL1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 91 (1091): Alarm content 2 『AL2』		

Function code	Name	Control method and Data setting range	Change when running	Data copying
E27	Terminal [30A/B/C] (Relay output)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 92 (1092): Alarm content 4 『AL4』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 93 (1093): Alarm content 8 『AL8』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 95 (1095): Forced operation 『FMRUN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 98 (1098): Light alarm 『L-ALM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 99 (1099): Alarm output 9『ALM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 101 (1101): EN circuit failure detected 1『DECF』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 102 (1102): EN terminal input OFF 『ENOFF』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 105 (1105): Braking transistor broken 『DBAL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 111 (1111) to 124(1124): Customizable logic output signal 1 to 14 『CLO1』 to 『CLO14』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 125 (1125): Integral power pulse output 『POUT』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 131 (1131): Speed limiting 『S-LIM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 132 (1132): Torque limit level 『T-LIM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 133 (1133): Low current detection 『IDL2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 135 (1135): Dancer upper limit position warning signal 『D-UPFL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 136 (1136): Dancer lower limit position warning signal 『D-DNFL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 137 (1137): Dancer position limit warning signal 『D-FL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 151 (1151): Overtravel detection 『OT-OUT』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 152 (1152): Forced stop detection 『STOP-OUT』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 153 (1153): Pass point detection 1 『PPAS1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 154 (1154): Pass point detection 2 『PPAS2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 158 (1158): Overload detected 『LLIM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 159 (1159): Performing light load automatic double speed operation 『LAC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 251(1251): M/Shift key ON/OFF status “MTGL” 『MTGL』		
		* Inside the ( ) is the negative logic signal (OFF at short-circuit)		
E29	Frequency arrival delay timer (FAR2)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 10.00s	Y	Y
E30	Frequency arrival detection width (Detection width)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 10.0Hz	Y	Y
E31	Frequency detection 1 (operation level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
E32	(Hysteresis width)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
E34	Overload early warning/Current detection (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 (Disable), 1 to 200% of inverter rated current (Inverter rated current dependent on F80)	Y	Y1 Y2
E35	(Timer)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 600.00s	Y	Y
E36	Frequency detection 2 (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y

*3 The rated current of the motor is set. For details, refer to the FRENIC-MEGA (G2) User's Manual.

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E37	Current detection 2/Low current detection (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 (Disable), 1 to 200% of inverter rated current (Inverter rated current dependent on F80)	Y	Y1 Y2
E38	(Timer)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 600.00s	Y	Y
E39	Constant rate of feeding coefficient 1/ Speed display auxiliary coefficient 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.000 to 9999	Y	Y
E42	LED display filter	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 5.0s	Y	Y
E43	LED monitor (display selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Speed monitor (Selectable with E48) 3: Output current 4: Output voltage when alarm occurred 8: Calculated motor output torque when alarm occurred 9: Power consumption 10: PID process command 12: PID feedback value 13: Timer value 14: PID output 15: Load factor 16: Motor output 17: Analog signal input monitor 21: Current position 22: Positioning deviation 23: Torque current (%) 24: Magnetic flux command(%) 25: Input watt-hour 26: Winding diameter 27: Position control start position 28: Stop target position 29: PID deviation 30: Torque bias 31: Estimated inertia acceleration/deceleration time conversion value (coming soon) 32: Customizable logic output	Y	Y
E44	(Display when stopped)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Specified value 1: Output value	Y	Y
E48	LED monitor details (Speed monitor selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Output frequency 1 (before slip compensation) 1: Output frequency 2 (after slip compensation) 2: Set frequency 3: Motor speed 4: Feed speed 5: Line speed 6: Constant feeding rate time 7: Speed (%) 8: Reference line speed 9: Line speed output value	Y	Y
E49	Torque Command Monitor (Polarity selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Torque polarity 1: Plus for driving, Minus for braking	Y	Y
E50	Display coefficient for speed monitor	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 600.00	Y	Y
E51	Display coefficient for “Input watt-hour data”	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.000 (Cancel/Reset), 0.001 to 9999	Y	Y
E52	Keypad menu selection	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Function code data setting mode (Menu 0, Menu 1, and Menu 7) 1: Function code data check mode (Menu 2 and Menu 7) 2: Full-menu mode	Y	Y
E54	Frequency detection 3 (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
E55	Current detection 3 (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 (Disable), 1 to 200% of inverter rated current (Inverter rated current dependent on F80)	Y	Y1 Y2
E56	(Timer)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 600.00s	Y	Y

*3 The rated current of the motor is set. For details, refer to the FRENIC-MEGA (G2) User's Manual.

Function code	Name	Control method and Data setting range	Change when running	Data copying
E57	Integral power pulse output unit	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Pulse output every 0.1 kWh 1: Pulse output every 1 kWh 2: Pulse output every 10 kWh 3: Pulse output every 100 kWh 4: Pulse output every 1000 kWh	Y	Y
E61	Terminal [12] (extended function)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: No extension function assignment 1: Auxiliary frequency setting 1 2: Auxiliary frequency setting 2 3: PID command 1 5: PID Dfeedback value 6: Ratio setting 7: Analog torque limiter A 8: Analog torque limit value B 9: Torque bias 10: Torque command 11: Torque current command 12: Acceleration/deceleration time ratio setting 13: Upper limit frequency 14: Lower limit frequency 15: Auxiliary frequency setting 3 16: Auxiliary frequency setting 4 17: Speed limit for forward rotation (FWD) 18: Speed limit for reverse rotation (REV) 20: Analog signal input monitor	N	Y
E62	Terminal [C1] (C1 function) (extended function)		N	Y
E63	Terminal [V2] (extended function)		N	Y
E64	Saving of digital reference frequency	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Auto saving (main power is turned off) 1: Save by turning FUNC DATA key ON	Y	Y
E65	Reference loss detection (Continuous running frequency)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Stop deceleration 20 to 120%, 999: Cancel	Y	Y
E66	Terminal [C1] (V3 function) (Extension function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: No extension function assignment 1: Auxiliary frequency setting 1 2: Auxiliary frequency setting 2 3: PID command 1 5: PID feedback value 6: Ratio setting 7: Analog torque limiter A 8: Analog torque limit value B 9: Torque bias 10: Torque command 11: Torque current command 12: Acceleration/deceleration time ratio setting 13: Upper limit frequency 14: Lower limit frequency 15: Auxiliary frequency setting 3 16: Auxiliary frequency setting 4 17: Speed limit for forward rotation (FWD) 18: Speed limit for reverse rotation (REV) 20: Analog signal input monitor	N	Y
E70	M/Shift key (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 (1000): Multistep frequency selection (0 to 1 steps) 『SS1』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 1 (1001): Select multistep frequency (0 to 3 steps) 『SS2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 2 (1002): Select multistep frequency (0 to 7 steps) 『SS4』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 3 (1003): Select multistep frequency (0 to 15 steps) 『SS8』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 4 (1004): Select ACC/DEC time (2 steps) 『RT1』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5 (1005): Select ACC/DEC time (4 steps) 『RT2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 6 (1006): Select 3-wire operation 『HLD』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 7 (1007): Coast to a stop command 『BX』	N	Y

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E70	M/Shift key (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 10 (1010): Ready for jogging 『JOG』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 11 (1011): Select frequency setting 2/ frequency setting 1 『Hz2/Hz1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 12 (1012): Select motor 2 『M2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 13: DC braking command 『DCBRK』 PM SLV is valid only when P30 = 0		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 14 (1014): Select torque limit 2/ torque limit 1 『TL2/TL1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 19 (1019): Allow function code editing (data change enabled) 『WE-KP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 20 (1020): Cancel PID control 『Hz/PID』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 21 (1021): Switch normal/ inverse operation 『IVS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 23 (1023): Cancel torque control 『Hz/TRQ』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 24 (1024): Select link operation (RS-485, BUS option) 『LE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 26 (1026): Select auto search for idling motor speed at starting 『STM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 30 (1030): Force to stop (30 = Active OFF/1030 = Active ON) 『STOP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 32 (1032): Pre-excite 『EXITE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 33 (1033): Reset PID integral and differential terms 『PID-RST』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 34 (1034): Hold PID integral term 『PID-HLD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 35 (1035): Local (keypad) command selection 『LOC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 36 (1036): Select motor 3 『M3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 37 (1037): Select motor 4 『M4』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 39: Condensation prevention 『DWP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 40: Switch to commercial power built-in sequence (50 Hz) 『ISW50』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 41: Switch to commercial power built-in sequence (60 Hz) 『ISW60』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 46 (1046): Overload stop enable command 『OLS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 47 (1047): Servo lock command 『LOCK』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 59 (1059): Battery operation selection 『BATRY』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 60 (1060): Select torque bias 1 『TB1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 61 (1061): Select torque bias 2 『TB2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 62 (1062): Hold torque bias 『H-TB』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 65 (1065): Check brake 『BRKE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 70 (1070): Cancel line speed control 『Hz/LSC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 71 (1071): Hold line speed control frequency in the memory 『LSC-HLD』		

Function code	Name	Control method and Data setting range	Change when running	Data copying
E70	M/Shift key (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 72 (1072): Input during operation with commercial power supply (motor 1) 『CRUN-M1』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 73 (1073): Input during operation with commercial power supply (motor 2) 『CRUN-M2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 74 (1074): Count the run time of commercial power-driven motor 3 『CRUN-M3』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 75 (1075): Count the run time of commercial power-driven motor 4 『CRUN-M4』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 76 (1076): Select droop control 『DROOP』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 77 (1077): Speed deviation error cancel 『PG-CCL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 78 (1078): Speed control parameter selection 1 『MPRM1』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 79 (1079): Speed control parameter selection 2 『MPRM2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 80 (1080): Cancel customizable logic 『CLC』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 81 (1081): Clear all customizable logic timers 『CLTC』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 82 (1082): Anti-regenerative control cancel 『AR-CCL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 83 (1083): PG input switching 『PG-SEL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 84 (1084): Acceleration/deceleration cancel (bypass) 『BPS』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 94: Forward rotation JOG 『FJOG』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 95: Reverse rotation JOG 『RJOG』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 97 (1097): Direction command 『DIR』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 100: No assignment 『NONE』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 105 (1105): Light load automatic double speed judgment permission 『LAC-ENB』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 110 (1110): Servo lock gain selection 『SLG2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 116 (1116): AVR cancel “AVR-CCL” 『AVR-CCL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 119 (1119): Speed regulator P selection “P-SEL” 『P-SEL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 121 (1121) to 129(1129): Customizable logic input 1 to 9 『CLI1』 to 『CLI9』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 134 (1134): Forced operation command 『FMS』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 135 (1135): Travel/absolute position switching 『INC/ABS』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 136 (1136): Orientation command 『ORT』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 137 (1137): Position control/speed control switching 『POS/Hz』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 138 (1138): Homing command 『ORG』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 141 (1141): Position clear command 『P-CLR』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 142 (1142): Position preset command 『P-PRESET』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 143 (1143): Teaching command 『TEACH』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 144 (1144): Positioning data change command 『POS-SET』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 145 (1145): Positioning data selection 1 『POS-SEL1』	N	Y

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E70	M/Shift key (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 146 (1146): Positioning data selection 2 『POS-SEL2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 147 (1147): Positioning data selection 4 『POS-SEL4』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 169 (1169): Initial diameter set command 『D-SET』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 170 (1170): Winding diameter calculation hold command 『D-HLD』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 171 (1171): PID control multistage command 1 『PID-SS1』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 172 (1172): PID control multistage command 2 『PID-SS2』 * Inside the ( ) is the negative logic signal (OFF at short-circuit).	N	Y
E71	M-LED indicator (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 (1000): Inverter running 『RUN』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 1 (1001): Frequency (speed) arrival 『FAR』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 2 (1002): Frequency (speed) detected 『FDT』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 3 (1003): Under voltage detected (inverter stopped) 『LU』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 4 (1004): Detected torque polarity 『B/D』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5 (1005): Inverter output limiting 『IOL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 6 (1006): Auto-restarting after momentary power failure 『IPF』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 7 (1007): Motor overload early warning 『OL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 8 (1008): Keypad operation 『KP』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 10 (1010): Inverter ready to run 『RDY』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 16 (1016): Pattern operation stage transition 『TU』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 17 (1017): Pattern operation cycle completed 『TO』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 18 (1018): Pattern operation stage 1 『STG1』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 19 (1019): Pattern operation stage 2 『STG2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 20 (1020): Pattern operation stage 4 『STG4』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 21 (1021): Frequency (speed) arrival 2 『FAR2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 22 (1022): Inverter output limiting with delay 『IOL2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 25 (1025): Cooling fan in operation 『FAN』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 26 (1026): Auto-resetting 『TRY』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 28 (1028): Heat sink overheat early warning 『OH』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 29 (1029): Master-follower operation complete 『SY』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 30 (1030): Lifetime alarm 『LIFE』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 31 (1031): Frequency (speed) detected 2 『FDT2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 33 (1033): Reference loss detected 『REF OFF』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 35 (1035): Inverter outputting 『RUN2』	N	Y

Function code	Name	Control method and Data setting range	Change when running	Data copying
E71	M-LED indicator (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 36 (1036): Overload prevention controlling 『OLP』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 37 (1037): Current detected 『ID』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 38 (1038): Current detected 2 『ID2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 39 (1039): Current detected 3 『ID3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 41 (1041): Low current detected 『IDL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 42 (1042): PID alarm 『PID-ALM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 43 (1043): Under PID control 『PID-CTL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 44 (1044): Under sleep mode of PID control 『PID-STP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 45 (1045): Low torque detected 『U-TL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 46 (1046): Torque detected 1 『TD1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 47 (1047): Torque detected 2 『TD2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 48 (1048): Motor 1 selected 『SWM1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 49 (1049): Motor 2 selected 『SWM2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 50 (1050): Motor 3 selected 『SWM3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 51 (1051): Motor 4 selected 『SWM4』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 52 (1052): Forward rotation 『FRUN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 53 (1053): Reverse rotation 『RRUN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 54 (1054): Under remote mode 『RMT』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 56 (1056): Motor overheat detected by thermistor 『THM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 57 (1057): Mechanical brake control 『BRKS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 58 (1058): Frequency (speed) detected 3 『FDT3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 59 (1059): Current input wire break detection (terminal [C1] and [C2]) 『C1OFF』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 70 (1070): Speed valid 『DNZS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 71 (1071): Speed agreement 『DSAG』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 72 (1072): Frequency (speed) arrival 3 『FAR3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 76 (1076): Speed mismatch error detection 『PG-ERR』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 77 (1077): Low DC link bus voltage detection 『U-EDC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 79 (1079): During decelerating at momentary power failure 『IPF2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 82 (1082): Positioning complete 『PSET』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 84 (1084): Maintenance timer counted up 『MNT』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 87 (1087): Frequency arrival and detected 『FARFDT』		

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E71	M-LED indicator (Function selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 89 (1089): Magnetic pole position detection complete signal 『PTD』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 95 (1095): Forced operation 『FMRUN』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 98 (1098): Light alarm 『L-ALM』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 99 (1099): Alarm output 『ALM』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 100: No assignment 『NONE』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 101 (1101): EN circuit failure detected 『DECF』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 102 (1102): EN terminal input OFF 『ENOFF』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 105 (1105): Braking transistor broken 『DBAL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 111 (1111) to 124(1124): Customizable logic output signal 1 to 14 『CLO1』 to 『CLO14』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 131(1131): Speed limiting 『S-LIM』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 132 to 1132: Torque limit level 『T-LIM』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 133 (1133): Low current detection 『IDL2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 135 (1135): Dancer upper limit position warning signal 『D-UPFL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 136 (1136): Dancer lower limit position warning signal 『D-DNFL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 137 (1137): Dancer position limit warning signal 『D-FL』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 151 (1151): Overtravel detection 『OT-OUT』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 152 (1152): Forced stop detection 『STOP-OUT』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 153 (1153): Pass point detection 1 『PPAS1』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 154 (1154): Pass point detection 2 『PPAS2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 158 (1158): Overload detection 『LLIM』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 159 (1159): Performing light load automatic double speed operation 『LAC』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 251 (1251): M/Shift key ON/OFF status 『MTGL』 * Inside the ( ) is the negative logic signal (OFF at short-circuit).	N	Y
E76	DC link bus low-voltage detection level	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 200 to 400 V (200V series) 400 to 800 V (400V series)	Y	Y2
E78	Torque detection 1 (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 300%	Y	Y
E79	(Timer)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 600.00s	Y	Y
E80	Torque detection 2/ low torque detection (Level)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 300%	Y	Y
E81	(Timer)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.01 to 600.00s	Y	Y
E98	Terminal [FWD] (function)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 (1000): Select multistep frequency (0 to 1 steps) 『SS1』	N	Y
E99	Terminal [REV] (function)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 1 (1001): Select multistep frequency (0 to 3 steps) 『SS2』 V/f PGV/f SLV PGV PM SLV PM PGV TRQ 2 (1002): Select multistep frequency (0 to 7 steps) 『SS4』	N	Y

Function code	Name	Control method and Data setting range	Change when running	Data copying
E99	Terminal [REV] (function)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 3 (1003): Select multistep frequency (0 to 15 steps) 『SS8』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 4 (1004): Select ACC/DEC time (2 steps) 『RT1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 5 (1005): Select ACC/DEC time (4 steps) 『RT2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 6 (1006): Select 3-wire operation 『HLD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 7 (1007): Coast to a stop command 『BX』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 8 (1008): Reset alarm (Abnormal) 『RST』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 9 (1009): External alarm (9 = Active OFF/1009 = Active ON) 『THR』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 10 (1010): Ready for jogging 『JOG』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 11 (1011): Select frequency setting 2/ frequency setting 1 『Hz2/Hz1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 12 (1012): Select motor 2 『M2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 13: DC braking command 『DCBRK』 PM SLV is valid only when P30 = 0		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 14 (1014): Select torque limit 2/ torque limit 1 『TL2/TL1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 15: Switch to commercial power (50 Hz) 『SW50』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 16: Switch to commercial power (60 Hz) 『SW60』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 17 (1017): UP command 『UP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 18 (1018): DOWN command 『DOWN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 19 (1019): Allow function code editing (data change enabled) 『WE-KP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 20 (1020): Cancel PID control 『Hz/PID』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 21 (1021): Switch normal/ inverse operation 『IVS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 22 (1022): Interlock 『IL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 23 (1023): Cancel torque control 『Hz/TRQ』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 24 (1024): Select link operation (RS-485, BUS option) 『LE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 25 (1025): Universal DI 『U-DI』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 26 (1026): Select auto search for idling motor speed at starting 『STM』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 30 (1030): Force to stop (30 = Active OFF/1030 = Active ON) 『STOP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 32 (1032): Pre-excite 『EXITE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 33 (1033): Reset PID integral and differential terms 『PID-RST』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 34 (1034): Hold PID integral term 『PID-HLD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 35 (1035): Local (keypad) command selection 『LOC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 36 (1036): Select motor 3 『M3』		

E codes :Extension Terminal Functions (terminal functions)

Function code	Name	Control method and Data setting range	Change when running	Data copying
E99	Terminal [REV] (function)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 37 (1037): Select motor 4 『M4』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 39: Condensation prevention 『DWP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 40: Switch to commercial power built-in sequence (50 Hz) 『ISW50』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 41: Switch to commercial power built-in sequence (60 Hz) 『ISW60』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 42 (1042): Activate the limit switch at start point 『LS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 46 (1046): Overload stop enable command 『OLS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 47 (1047): Servo lock command 『LOCK』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 49 (1049): Pulse train sign terminal 『SIGN』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 58(1058) : UP/DOWN frequency clear 『STZ』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 59 (1059): Battery operation selection 『BATRY』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 60 (1060): Select torque bias 1 『TB1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 61 (1061): Select torque bias 2 『TB2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 62 (1062): Hold torque bias 『H-TB』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 65 (1065): Check brake 『BRKE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 70 (1070): Cancel line speed control 『Hz/LSC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 71 (1071): Hold line speed control frequency in the memory 『LSC-HLD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 72 (1072): Count the run time of commercial power-driven motor 1 『CRUN-M1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 73 (1073): Count the run time of commercial power-driven motor 2 『CRUN-M2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 74 (1074): Count the run time of commercial power-driven motor 3 『CRUN-M3』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 75 (1075): Count the run time of commercial power-driven motor 4 『CRUN-M4』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 76 (1076): Select droop control 『DROOP』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 77 (1077): Speed deviation error cancel 『PG-CCL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 78 (1078): Speed control parameter selection 1 『MPRM1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 79 (1079): Speed control parameter selection 2 『MPRM2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 80 (1080): Cancel customizable logic 『CLC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 81 (1081): Clear all customizable logic timers 『CLTC』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 82 (1082): Anti-regenerative control cancel 『AR-CCL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 83 (1083): PG input switching 『PG-SEL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 84 (1084): Acceleration/deceleration cancel (bypass) 『BPS』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 94: Forward rotation JOG 『FJOG』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 95: Reverse rotation JOG 『RJOG』		

Function code	Name	Control method and Data setting range	Change when running	Data copying
E99	Terminal [REV] (function)	**V/f PGV/f SLV PGV PM SLV PM PGV TRQ** 97 (1097): Direction command 『DIR』	N	Y
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 98: Run forward / stop command 『FWD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 99: Run reverse / stop command 『REV』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 100: No assignment 『NONE』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 105 (1105): Light load automatic double speed judgment permission 『LAC-ENB』		
		V/f PGV/f SLV **PGV** PM SLV **PM PGV** TRQ 110 (1110): Servo lock gain selection 『SLG2』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 111 (1111): Forced stop (terminal block only) 『STOP-T』 (111 = Active OFF/1111 = Active ON)		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 116 (1116): AVR cancel “AVR-CCL” 『AVR-CCL』		
		V/f PGV/f **SLV PGV PM SLV PM PGV** TRQ 119 (1119): Speed regulator P selection “P-SEL” 『P-SEL』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 121 (1121) to 129 (1129): Customizable logic input 1 to 9 『CLI1』～『CLI9』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 134 (1134): Forced operation command 『FMS』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 135 (1135): Travel/absolute position switching 『INC/ABS』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 136 (1136): Orientation command 『ORT』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 137 (1137): Position control/speed control switching 『POS/Hz』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 138 (1138): Homing command 『ORG』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 139 (1139): + direction overtravel 『+OT』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 140 (1140): - direction overtravel 『-OT』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 141 (1141): Position clear command 『P-CLR』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 142 (1142): Position preset command 『P-PRESET』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 143 (1143): Teaching command 『TEACH』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 144 (1144): Positioning data change command 『POS-SET』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 145 (1145): Positioning data selection 1 『POS-SEL1』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 146 (1146): Positioning data selection 2 『POS-SEL2』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 147 (1147): Positioning data selection 4 『POS-SEL4』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 169 (1169): Initial diameter set command 『D-SET』		
		V/f **PGV/f** SLV **PGV** PM SLV **PM PGV** TRQ 170 (1170): Winding diameter calculation hold command 『D-HLD』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 171 (1171): PID control multistage command 1 『PID-SS1』		
		V/f PGV/f SLV PGV PM SLV PM PGV TRQ 172 (1172): PID control multistage command 2 『PID-SS2』		
		* Inside the ( ) is the negative logic signal (OFF at short-circuit).		

C codes :Control Functions of Frequency (Control function)

Function code	Name	Control method and Data setting range	Change when running	Data copying
C01	Jump frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
C02	2		Y	Y
C03	3		Y	Y
C04	(Skip width)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 30.0Hz	Y	Y
C05	Multistep frequency 1	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 599.00Hz	Y	Y
C06	2		Y	Y
C07	3		Y	Y
C08	4		Y	Y
C09	5		Y	Y
C10	6		Y	Y
C11	7		Y	Y
C12	8		Y	Y
C13	9		Y	Y
C14	10		Y	Y
C15	11		Y	Y
C16	12		Y	Y
C17	13		Y	Y
C18	14		Y	Y
C19	15		Y	Y
C20	Jogging frequency	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 599.00Hz	Y	Y
C21	Pattern operation / timed operation (Operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: cycle operation 1: Repetition operation 2: Constant speed operation after 1 cycle operation 3: Timed operation	N	Y
C22	(Stage 1)	Special setting: Press the key 3 times. 1st: Set run time 0.0 to 6000 s and press the key. 2nd: Set rotational direction F (forward) or r (reverse) and press the key. 3rd: Set acceleration/deceleration time 1 to 4 and press the key.	Y	Y
C23	(Stage 2)		Y	Y
C24	(Stage 3)		Y	Y
C25	(Stage 4)		Y	Y
C26	(Stage 5)		Y	Y
C27	(Stage 6)		Y	Y
C28	(Stage 7)		Y	Y
C30	Frequency setting 2	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Keypad key operation (/ keys) 1: Analog voltage input (Terminal [12]) (from 0 to ±10 VDC) 2: 2: Analog current input (Terminal [C1] (C1 function)) (0 to 20 mA DC) 3: 3: Analog voltage input (Terminal [12]) + Analog current input (Terminal [C1] (C1 function)) 5: 5: Analog voltage input (Terminal [V2]) (from 0 to ±10 VDC) 6: 6: Analog voltage input (Terminal [C1] (V3 function)) (0 to 10 VDC) 7: 7: UP/DOWN control 8: 8: Keypad key operation (/ keys) (with balanceless bumpless) 10: 10: Pattern operation 11: 11: Digital input interface card OPC-DI (option) 12: 12: Pulse train input	N	Y
C31	Analog input adjustment (Terminal [12]) (Offset)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -5.0 to 5.0%	Y*	Y
C32	(Gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 400.00%	Y*	Y
C33	(Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
C34	(Gain base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C35	(polarity selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Bipolar 1: Unipolar	N	Y
C36	Analog input adjustment (Terminal [C1]) (C1 function) (Offset)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -5.0 to 5.0%	Y*	Y
C37	(Gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 400.00%	Y*	Y

Function code	Name	Control method and Data setting range	Change when running	Data copying
C38	Analog input adjustment (Terminal [C1]) (C1 function) (Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
C39	(Gain base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C40	(Operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: 4 to 20 mA Unipolar 1: 0 to 20 mA Unipolar 10: 4 to 20 mA Bipolar 11: 0 to 20 mA Bipolar	N	Y
C41	Analog input adjustment (Terminal [V2]) (offset)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -5.0 to 5.0%	Y*	Y
C42	(Gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 400.00%	Y*	Y
C43	(Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
C44	(Gain base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C45	(polarity selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Bipolar 1: Unipolar	N	Y
C50	Bias (for frequency setting 1) (Bias base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C51	Bias (PID command 1) (bias value)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -100.0 to 0.00 to 100.00%	Y*	Y
C52	(Bias base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C53	Selection of normal/inverse operation (Frequency setting 1)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Normal 1: Inverse	Y	Y
C54	(Frequency setting 2)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Normal 1: Inverse	Y	Y
C55	Analog input adjustment (Terminal [12]) (Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -200.0 to 0.00 to 200.00%	Y*	Y
C56	(Bias base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C58	(Display unit)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 92	Y	Y
C59	(maximum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -999.0 to 0.00 to 9990.0	N	Y
C60	(minimum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -999.0 to 0.00 to 9990.0	N	Y
C61	Analog input adjustment (Terminal [C1] (C1 function)) (Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -200.0 to 0.00 to 200.00%	Y*	Y
C62	(Bias base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C64	(Display unit)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 92	Y	Y
C65	(maximum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -999.0 to 0.00 to 9990.0	N	Y
C66	(minimum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -999.0 to 0.00 to 9990.0	N	Y
C67	Analog input adjustment (Terminal [V2]) (Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -200.0 to 0.00 to 200.00%	Y*	Y
C68	(Bias base point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C70	(Display unit)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 92	Y	Y
C71	(maximum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -999.0 to 0.00 to 9990.0	N	Y
C72	(minimum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -999.0 to 0.00 to 9990.0	N	Y
C74	Analog input adjustment (Terminal [C1]) (V3 function) (Offset)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -5.0 to 5.0%	Y*	Y

C codes :Control Functions of Frequency (Control function)

Function code	Name	Control method and Data setting range	Change when running	Data copying
C75	Analog input adjustment (Terminal [C1]) (V3 function) (Gain)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 400.00%	Y*	Y
C76	(Filter)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 5.00s	Y	Y
C77	(Gain reference point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C78	(Operation selection)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0: Bipolar 1: Unipolar	N	Y
C82	(Bias)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -200.0 to 0.00v200.00%	Y*	Y
C83	(Bias reference point)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 100.00%	Y*	Y
C84	(Display unit)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0 to 92	Y	Y
C85	(Maximum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ The analog input monitor terminal [C1] (C1 and V2 functions) display in the - 999.0 to 0.00 to 9990.0 range can be converted into easily recognizable physical quantities. This function can also be used for PID feedback and PID command values.	N	Y
C86	(Minimum scale)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ The analog input monitor terminal [C1] (C1 function) display in the -999.0 to 0.00 to 9990.0 range can be converted into easily recognizable physical quantities. This function can also be used for PID feedback and PID command values.	N	Y
C89	Frequency compensation 1 via communication (Numerator)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -32768 to 32767 (Keypad display is 8000 to 7FFF (in hexadecimal)) (Interpreted as 1 when the value is set to 0)	Y	Y
C90	Frequency compensation 2 via communication (Denominator)	V/f PGV/f SLV PGV PM SLV PM PGV TRQ -32768 to 32767 (Keypad display is 8000 to 7FFF (in hexadecimal)) (Interpreted as 1 when the value is set to 0)	Y	Y
C94	Jump frequency 4	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.0 to 599.0Hz	Y	Y
C95	5		Y	Y
C96	6		Y	Y
C99	Digital setting frequency	V/f PGV/f SLV PGV PM SLV PM PGV TRQ 0.00 to 599.00Hz	Y*	Y

Options

Connection configuration

For main power input and inverter output

AC reactor [ACR□-□□□]
When using a power supply with unstable voltage.

*1 If not using an R0, T0 terminal, connect a connector at this location.

Arrester [CN5□□□] Consult our sales representatives
Suppresses induced lightning surges from the power source to protect entire equipment connected to the power source.

Ferrite ring for reducing radio noise [ACL-40C, ACL-74C, F200160]
Used to reduce radio noise. Suppressive effect to the frequency band is available by approximately 1MHz or more. This is appropriate as a simple measure against noise since it affects broad range in the frequency band.

EMC compliance filter [EFL-□□□, FS□□, FN□□]
Dedicated filter to comply with the European EMC Directive (Emission). Install the filter while referring to the details in the installation manual.

Power filter for output circuit [RNF□□□□-□□] Consult our sales representatives
This will become more effective in noise reduction if used together with the power filter for input circuit.

*2 If using an R0, T0 terminal, connect a connector at this location.

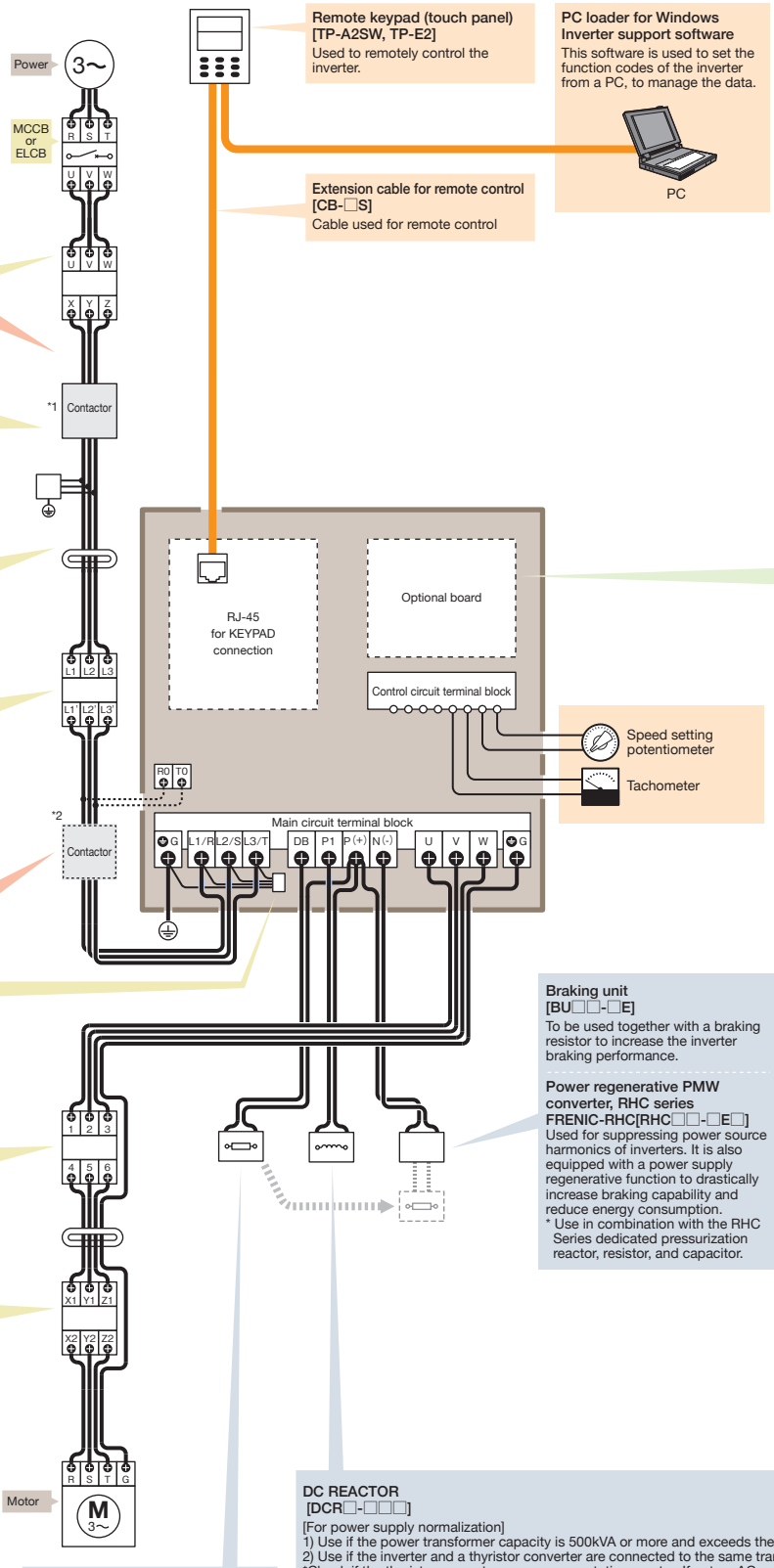
Filter capacitor for reducing radio noise [NFM□□M315KPD□] Consult our sales representatives
Used to reduce radio noise. This is effective for the AM radio frequency band.
*Do not use it on the inverter output side.
[Made by Nippon Chemi-con]

Power filter for input circuit [RNF□□□□-□□] Consult our sales representatives
This filter can be used for the same purpose as the EMC compliance filter, but is not an EMC compliance.

Output circuit filter [OFL-□□□-4A]
Connected to the output of an inverter to:
- Suppress fluctuations of motor terminal voltage.
- Prevent damages to the motor insulation due to surge voltage in 400V series inverter.

*This filter is not limited by carrier frequency. Also, motor can be tuned while this option is installed.

External operation, measurement, and communication



Remote keypad (touch panel) [TP-A2SW, TP-E2]
Used to remotely control the inverter.

Extension cable for remote control [CB-□S]
Cable used for remote control

PC loader for Windows Inverter support software
This software is used to set the function codes of the inverter from a PC, to manage the data.

PC

Speed setting potentiometer

Tachometer

Braking unit [BU□□-□E]
To be used together with a braking resistor to increase the inverter braking performance.

Power regenerative PMW converter, RHC series FRENIC-RHC[RHC□□-□E□]
Used for suppressing power source harmonics of inverters. It is also equipped with a power supply regenerative function to drastically increase braking capability and reduce energy consumption.
* Use in combination with the RHC Series dedicated pressurization reactor, resistor, and capacitor.

Braking resistor [DB□□-□, DB□□-□C]
Increases braking capability for highly frequent stopping and large moment of inertia. When used together with a braking unit, connect this to the connection terminal of the braking unit.

DC REACTOR [DCR□-□□□]
[For power supply normalization]
1) Use if the power transformer capacity is 500kVA or more and exceeds the inverter rated capacity by 10 times.
2) Use if the inverter and a thyristor converter are connected to the same transformer.
*Check if the thyristor converter uses a commutation reactor. If not,an AC reactor must be connected to the power supply side.
3) Connect to prevent trips when trip occurs due to opening/closing of the phase-advancing capacitor for the power supply lines.
4) Use if the voltage unbalance exceeds 2%.
[For improving the input power-factor and reducing harmonics]
•Used to reduce the input harmonic current (correcting power-factor)
* For the drop effect, refer to the guideline appendix.

Built-in option card

■Control option cards

- **Relay output interface card [OPC-RY]**
  Converts inverter transistor output to relay output signal
- **Digital interface cards [OPC-DI], [OPC-DO]**
  Frequency setting by binary and BCD digital signals
- **Analog interface card [OPC-AIO]**
  Torque control by external analog signal
- **PG interface card [OPC-PG□]**
  Performs PG vector control via feedback signals from the encoder
- **[OPC-PMPG]**
  Enables sensor-equipped synchronous motor operation

■Communication option cards

- **SX bus card [OPC-SX]**
- **T-Link communication card [OPC-TL]**
  Data link between PLC (MICREX-F) and inverter

●Open bus cards
Data link between various open buses and inverters

- **Multi-protocol Ethernet communications card [OPC-ETM]**
- **PROFIBUS-DP communication card [OPC-PDP2]**
- **DeviceNet communication card [OPC-DEV]**
- **CANopen communication card [OPC-COP2]**
- **CC-Link communication card [OPC-CCL]**

Filter unit [IFL-□□U-□]
Effectively reduces harmonics and noise when used in combination with an inverter.
Comes with a built-in DC reactor, zero-phase reactor, and capacitive filter that effectively reduces noise.

IP40 compatible attachment [P40ST-F□1]
This attachment makes the inverter's protective structure totally enclosed (IP40).

Compatibility attachment [MA-■-□□]
This attachment makes mounting compatible with our older models.

External cooling attachment [PB-F1-□□]
This attachment is used to move the inverter's cooling fins to a position that is outside the board.

Peripheral and structure options

Multifunctional keypad
[TP-A2SW]

- Equipped with a highly visible LCD.
- Supports a total of 19 languages, including Japanese hiragana, katakana and kanji.
- Parameter changes and mantenance can be perfpromed remotely using a mobile device built-in bluetooth.

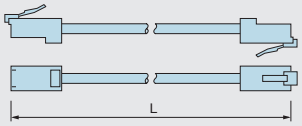
Item	Specification	Remarks
Supported languages	Supports a total of 19 languages, including Japanese, English and Chinese.	
Copy function	Three sets can be stored.	
USB port	Type.mini B	FRENIC Loader for Windows OS
Wireless communi-cation network	Bluetooth Ver.5.0	FRENIC Mobile Loader for Android OS
micro SD card*	SDHC standards (max 32GB)	
Battery*	CR2032	Trace back function
Extension cable	ANSI/TIA/EIA568A Category 5 (10BASE-T/100BASE-TX)	Real-time clock function
Connector for keypad	RJ-45	Option type: CB-□S
Enclosure	Outside cabinet：IP55, inverter back side: IP20	
Approx.weight	135 g	

*SD card not included.

Extension cable for remote control
[CB-□S]

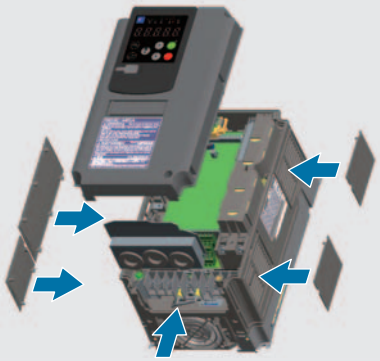
This straight cable is used to connect the RJ-45 connector of the inverter body to the keypad, USB-RS485 converter, etc.
Available in three lengths (1, 3, 5m).

- Cable



Type	CB-5S	CB-3S	CB-1S
Length [m]	5	3	1

IP40 compatible attachment
[P40ST-F□1]



IP40 supporting attachment.
By attaching an attachment to the basic type body, the protective structure can be changed from IP20 to IP40.

■Applicable list table

Item	Specification										
Type	P40ST-FA1		P40ST-FB1			P40ST-FC1			P40ST-FD1		
Applicable inverter type FRN□□□□G2S-4G	0002	0003	0004	0006	0009	0018	0023	0031	0038	0045	0060
FRN□□□□G2S-2G	0003	0005	0008	0011	0018	0032	0046	0059	0075	0088	0115
Approx. weight [kg]	0.1		0.2			0.3			0.4		

■Configuration kit

Type	Remarks
P40ST-FA1	Closing plate (small side) x 3 pcs. / Closing plate (large side) x 1 pc. / Wiring cover x 1 pc.
P40ST-FB1	Closing plate (small side) x 3 pcs. / Closing plate (large side) x 1 pc. / Wiring cover x 1 pc.
P40ST-FC1	Closing plate (small side) x 3 pcs. / Closing plate (large side) x 1 pc. / Closing plate (right corner) x 1 pc. (left corner) x 1 pc. / Wiring cover x 1 pc. / Cross-recessed pan head screw with built-in washer × 2 pcs. (M5 × 10)
P40ST-FD1	Closing plate (small side) x 3 pcs. / Closing plate (large side) x 2 pcs. / Closing plate (right corner) x 1 pc. (left corner) x 1 pc. / Wiring cover x 1 pc. / Cross-recessed pan head screw with built-in washer × 2 pcs. (M5 × 10)

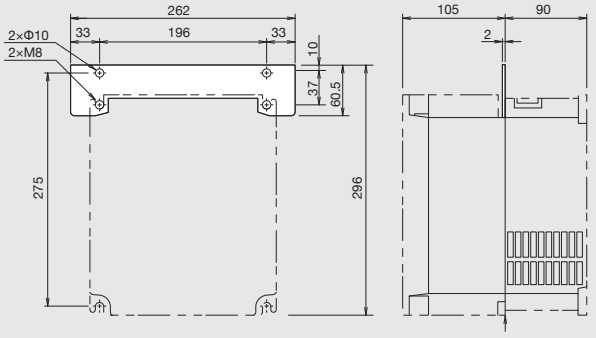
Note 1 The attachiment cannot apply to The EMC filter built-in type.
Note 2 Ambient temperature: -10 to +40°C
Note 3 When attaching the IP40 option, only one optional card can be mounted (two OPC-RY cards can be mounted).
Note 4 After attaching the IP40 option, change the setting with bit 7 (IP20 / IP40 switching) of the function code H98 (protection / operation selection).

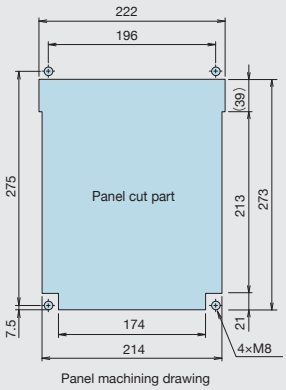
External cooling attachment
[PB-F1-□□]

This attachment is used to move the inverter's cooling fins to a position that is outside the board.

■PB-F1-15

(unit: mm)



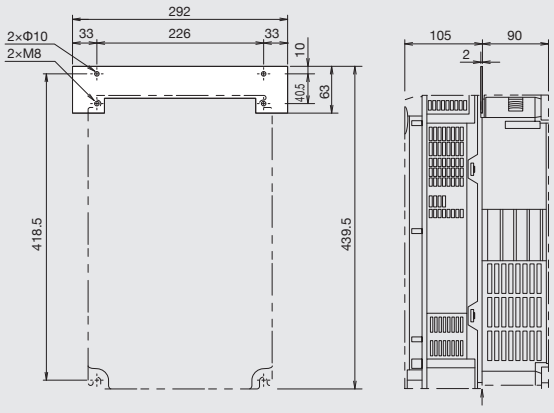


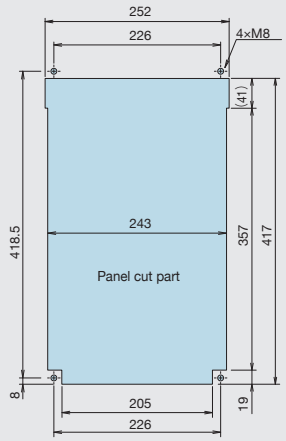
Panel machining drawing

Applicable inverter type
FRN0018G2■-4G
FRN0023G2■-4G
FRN0031G2■-4G
FRN0032G2S-2G
FRN0046G2S-2G
FRN0059G2S-2G

■PB-F1-30

(unit: mm)





Panel machining drawing

Applicable inverter type
FRN0038G2■-4G
FRN0045G2■-4G
FRN0060G2■-4G
FRN0075G2S-2G
FRN0088G2S-2G
FRN0115G2S-2G

Control terminal block
[OPC-G1-TB1]

A round terminal blocks can be connected. Compatible with the conventional FRENIC-MEGA_G1 series.

■Specification of the screw and the torque and recommended wire size

Common terminal	Specification of the screw		Recommended wire size (mm²)
	Screw size	Tightening torque (N·m)	
Control circuit terminal	M3	0.7	0.75 *
fixation screw	M3	0.7	—

* When attaching the terminal block, can not to used the function of the terminal【X6】,【EN1】,【EN2】and【FM2】.
If using the terminal【X6】in FRENIC-MEGA_G1 series, assign it to other than terminal【X6】.

Built-in option card

Item	Type	Specification
PG interface card	OPC-PG	Comes with a two-system pulse input circuit, enabling speed control, position control, and synchronous operation. • Applications: Speed control (vector control with sensor) pulse train input • Specifications: 20 to 3000 P/R A, B, Z phase (incremental) Open collector/complimentary system • PG power supply +12 Vdc ±10% / 120 mA or less or +15 Vdc ±10% / 120 mA or less
PG interface (5 V line driver) card	OPC-PG2	Comes with a single-system pulse input circuit, enabling speed control (vector control with sensor) with PG-based feedback signals. • Applications: Speed control (vector control with sensor) • Specifications: 20 to 3000 P/R 5 V line driver system (single system) • PG power supply: +5 VDC ±10% / 200 mA or less
PG interface (5 V line driver x 2 systems) card	OPC-PG22	Comes with two 5 V line driver pulse input circuits, enabling synchronous operation, positioning control and vibration control of two PG-equipped motors using PG-based feedback signals, as well as frequency command using pulse train input. • Applications: Speed control (vector control with sensor, V/f control with sensor, dynamic torque vector control with sensor), pulse train input, synchronous operation, positioning control • Specifications: 20 to 3000 P/R, 5 V line driver system (two systems) • PG power supply: +5 VDC ±10% / 300 mA or less
PG interface card for synchronous motor drive	OPC-PMPG2	Comes with a 5 V line driver single-system pulse input circuit, enabling synchronous motor operation (vector control with synchronous motor sensor) with PG-based feedback signals. • Applications: Synchronous motor operation (vector control with sensor) • Specifications: 20 to 3000 P/R 5 V line driver system • PG power supply: +5 VDC ±10% / 300 mA or less
Relay output interface card	OPC-RY	This is an option card for converting the transistor outputs of terminals Y1 to Y4 of the inverter into relay outputs (1C contact). Comes with 2 relay outputs, but supports 4 relay outputs when 2 interface cards are installed. • Relay output: 2 circuits built-in • Signal type: 1C contact • Contact capacity: 250 VAC, 0.3 A cosϕ = 0, 48 VDC, 0.5 A (resistive load)
Digital interface card	OPC-DI	Enables frequency setting (8, 12, 15, 16 bit) and frequency setting via BCD code.
	OPC-DO	The output interface card enables monitoring of frequency, output voltage, and output current using binary codes.
Analog interface card	OPC-AIO	Enables torque limit value, frequency setting, and ratio tuning setting via analog input. Enables monitoring of inverter output frequency, current, torque, etc. in analog quantities. • Analog input Analog voltage input: 1 (0 to ±10 V) Analog current input: 1 (4 to 20 mA or 0 to 20 mA) • Analog output Analog voltage output: 1 (0 to ±10 V) Analog current output: 1 (4 to 20 mA)
Multi-protocol Ethernet communication card	OPC-ETM	Connects to the master device via Ethernet communication (EtherNet/IP, PROFINET), enabling setting of operation commands and frequency commands, and setting and checking of function codes. • Connector type: RJ-45 shielded • Ethernet cable: CAT-5e or higher UTP or STP cable • Physical layer type: IEEE 802.3 • No. of ports: 2-port (with built-in switch function) • Communication speed: 10 Mbps/100 Mbps (auto detection)
DeviceNet communication card	OPC-DEV	Operation and frequency commands can be set from DeviceNet master, enabling monitoring of operation status and changing/checking of all function codes • No. of connected nodes: Up to 64 (including master) • MAC ID: 0 to 63 • Insulation: 500 VDC (photocoupler insulation) • Communication speed: 500 kbps/250 kbps/125 kbps • Network power consumption: Up to 80 mA 24 VDC
PROFIBUS-DP communication card	OPC-PDP2	Operation and frequency commands can be set from PROFIBUS-DP master, enabling monitoring of operation status and changing/checking of all function codes. • Communication speed: 9.6 kbps to 12 Mbps • Transmission distance: Up to 1,200 m • Connection connector: 2 x 6-pole terminal block
CC-Link communication card	OPC-CCL	When connecting to a CC-Link master unit, it supports a communication speed of up to 10 Mbps and a total length of up to 1,200 m. • No. of connected units: 42 • Communication method: CC-Link Ver1.10 and Ver2.0 • Communication speed: 156 kbps or faster
SX bus communication card	OPC-SX	This is an option to connect our PLCs (MICREX-SX Series) and inverters via SX bus. Allows for the following: • No. of transmission words occupied: 16 words • Maximum transmission speed: 25 Mbps • Setting of operating frequency • Setting of operation commands (FWD, REV, RST, etc.) • Operation status monitor • Set/read data code for each function code
T-Link communication card	OPC-TL	This is an option to connect our PLCs (MICREX-SX, MICREX-F) and inverters via T-link (I/O transmission). Allows for the following: • No. of transmission words occupied: 8 words • No. of connected inverters: Up to 12 • Maximum transmission speed: 500 kbps • Setting of operating frequency • Setting of operation commands (FWD, REV, RST, etc.) • Operation status monitor • Set/read data code for each function code
CANopen communication card	OPC-COP2	Operation and frequency commands can be set from CANopen master (PC, PLC, etc.), as well as setting/checking of all function codes. • No. of connected nodes: Up to 127 • Communication speed: 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 800 kbps, 1 Mbps • Transmission distance: Up to 2,500 m

AC Reactor
[Standard specifications]
[DB□□ -□]

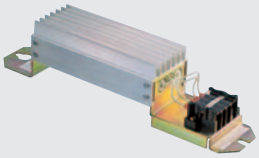


Fig. A

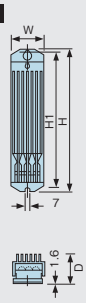


Fig. B

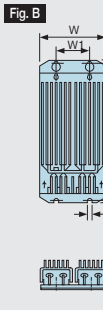


Fig. C

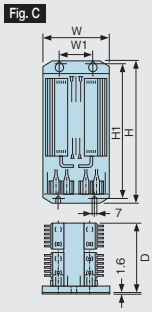


Fig. D

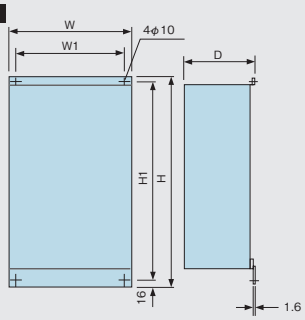
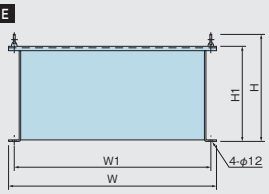


Fig. E



Voltage	Type	Fig	Dimensions [mm]					Approx. weight [kg]
			W	W1	H	H1	D	
3-phase 200V	DB0.75-2	A	68	–	310	295	67	1.3
	DB2.2-2		80		345	332	94	2
	DB3.7-2		80		345	332	94	2
	DB5.5-2	B	146	90	450	430	67.5	4.5
	DB7.5-2		160	90	390	370	90	5
	DB11-2	C	142	74	430	415	160	6.9
	DB15-2		142	74	430	415	160	6.9
	DB18.5-2		142	74	510	495	160	8.7
	DB22-2		142	74	510	495	160	8.7
	DB30-2C	D	400	368	660	628	140	10
	DB37-2C						240	13
	DB45-2C							18
	DB55-2C		405		750	718		22
	DB75-2C	E	450	420	283	240	440	35
	DB110-2C		550	520				32

Voltage	Type	Fig	Dimensions [mm]					Approx. weight [kg]
			W	W1	H	H1	D	
3-phase 400V	DB0.75-4	A	68	–	310	295	67	1.3
	DB2.2-4		68		470	455	67	2
	DB3.7-4		68		470	455	67	1.7
	DB5.5-4	B	146	74	470	455	67	4.5
	DB7.5-4		146	74	510	495	67	5
	DB11-4	C	142	74	430	415	160	6.9
	DB15-4		142	74	430	415	160	6.9
	DB18.5-4		142	74	510	495	160	8.7
	DB22-4		142	74	510	495	160	8.7
	DB30-4C	D	420	388	660	628	140	11
	DB37-4C						240	14
	DB45-4C							19
	DB55-4C		425		750	718		21
	DB75-4C	E	550	520	283	240	440	26
	DB110-4C							30
	DB132-4C		650	620				41
	DB160-4C		750	720				57
	DB200-4C							43
	DB220-4C*		600	570				74

* DB220-4C is a set of two with the above dimensions.

AC Reactor
[10%EDSpec.]
[DB□□ -□C]

Fig. A

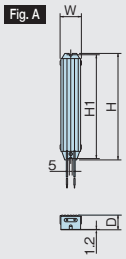


Fig. B

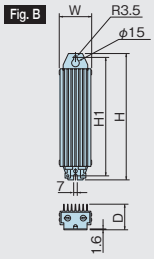


Fig. C

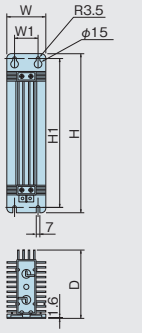
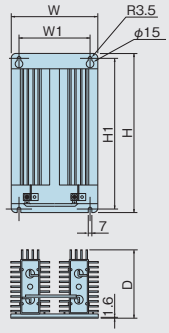
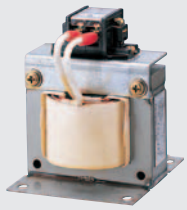


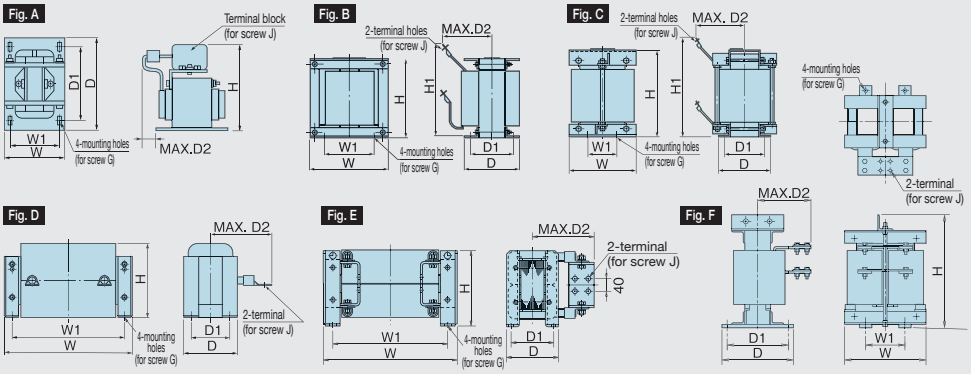
Fig. D



Voltage	Type	Dimensions [mm]				
		W	W1	H	H1	D
DB0.75-2C/4C	A	43	–	221	215	30.5
DB2.2-2C/4C	B	67	–	188	172	55
DB3.7-2C/4C		67	–	328	312	55
DB5.5-2C/4C		80	–	378	362	78
DB7.5-2C/4C		80	–	418	402	78
DB11-2C/4C	C	80	50	460	440	140
DB15-2C/4C		80	50	580	560	140
DB22-2C/4C	D	180	144	400	383	145

DC Reactor
[DCR□-□□□]



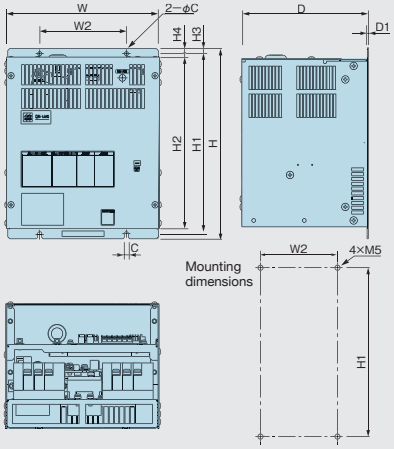


Voltage	Type	Fig	Dimensions [mm]									Approx. weight [kg]
			W	W1	D	D1	D2	G	H	H1	J	
3-phase 200V	DCR2-0.4	A	66	56	90	72	15	M4(5.2×8)	94	–	M4	1.0
	DCR2-0.75		66	56	90	72	20	M4(5.2×8)	94	–	M4	1.4
	DCR2-1.5		66	56	90	72	20	M4(5.2×8)	94	–	M4	1.6
	DCR2-2.2		86	71	100	80	10	M5(6×9)	110	–	M4	1.8
	DCR2-3.7		86	71	100	80	20	M5(6×9)	110	–	M4	2.6
	DCR2-5.5		111	95	100	80	20	M6(7×11)	130	–	M5	3.6
	DCR2-7.5		111	95	100	80	23	M6(7×11)	130	–	M5	3.8
	DCR2-11		111	95	100	80	24	M6(7×11)	137	–	M6	4.3
	DCR2-15		146	124	120	96	15	M6(7×11)	180	–	M8	5.9
	DCR2-18.5		146	124	120	96	25	M6(7×11)	180	–	M8	7.4
	DCR2-22A		146	124	120	96	25	M6(7×11)	180	–	M8	7.5
	DCR2-30B	B	152	90	156	116	115	M6(Φ8)	130	190	M10	12
	DCR2-37B		171	110	151	110	115	M6(Φ8)	150	200	M10	14
	DCR2-37C	D	210	185	101	81	125	M6(7×13)	125	–	M10	7.4
	DCR2-45B	B	171	110	166	125	120	M6(Φ8)	150	200	M10	16
	DCR2-45C	D	210	185	106	86	135	M6(7×13)	125	–	M12	8.4
	DCR2-55B	C	190	160	131	90	100	M6(Φ8)	210	250	M12	16
	DCR2-55C	D	255	225	96	76	140	M6(7×13)	145	–	M12	11
	DCR2-75C		255	225	106	86	145	M6(7×13)	145	–	M12	12
	DCR2-90C		255	225	116	96	155	M6(7×13)	145	–	M12	14
	DCR2-110C		300	265	116	90	185	M8(10×18)	160	–	M12	17
3-phase 400V	DCR4-0.4	A	66	56	90	72	15	M4(5.2×8)	94	–	M4	1.0
	DCR4-0.75		66	56	90	72	20	M4(5.2×8)	94	–	M4	1.4
	DCR4-1.5		66	56	90	72	20	M4(5.2×8)	94	–	M4	1.6
	DCR4-2.2		86	71	100	80	15	M5(6×9)	110	–	M4	2.0
	DCR4-3.7		86	71	100	80	20	M5(6×9)	110	–	M4	2.6
	DCR4-5.5		86	71	100	80	20	M5(6×9)	110	–	M4	2.6
	DCR4-7.5		111	95	100	80	24	M6(7×11)	130	–	M5	4.2
	DCR4-11		111	95	100	80	24	M6(7×11)	130	–	M5	4.3
	DCR4-15		146	124	120	96	15	M6(7×11)	168	–	M5	5.9
	DCR4-18.5		146	124	120	96	25	M6(7×11)	171	–	M6	7.2
	DCR4-22A		146	124	120	96	25	M6(7×11)	171	–	M6	7.2
	DCR4-30B	B	152	90	157	115	100	M6(Φ8)	130	190	M8	13
	DCR4-37B	B	171	110	150	110	100	M6(Φ8)	150	200	M8	15
	DCR4-37C	C	210	185	101	81	105	M6(7×13)	125	–	M8	7.4
	DCR4-45B	B	171	110	165	125	110	M6(Φ8)	150	210	M8	18
	DCR4-45C	C	210	185	106	86	120	M6(7×13)	125	–	M8	8.4
	DCR4-55B	B	171	110	170	130	110	M6(Φ8)	150	210	M8	20
	DCR4-55C	C	255	225	96	76	120	M6(7×13)	145	–	M10	11
	DCR4-75C	C	255	225	106	86	125	M6(7×13)	145	–	M10	13
	DCR4-90C		255	225	116	96	140	M6(7×13)	145	–	M12	15
	DCR4-110C		300	265	116	90	175	M8(10×18)	155	–	M12	19
	DCR4-132C		300	265	126	100	180	M8(10×18)	160	–	M12	22
	DCR4-160C		350	310	131	103	180	M10(12×22)	190	–	M12	26
	DCR4-200C		350	310	141	113	185	M10(12×22)	190	–	M12	30
	DCR4-220C		350	310	146	118	200	M10(12×22)	190	–	M12	33
	DCR4-250C		350	310	161	133	210	M10(12×22)	190	–	M12	35
	DCR4-280C		350	310	161	133	210	M10(12×22)	190	–	M16	37
	DCR4-315C		400	345	146	118	200	M10(12×22)	225	–	M16	40
	DCR4-355C	E	400	345	156	128	200	M10(12×22)	225	–	4×M12	49
	DCR4-400C		445	385	145	117	213	M10(12×22)	245	–	4×M12	52
	DCR4-450C		440	385	150	122	215	M10(12×22)	245	–	4×M12	62
	DCR4-500C		445	390	165	137	220	M10(12×22)	245	–	4×M12	72
	DCR4-560C	F	270	145	203	170	195	M12(14×20)	485	–	2×M12	70
	DCR4-630C		285	145	203	170	195	M12(14×20)	480	–	2×M12	75
	DCR4-710C		340	160	295	255	225	M12(Φ15)	480	–	4×M12	95

* The DCR2/4-□□B type is also prepared for motors with 75 kW or larger, which are applicable as standard. Contact us for ordering product separately.
* If using motors with output of 75 kW or higher, be sure to use a DC reactor (option).

DC Reactor Type	Remarks
Input power factor of DCR2/4-□□/□□A/□□B: approx. 90 to 95%	The symbol at the end of the type code varies depending on the capacity.
Input power factor of the DCR2/4-□□C: about 86 to 90%	This can be selected with the inverter of 37kW or more.

Braking unit
[BU□□-□E]



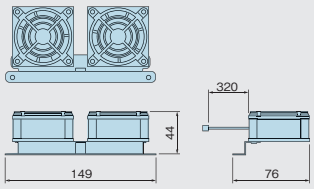
Voltage	Type	Dimensions [mm]											Approx. weight [kg]
		W	W1	W2	W3	H	H1	H2	H3	H4	D	D1	
3-phase 200V	BU90-2E	250	–	150	–	370	355	340	7.5	15	160	2.4	9
3-phase 400V	BU90-4E	230	–	130	–	280	265	250	7.5	15	160	1.2	5.5
	BU132-4E	250	–	150	–	370	355	340				2.4	9
	BU220-4E					450	435	420					13

Fan unit for braking unit

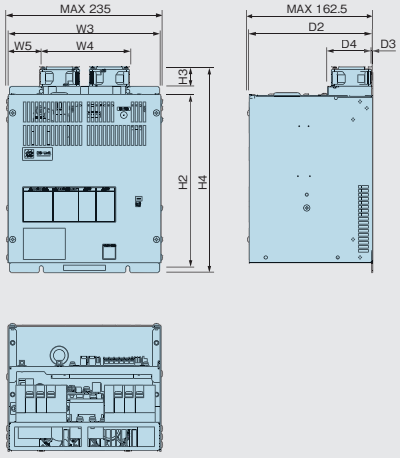
The duty cycle [%ED] of the model with an external braking unit is increased from 10% ED to 30% ED byusing this option.

Fan unit

●BU-F



Braking unit + Fan unit



Voltage	Type	Dimensions [mm]								
		W3	W4	W5	H2	H3	H4	D2	D3	D4
3-phase 200V	BU90-2EF	250	135	57.5	370	30	400	160	1.2	64
3-phase 400V	BU90-4EF	230	135	47.5	280	30	310	160	1.2	64
	BU132-4EF	250		57.5	370		400			
	BU220-4EF	250		57.5	450		480			

AC Reactor
[ACR□ -□□□]

Fig. A

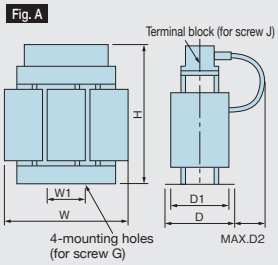


Fig. B

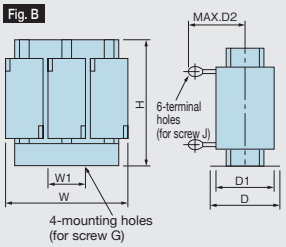


Fig. C

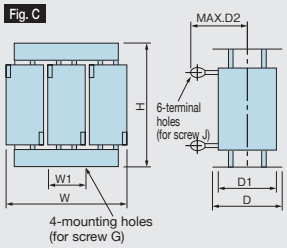


Fig. D

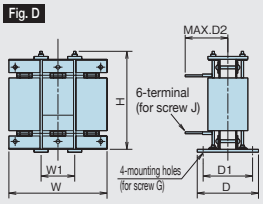
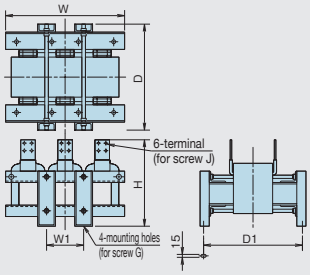


Fig. E



Voltage	Type	Fig	Dimensions [mm]								Approx. weight [kg]
			W	W1	D	D1	D2	G	H	J	
3-phase 200V	ACR2-0.4A	A	120	40	90	65	20	M5(6×10)	115	M4	1.4
	ACR2-0.75A		120	40	100	75	20	M5(6×10)	115	M4	1.9
	ACR2-1.5A		120	40	100	75	20	M5(6×10)	115	M4	2
	ACR2-2.2A		120	40	100	75	20	M5(6×10)	115	M4	2
	ACR2-3.7A		125	40	100	75	25	M5(6×10)	125	M4	2.4
	ACR2-5.5A		125	40	115	90	25	M5(6×10)	125	M4	3.1
	ACR2-7.5A	B	125	40	115	90	106	M5(6×10)	95	M5	3.1
	ACR2-11A		125	40	125	100	106	M5(6×10)	95	M6	3.7
	ACR2-15A		180	60	110	85	106	M6(7×11)	115	M6	4.8
	ACR2-18.5A		180	60	110	85	109	M6(7×11)	115	M6	5.1
	ACR2-22A		180	60	110	85	109	M6(7×11)	115	M6	5.1
	ACR2-37		190	60	120	90	172	M6(7×11)	190	M8	11
	ACR2-55	C	190	60	120	90	200	M6(7×11)	190	M12	13
	ACR2-75		250	100	120	90	200	M8(9×14)	250	M12	25
	ACR2-90		285	190	158	120	190	M10(12×20)	210	M12	26
	ACR2-110		280	150	138	110	200	M8(10×20)	270	M12	30
3-phase 400V	ACR4-0.75A	B	120	40	90	65	106	M5(6×10)	85	M4	1.1
	ACR4-1.5A		125	40	100	75	106	M5(6×10)	85	M4	1.9
	ACR4-2.2A		125	40	100	75	106	M5(6×10)	95	M4	2.2
	ACR4-3.7A		125	40	100	75	106	M5(6×10)	95	M4	2.4
	ACR4-5.5A		125	40	115	90	106	M5(6×10)	95	M5	3.1
	ACR4-7.5A		125	40	115	90	106	M5(6×10)	95	M5	3.7
	ACR4-11A		180	60	110	85	106	M6(7×11)	115	M6	4.3
	ACR4-15A		180	60	110	85	106	M6(7×11)	137	M6	5.4
	ACR4-18.5A		180	60	110	85	106	M6(7×11)	137	M6	5.7
	ACR4-22A		180	60	110	85	106	M6(7×11)	137	M6	5.9
	ACR4-37		190	60	120	90	172	M6(7×11)	190	M8	12
	ACR4-55	C	190	60	120	90	200	M6(7×11)	190	M10	14
	ACR4-75		190	60	126	90	157	M6(7×10)	190	M10	16
	ACR4-110		250	100	136	105	202	M8(9.5×18)	245	M12	24
	ACR4-132		250	100	146	115	207	M8(10×16)	250	M12	32
	ACR4-220		320	120	150	110	240	M10(12×20)	300	M12	40
	ACR4-280		380	130	150	110	260	M10(12×20)	300	M12	52
	ACR4-355		380	130	150	110	260	M10(12×20)	300	M12	52
	ACR4-450	D	460	155	290	230	200	M12(ϕ15)	490	4×M12	95
	ACR4-530	E	480	155	420	370	–	M12(15×25)	380	4×M12	100
	ACR4-630		510	170	420	370	–	M12(15×25)	390	4×M12	110

Note) It is not necessary to use the reactor unless a particularly stable power supply is required, i.e., DC bus connection operation (PN connection operation).
Use the DC reactor (DCR) as a measure against harmonics.

Output circuit filter
(OFL-□□□-4A) [for 3-phase 200 V/400 V Series]

Filter dimensions (22kW or less)

Fig. A

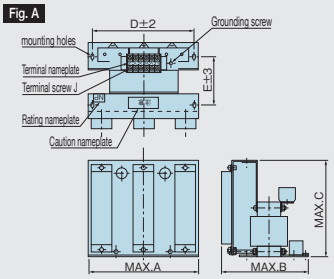
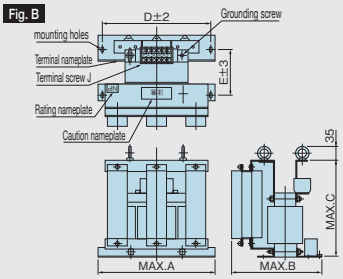


Fig. B



Filter dimensions (30kW or more):reactor

Fig. C

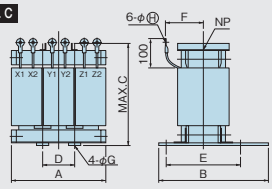


Fig. D

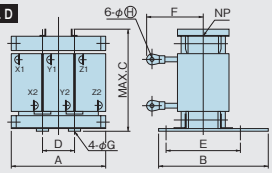


Fig. E

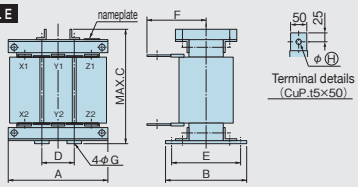
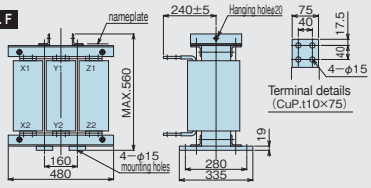
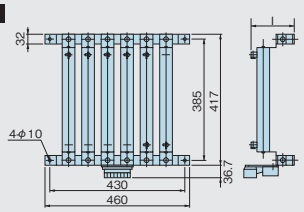


Fig. F



Filter dimensions (30kW or more):resistor/capacitor

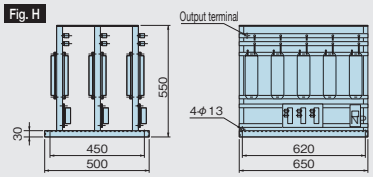
Fig. G



The reactor, capacitor and resistor for filter OFL-30-4A or larger have to be installed separately.

(Those items are not included in the mass indicated in the table below. They are shipped as a set by ordering the filter.)

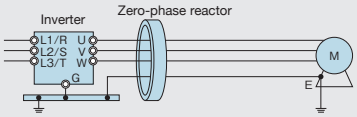
Fig. H

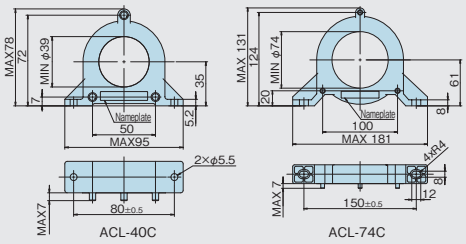


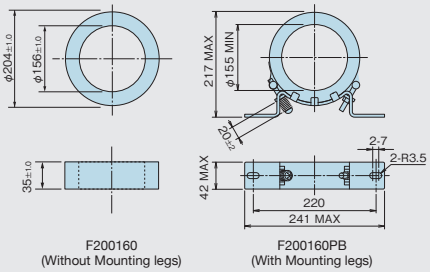
Type		Fig	Dimensions [mm]										Approx. weight [kg]		
			A	B	C	D	E	F	I	Grounding screw	Terminal screw H	Terminal screw (G: mounting hole)	Filter	Reactor	Resistor and capacitor
3-phase 400V	OFL-0.4-4A	A	220	175	195	200	95	–	–	M4	M4	M5	7	–	
	OFL-1.5-4A			225	220		115						14		
	OFL-3.7-4A		290	290	230	260	160			M5	M5	M6	22		
	OFL-7.5-4A	B	330	275	310	300	145			M6	M6	M8	35		
	OFL-15-4A			300	330		170						45		
	OFL-22-4A														
	OFL-30-4A	C・G	210	175	210	70	140	90	160	–	6.4	8	–	12	3
	OFL-37-4A		220	190	220	75	150	95						15	5.5
	OFL-45-4A			195	265	70	155	140			8.4	10		17	
	OFL-55-4A	D・G	260	200	275	85	160	150						22	
	OFL-75-4A			210	290		170		233		10.5	12		25	10
	OFL-90-4A							155						28	
	OFL-110-4A		300	230	330	100	190	170						38	
	OFL-132-4A			240	340		200				13	15		42	
	OFL-160-4A							180						48	13
	OFL-200-4A		320	270	350	105	220	190	333					60	16
	OFL-220-4A		340	300	390	115	250							70	
	OFL-280-4A		350		430			200						78	19
	OFL-315-4A	E・H	440	275	450	150	230	170	–		15			90	36
	OFL-355-4A			290	480		245	175						100	
	OFL-400-4A			295	510		240							110	
	OFL-450-4A			325	470		270	195						125	
	OFL-500-4A			335	500		280	210						145	
	OFL-630-4A	F・H	480	335	560	160	280	240						170	

* This filter is not limited by carrier frequency.

Zero-phase reactor for reducing radiated noise
[ACL-40C, ACL-74C, F200160]







Applied wire size list

Type	Q'ty	No. of turns	Recommended wire size [mm²] Note)
ACL-40C	1	4	2.0, 3.5, 5.5
	2	2	8, 14
ACL-74C	1	4	8, 14
	2	2	22, 38, 60, 5.5×2, 8×2, 14×2, 22×2
	4	1	100, 150, 200, 250, 38×2, 60×2, 100×2
F200160 F200160PB	4	1	325, 150×2, 200×2, 250×2, 325×2, 150×3, 200×3, 250×3, 325×3, 250×4, 325×4

NOTE) Use a 600V HIV insulation cable (Allowable temp. 75°C).

Product Warranty

To all our customers who purchase Fuji Electric products included in this catalog:

Please take the following items into consideration when placing your order.

When requesting an estimate and placing your orders for the products included in these materials, please be aware that any items such as specifications which are not specifically mentioned in the contract, catalog, specifications or other materials will be as mentioned below.
In addition, the products included in these materials are limited in the use they are put to and the place where they can be used, etc., and may require periodic inspection. Please confirm these points with your sales representative or directly with this company.
Furthermore, regarding purchased products and delivered products, we request that you take adequate consideration of the necessity of rapid receiving inspections and of product management and maintenance even before receiving your products.

1. Free of Charge Warranty Period and Warranty Range

1-1 Free of charge warranty period

(1) The product warranty period is "1 year from the date of purchase" or 24 months from the manufacturing date imprinted on the name place, whichever date is earlier.
(2) However, in cases where the operating environment, conditions of use, use frequency and times used, etc., have an effect on product life, this warranty period may not apply.
(3) Furthermore, the warranty period for parts restored by Fuji Electric's Service Department is "6 months from the date that repairs are completed."

1-2 Warranty range

(1) In the event that breakdown occurs during the product's warranty period which is the responsibility of Fuji Electric, Fuji Electric will replace or repair the part of the product that has broken down free of charge at the place where the product was purchased or where it was delivered. However, if the following cases are applicable, the terms of this warranty may not apply.

1) The breakdown was caused by inappropriate conditions, environment, handling or use methods, etc. which are not specified in the catalog, operation manual, specifications or other relevant documents.
2) The breakdown was caused by the product other than the purchased or delivered Fuji's product.
3) The breakdown was caused by the product other than Fuji's product, such as the customer's equipment or software design, etc.
4) Concerning the Fuji's programmable products, the breakdown was caused by a program other than a program supplied by this company, or the results from using such a program.
5) The breakdown was caused by modifications or repairs affected by a party other than Fuji Electric.
6) The breakdown was caused by improper maintenance or replacement using consumables, etc. specified in the operation manual or catalog, etc.
7) The breakdown was caused by a chemical or technical problem that was not foreseen when making practical application of the product at the time it was purchased or delivered.
8) The product was not used in the manner the product was originally intended to be used.
9) The breakdown was caused by a reason which is not this company's responsibility, such as lightning or other disaster.

(2) Furthermore, the warranty specified herein shall be limited to the purchased or delivered product alone.
(3) The upper limit for the warranty range shall be as specified in item (1) above and any damages (damage to or loss of machinery or equipment, or lost profits from the same, etc.) consequent to or resulting from breakdown of the purchased or delivered product shall be excluded from coverage by this warranty.

1-3. Trouble diagnosis

As a rule, the customer is requested to carry out a preliminary trouble diagnosis. However, at the customer's request, this company or its service network can perform the trouble diagnosis on a chargeable basis. In this case, the customer is asked to assume the burden for charges levied in accordance with this company's fee schedule.

2. Exclusion of Liability for Loss of Opportunity, etc.

Regardless of whether a breakdown occurs during or after the free of charge warranty period, this company shall not be liable for any loss of opportunity, loss of profits, or damages arising from special circumstances, secondary damages, accident compensation to another company, or damages to products other than this company's products, whether foreseen or not by this company, which this company is not be responsible for causing.

3. Repair Period after Production Stop, Spare Parts Supply Period (Holding Period)

Concerning models (products) which have gone out of production, this company will perform repairs for a period of 7 years after production stop, counting from the month and year when the production stop occurs. In addition, we will continue to supply the spare parts required for repairs for a period of 7 years, counting from the month and year when the production stop occurs. However, it is estimated that the life cycle of certain electronic and other parts is short and it will be difficult to procure or produce those parts, so there may be cases where it is difficult to provide repairs or supply spare parts even within this 7-year period. For details, please confirm at our company's business office or our service office.

4. Transfer Rights

In the case of standard products which do not include settings or adjustments in an application program, the products shall be transported to and transferred to the customer and this company shall not be responsible for local adjustments or trial operation.

5. Service Contents

The cost of purchased and delivered products does not include the cost of dispatching engineers or service costs. Depending on the request, these can be discussed separately.

6. Applicable Scope of Service

Above contents shall be assumed to apply to transactions and use of the country where you purchased the products. Consult the local supplier or Fuji for the detail separately.

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NOTES

When running general-purpose motors

- **Driving a 400V general-purpose motor**
  When driving a 400V general-purpose motor with an inverter using extremely long cables, damage to the insulation of the motor may occur. Use an output circuit filter (OFL) if necessary after checking with the motor manufacturer. Fuji's motors do not require the use of output circuit filters because of their reinforced insulation.
- **Torque characteristics and temperature rise**
  When the inverter is used to run a general-purpose motor, the temperature of the motor becomes higher than when it is operated using a commercial power supply. In the low-speed range, the cooling effect will be weakened, so decrease the output torque of the motor. If constant torque is required in the low-speed range, use a Fuji inverter motor or a motor equipped with an externally powered ventilating fan.
- **Vibration**
  When the motor is mounted to a machine, resonance may be caused by the natural frequencies, including that of the machine. Operation of a 2-pole motor at 60Hz or more may cause abnormal vibration.
  * Study use of tier coupling or dampening rubber.
  * It is also recommended to use the inverter jump frequency control to avoid resonance points.
- **Noise**
  When an inverter is used with a general-purpose motor, the motor noise level is higher than that with a commercial power supply. To reduce noise, raise carrier frequency of the inverter. High-speed operation at 60Hz or more can also result in more noise.

When running special motors

- **High-speed motors**
  When driving a high-speed motor while setting the frequency higher than 120Hz, test the combination with another motor to confirm the safety of high-speed motors.
- **Explosion-proof motors**
  When driving an explosion-proof motor with an inverter, use a combination of a motor and an inverter that has been approved in advance.
- **Submersible motors and pumps**
  These motors have a larger rated current than general-purpose motors. Select an inverter whose rated output current is greater than that of the motor.
  These motors differ from general-purpose motors in thermal characteristics. Set a low value in the thermal time constant of the motor when setting the electronic thermal function.
- **Brake motors**
  For motors equipped with parallel-connected brakes, their braking power must be supplied from the primary circuit (commercial power supply). If the brake power is connected to the inverter power output circuit (secondary circuit) by mistake, problems may occur.
  Do not use inverters for driving motors equipped with series-connected brakes.
- **Geared motors**
  If the power transmission mechanism uses an oil-lubricated gearbox or speed changer/reducer, then continuous motor operation at low speed may cause poor lubrication. Avoid such operation.
- **Synchronous motors**
  It is necessary to use software suitable for this motor type. Contact Fuji for details.
- **Single-phase motors**
  Single-phase motors are not suitable for inverter-driven variable speed operation. Use three-phase motors.
  * Even if a single-phase power supply is available, use a three-phase motor as the inverter provides three-phase output.

Environmental conditions

- **Installation location**
  Use the inverter in a location with an ambient temperature range of -10 to 50˚C.
  The inverter and braking resistor surfaces become hot under certain operating conditions. Install the inverter on nonflammable material such as metal.
  Ensure that the installation location meets the environmental conditions specified in "Environment" in inverter specifications.

Combination with peripheral devices

- **Installing a molded case circuit breaker (MCCB)**
  Install a recommended molded case circuit breaker (MCCB) or an earth leakage circuit breaker (ELCB) in the primary circuit of each inverter to protect the wiring. Ensure that the circuit breaker capacity is equivalent to or lower than the recommended capacity.
- **Installing a magnetic contactor (MC) in the output (secondary) circuit**
  If a magnetic contactor (MC) is mounted in the inverter's secondary circuit for switching the motor to commercial power or for any other purpose, ensure that both the inverter and the motor are fully stopped before you turn the MC on or off. Remove the surge killer integrated with the MC.
- **Installing a magnetic contactor (MC) in the input (primary) circuit**
  Do not turn the magnetic contactor (MC) in the primary circuit on or off more than once an hour as an inverter fault may result. If frequent starts or stops are required during motor operation, use FWD/REV signals.
- **Protecting the motor**
  The electronic thermal function of the inverter can protect the motor. The operation level and the motor type (general-purpose motor, inverter motor) should be set. For high-speed motors or water-cooled motors, set a small value for the thermal time constant to protect the motor.
  If you connect the motor thermal relay to the motor with a long cable, a high-frequency current may flow into the wiring stray capacitance. This may cause the relay to trip at a current lower than the set value for the thermal relay. If this happens, lower the carrier frequency or use the output circuit filter (OFL).
- **Regarding power-factor correcting capacitor**
  Do not mount power factor correcting capacitors in the inverter (primary) circuit. Use the DC REACTOR to improve the inverter power factor. Do not use power factor correcting capacitors in the inverter output circuit (secondary). An overcurrent trip will occur, disabling motor operation.
- **Discontinuance of surge killer**
  Do not mount surge killers in the inverter output (secondary) circuit.
- **Reducing noise**
  Use of a filter and shielded wires are typical measures against noise to ensure that EMC Directives are met.
- **Measures against surge currents**
  If an overvoltage trip occurs while the inverter is stopped or operated under a light load, it is assumed that the surge current is generated by open/close of the phase-advancing capacitor in the power system.
  We recommend connecting a DC REACTOR to the inverter.
- **Megger test**
  When checking the insulation resistance of the inverter, use a 500V megger and follow the instructions contained in the Instruction Manual.

Wiring

- **Wiring distance of control circuit**
  When performing remote operation, use twisted shield wire and limit the distance between the inverter and the control box to 20m.
- **Wiring length between inverter and motor**
  If long wiring is used between the inverter and the motor, the inverter will overheat or trip as a result of overcurrent (high-frequency current flowing into the stray capacitance) in the wires connected to the phases. Ensure that the wiring is shorter than 50m. If this length must be exceeded, lower the carrier frequency or mount an output circuit filter (OFL).
- **Wiring size**
  Select cables with a sufficient capacity by referring to the current value or recommended wire size.
- **Wiring type**
  Do not use multicore cables that are normally used for connecting several inverters and motors.
- **Grounding**
  Securely ground the inverter using the grounding terminal.

Selecting inverter capacity

- **Driving general-purpose motor**
  Select an inverter according to the applicable motor ratings listed in the standard specifications table for the inverter. When high starting torque is required or quick acceleration or deceleration is required, select an inverter with a capacity one size greater than the standard.
- **Driving special motors**
  Select an inverter that meets the following condition: Inverter rated current > Motor rated current.

Transportation and storage

When transporting or storing inverters, follow the procedures and select locations that meet the environmental conditions that agree with the inverter specifications.

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